

Related U.S. Application Data

- (60) Provisional application No. 63/299,385, filed on Jan. 13, 2022, provisional application No. 63/176,817, filed on Apr. 19, 2021, provisional application No. 63/152,126, filed on Feb. 22, 2021.

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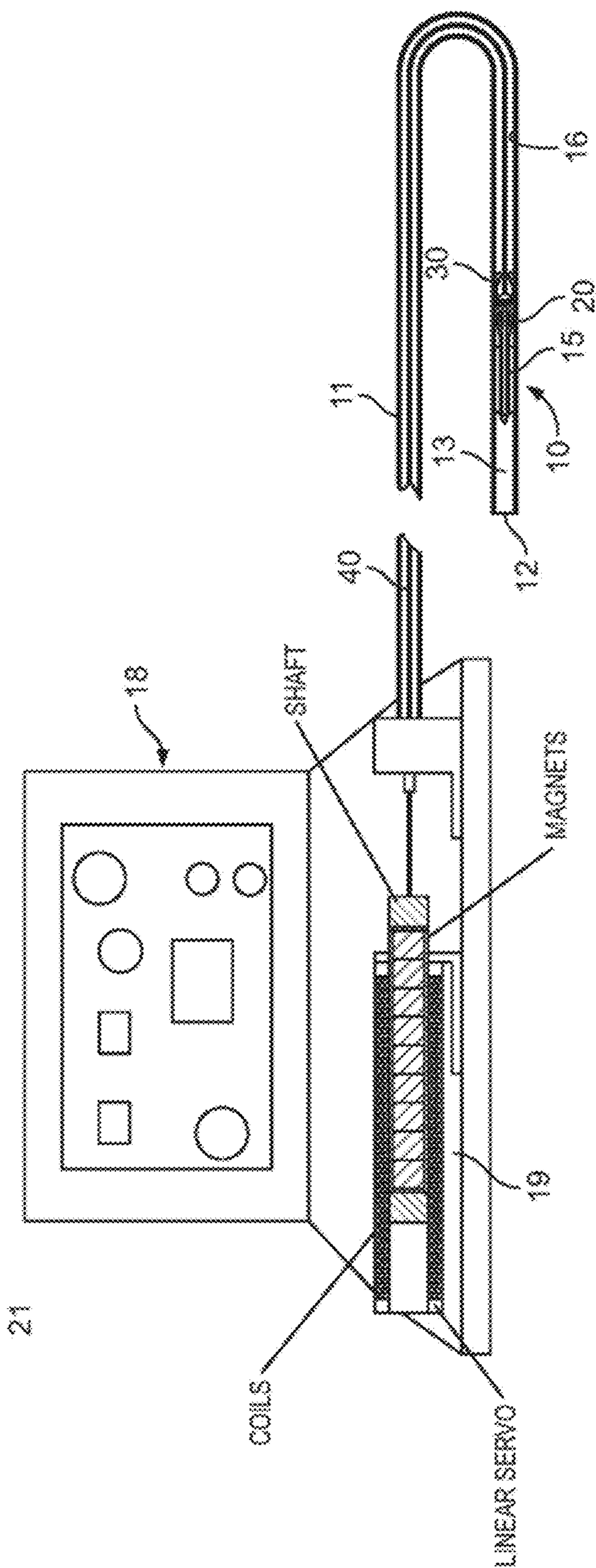


FIG. 1

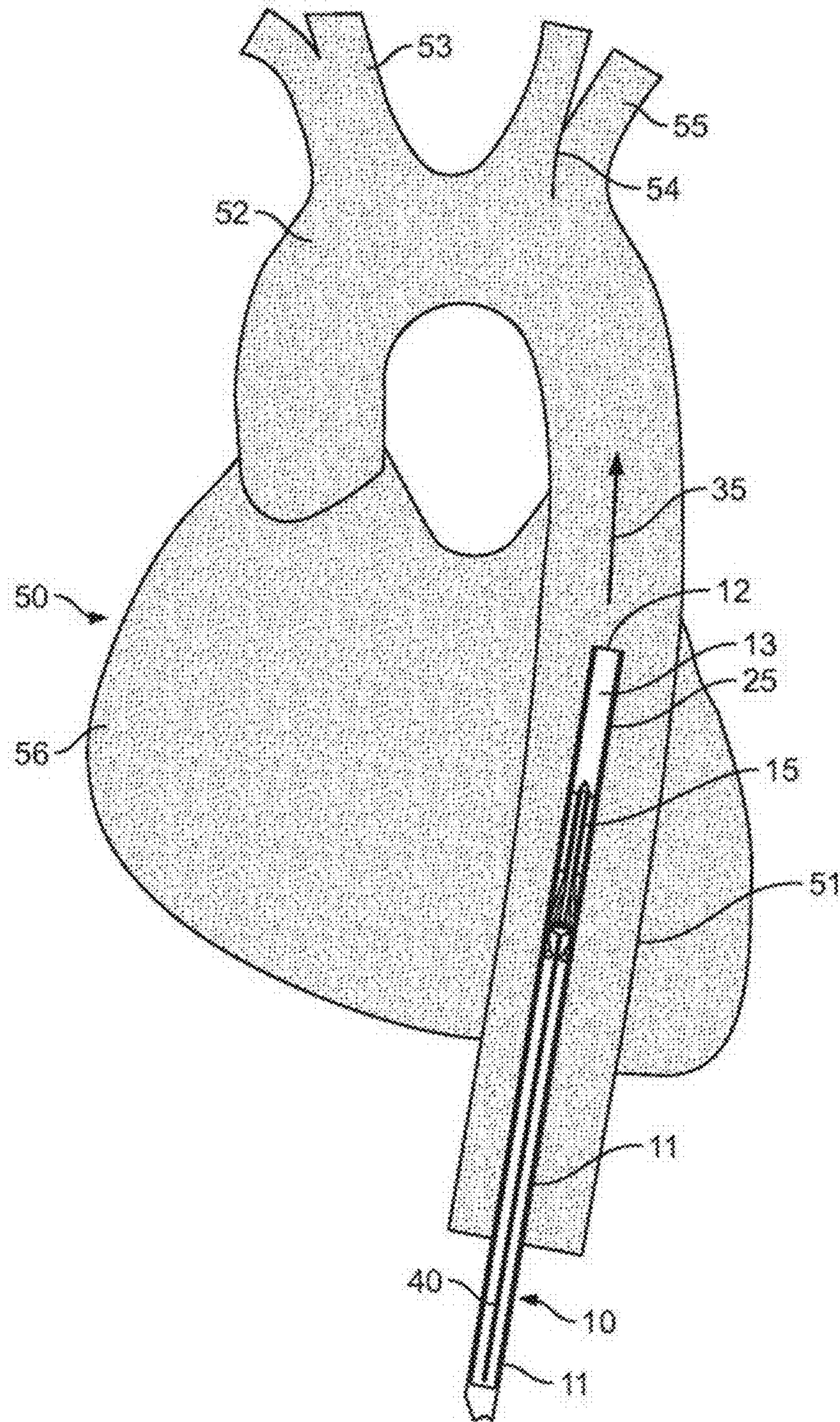


FIG. 2

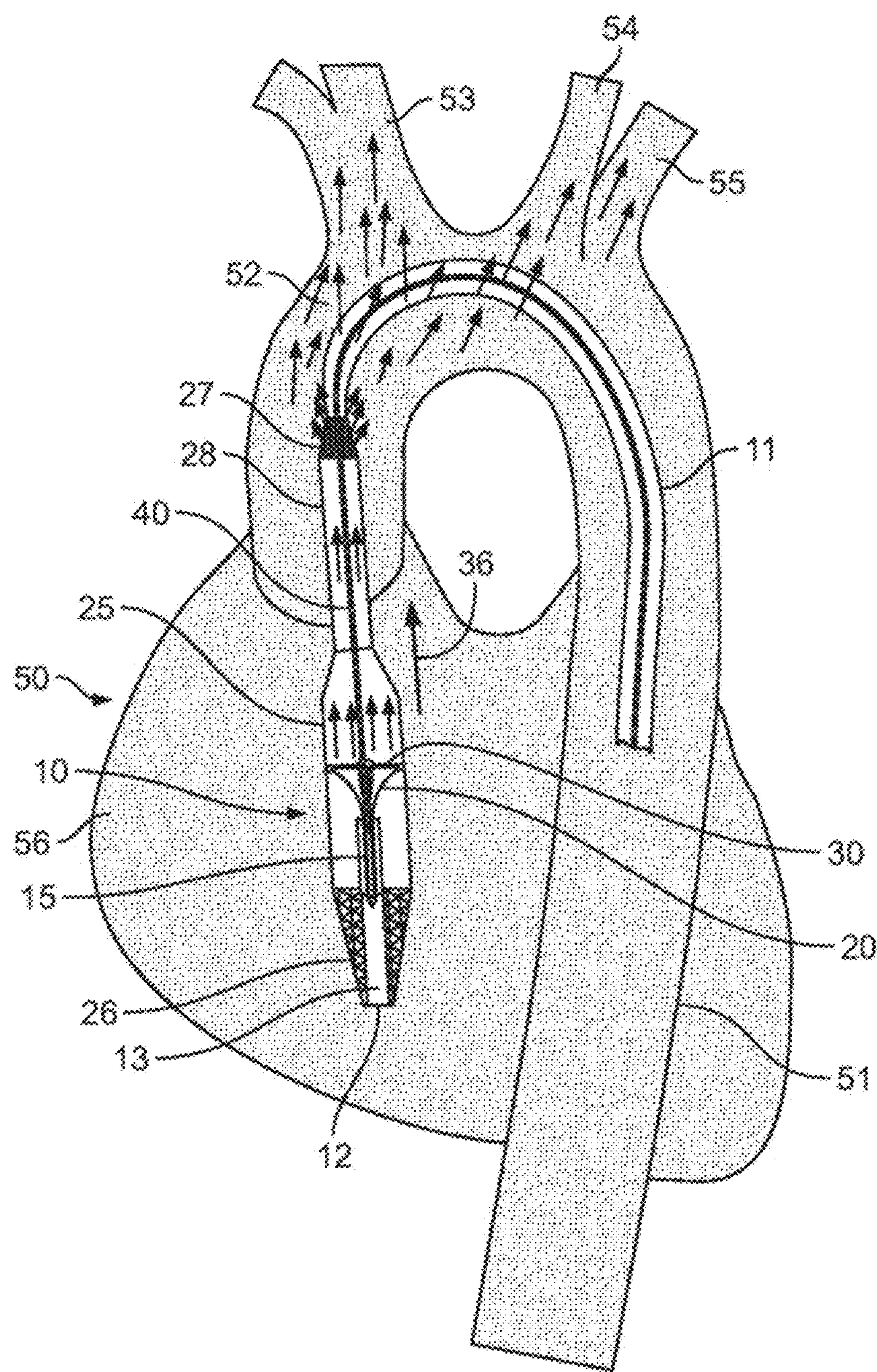


FIG. 3

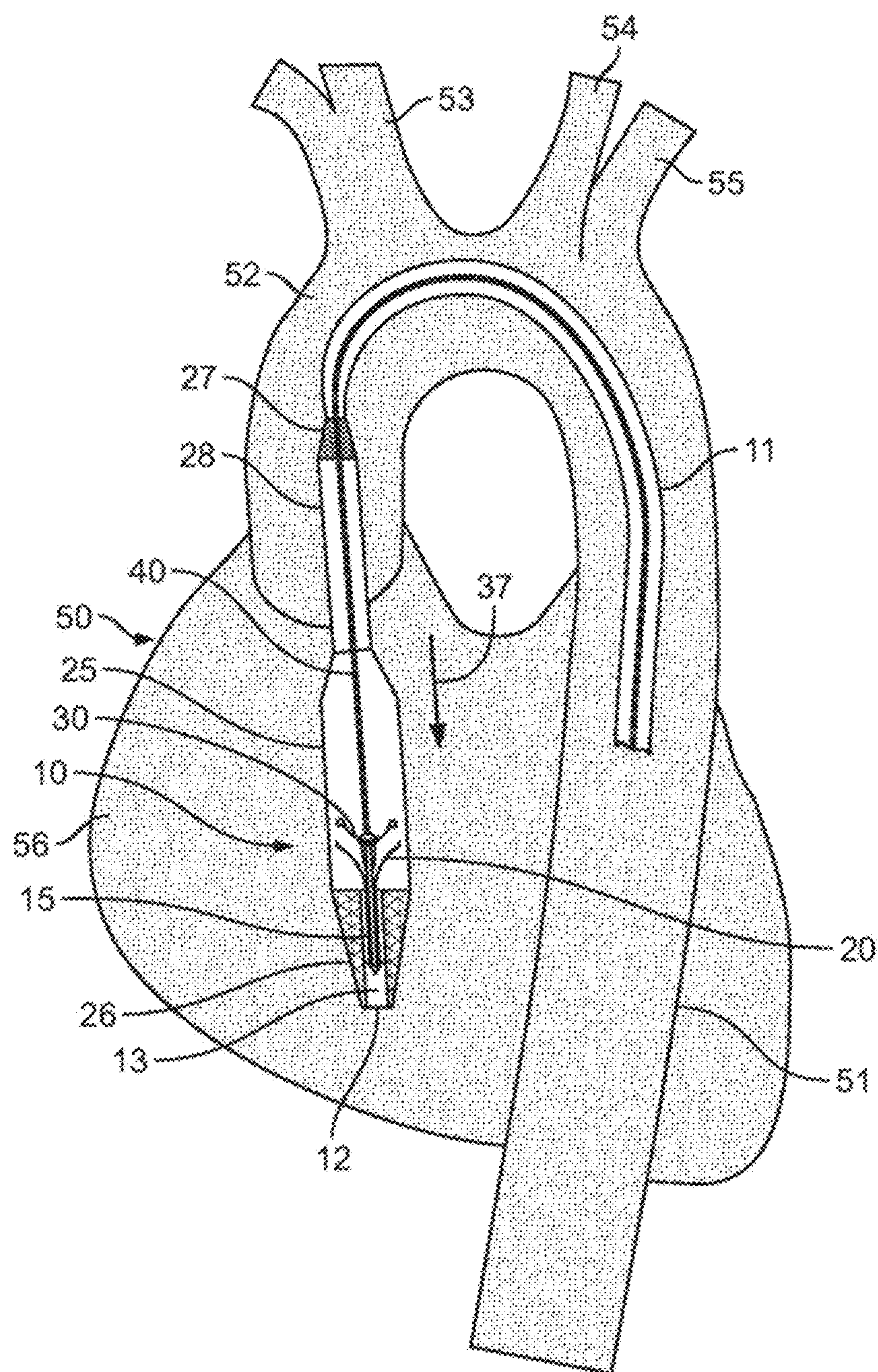


FIG. 4

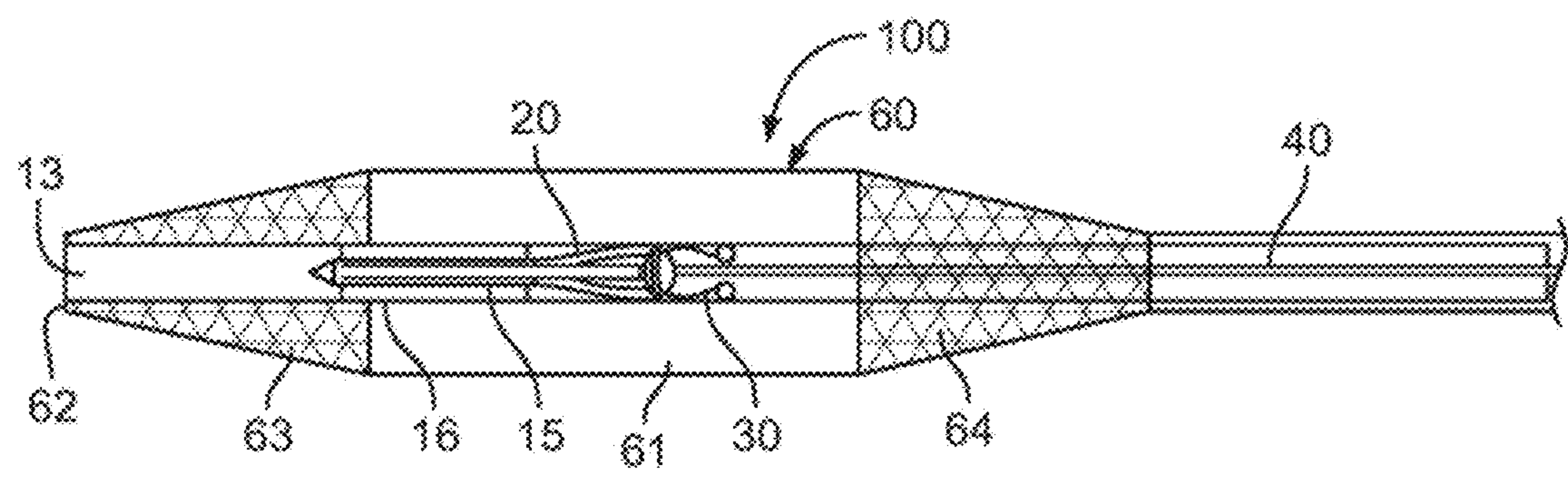


FIG. 5

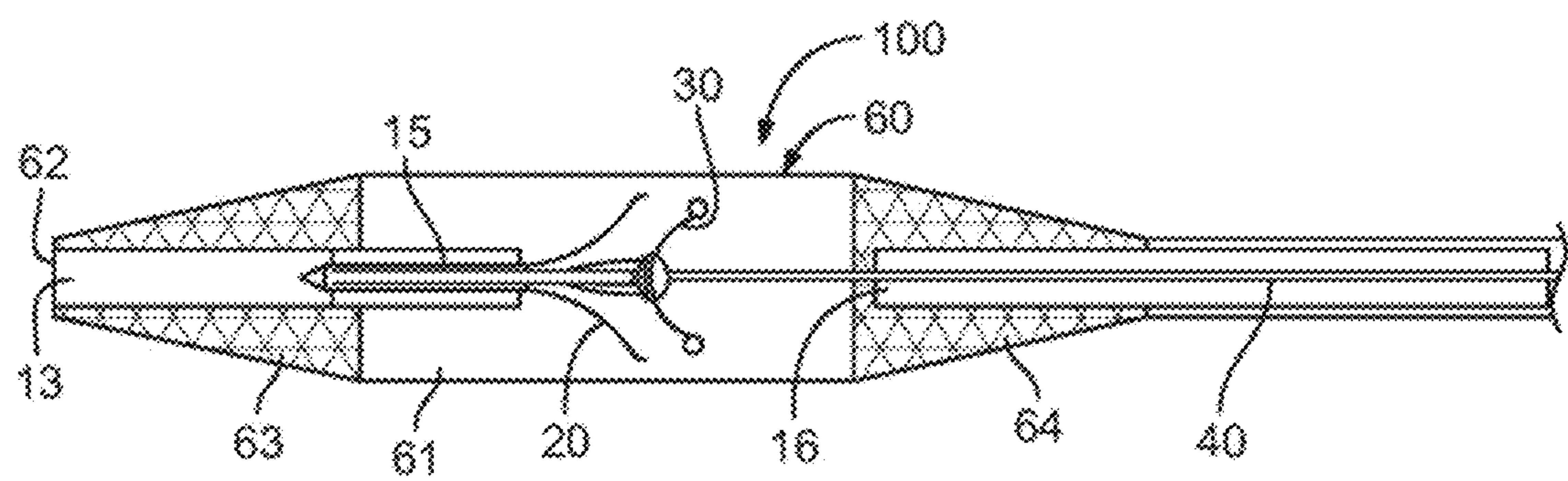


FIG. 6

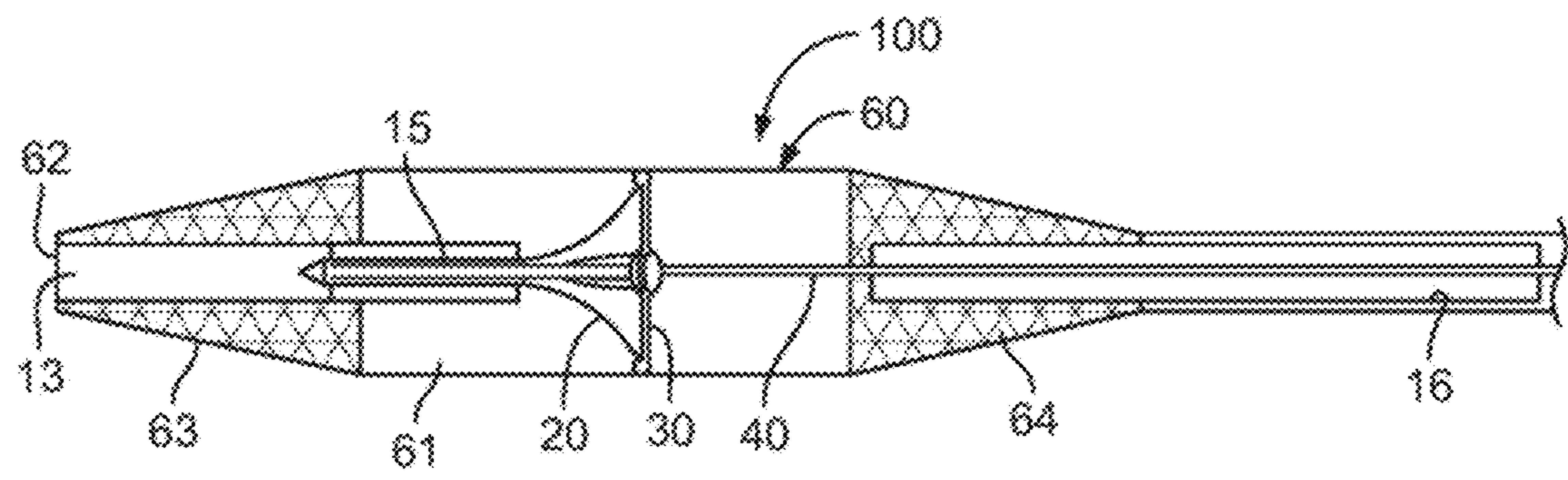


FIG. 7

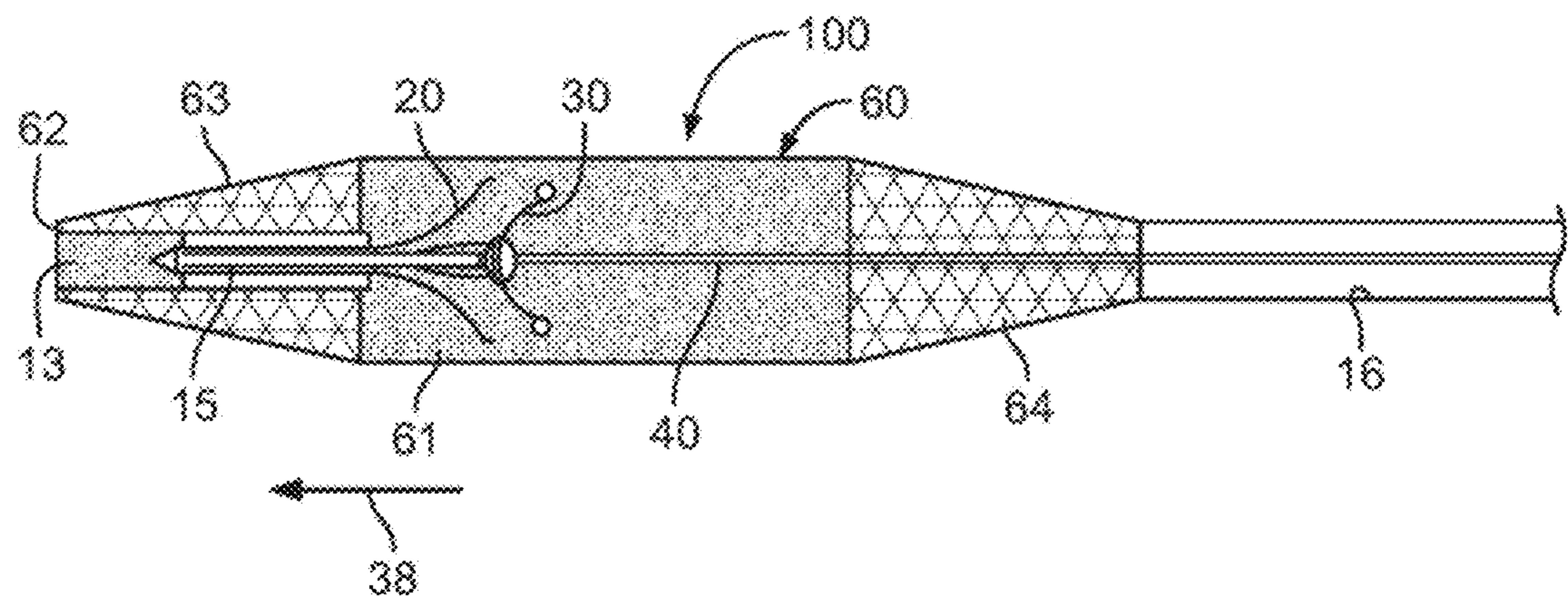


FIG. 8

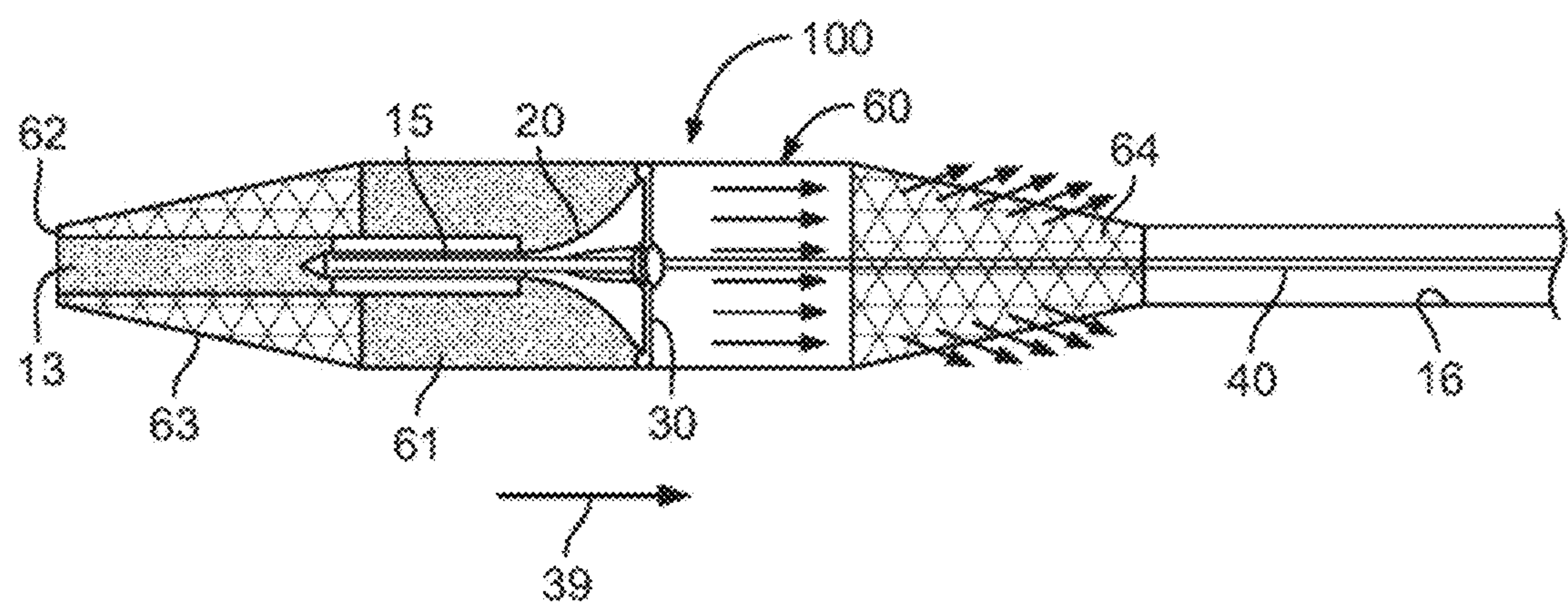


FIG. 9

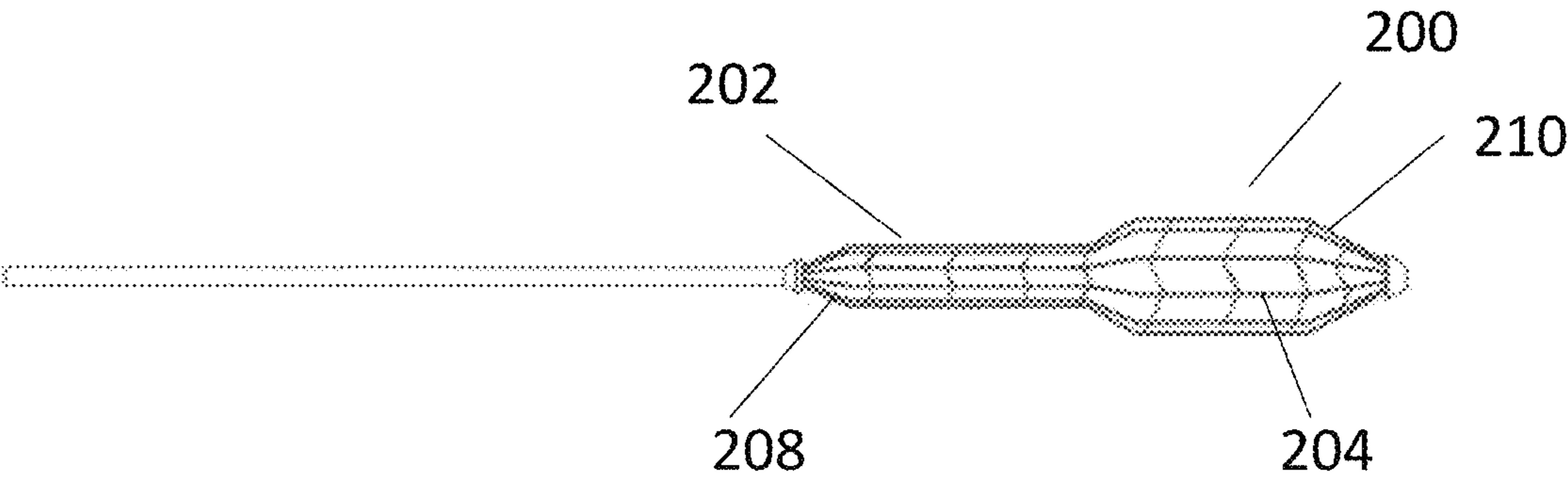


FIG. 10A

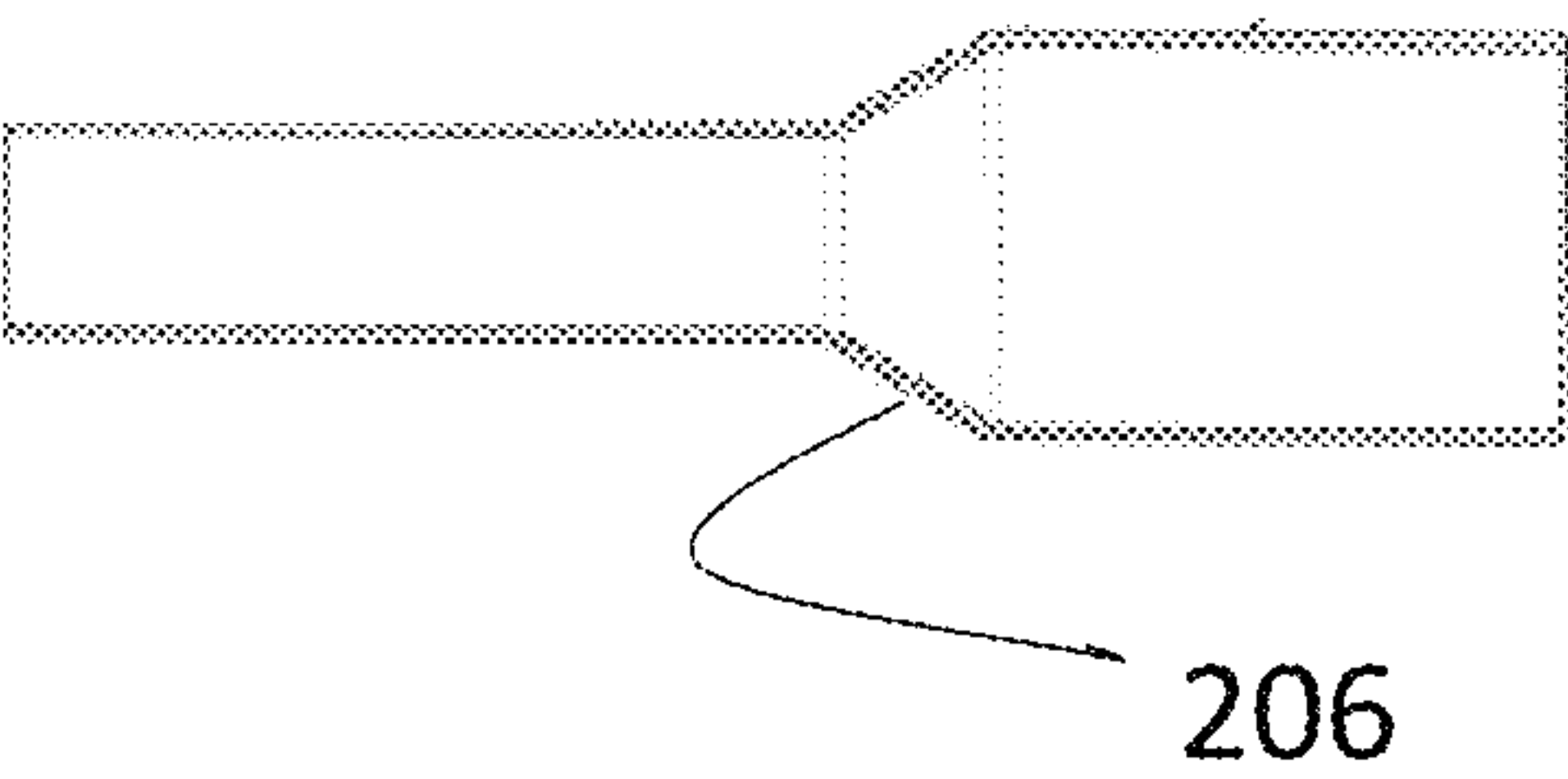


FIG. 10B

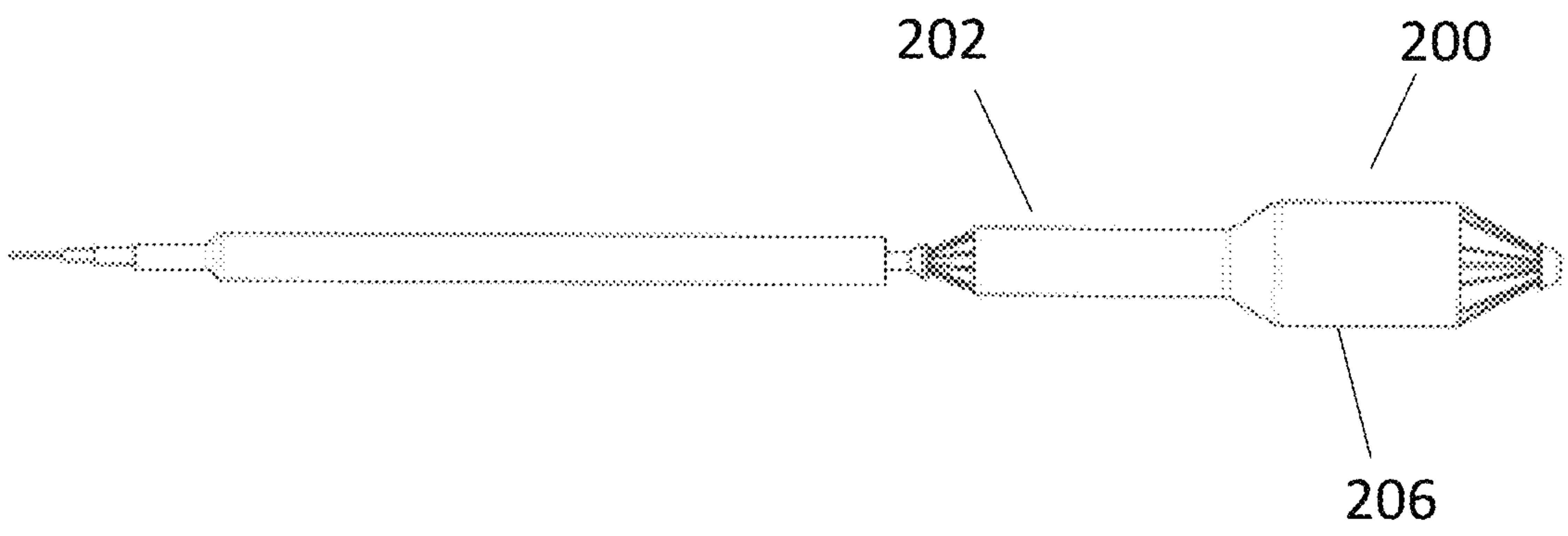


FIG. 10C

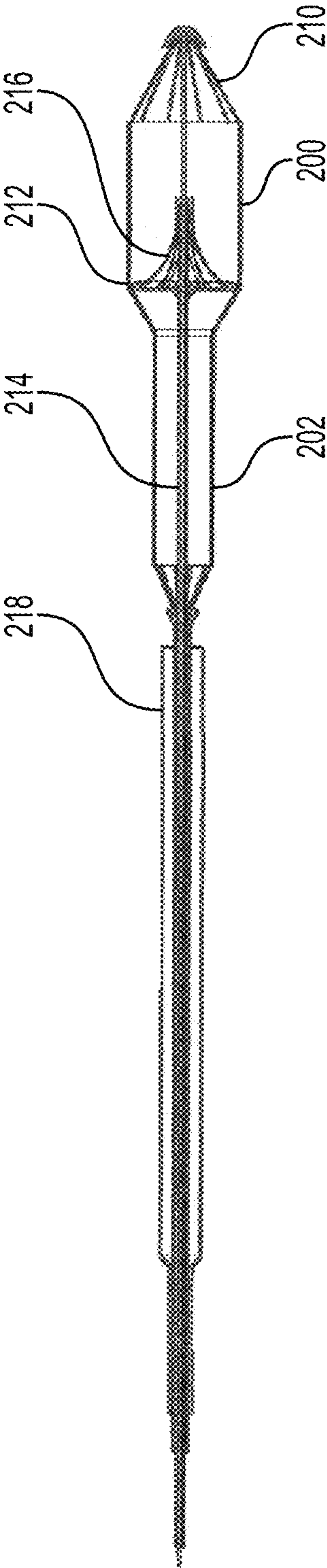


FIG. 11

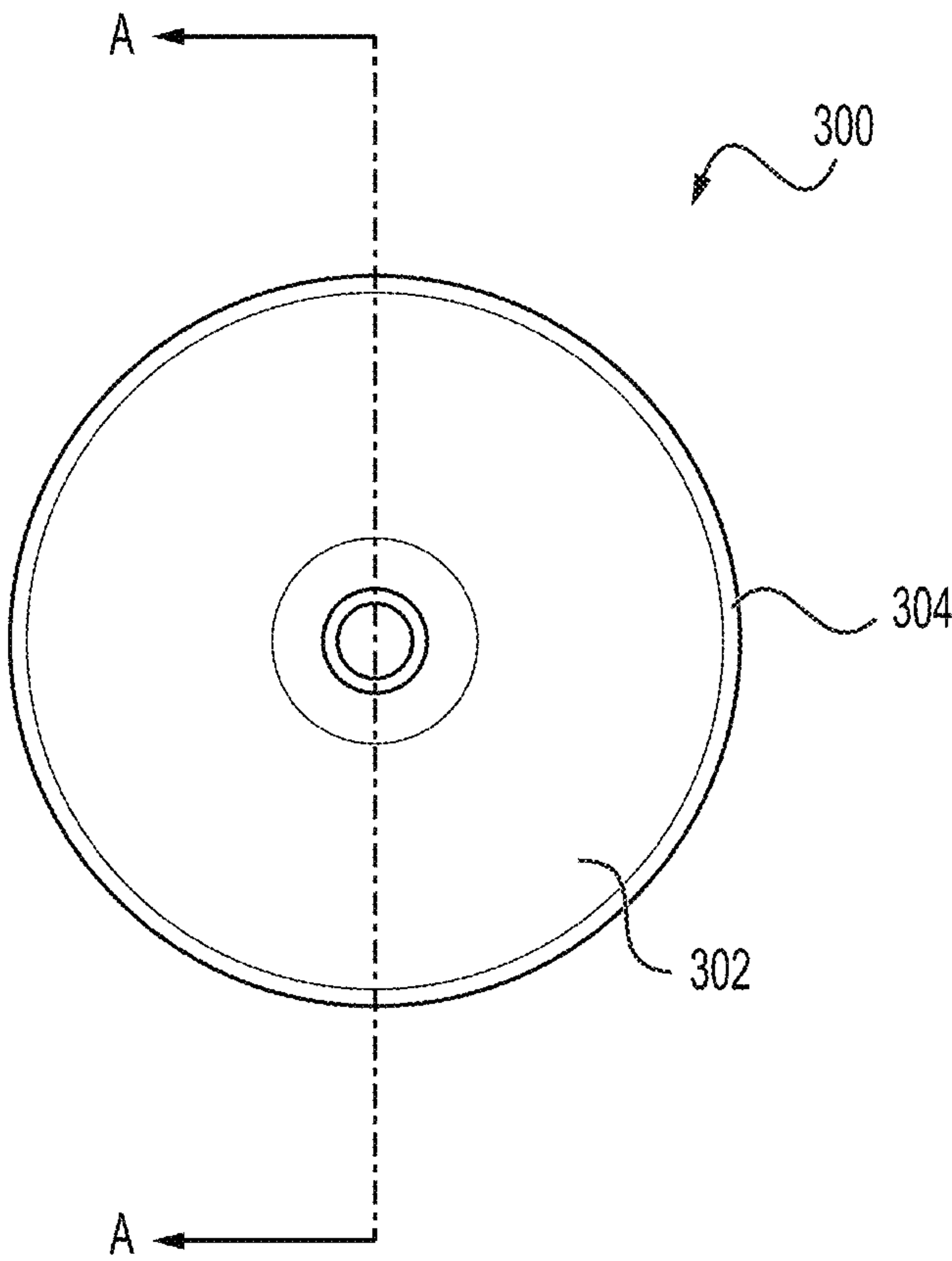


FIG. 12A

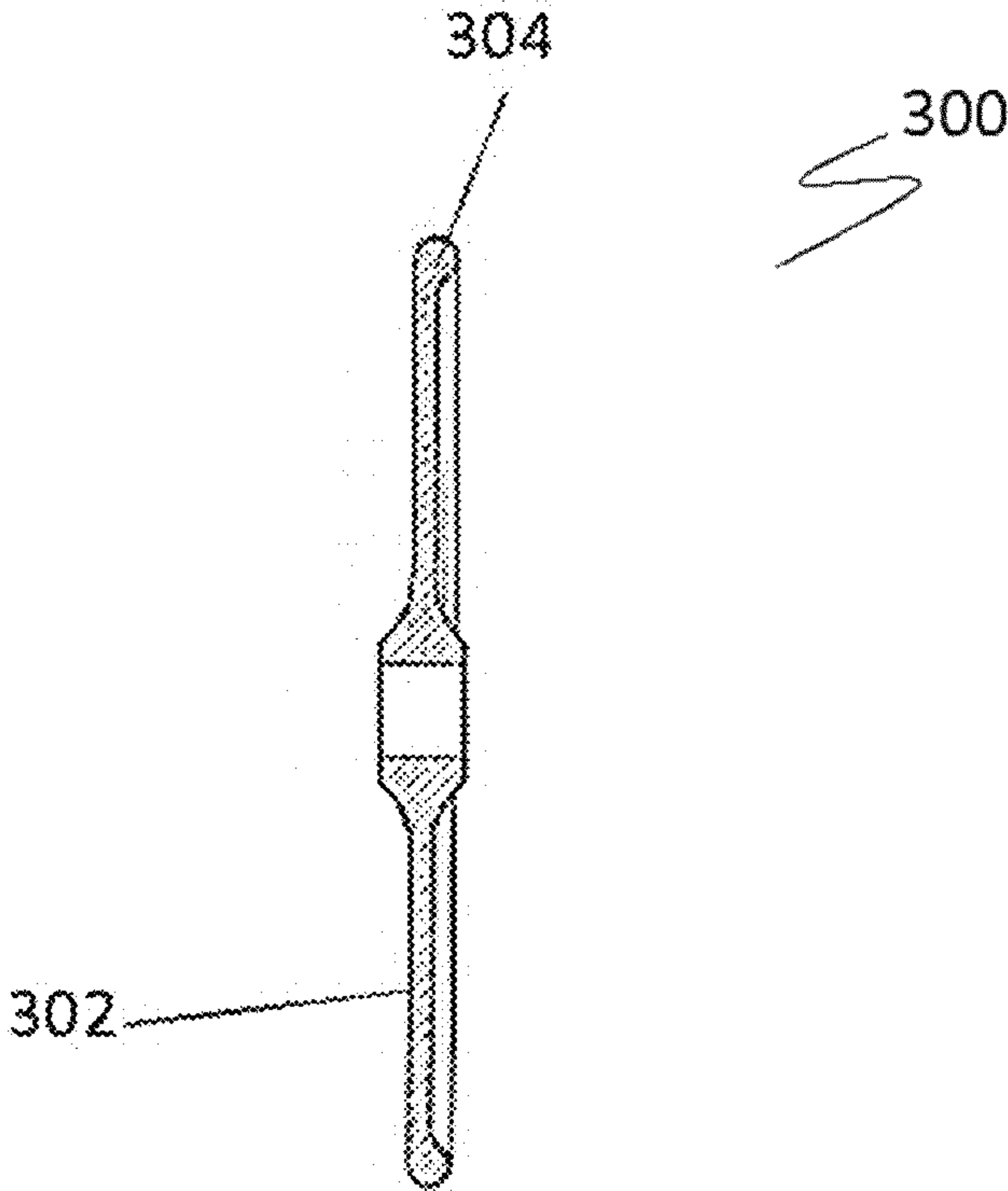


FIG. 12B

FIG. 12A

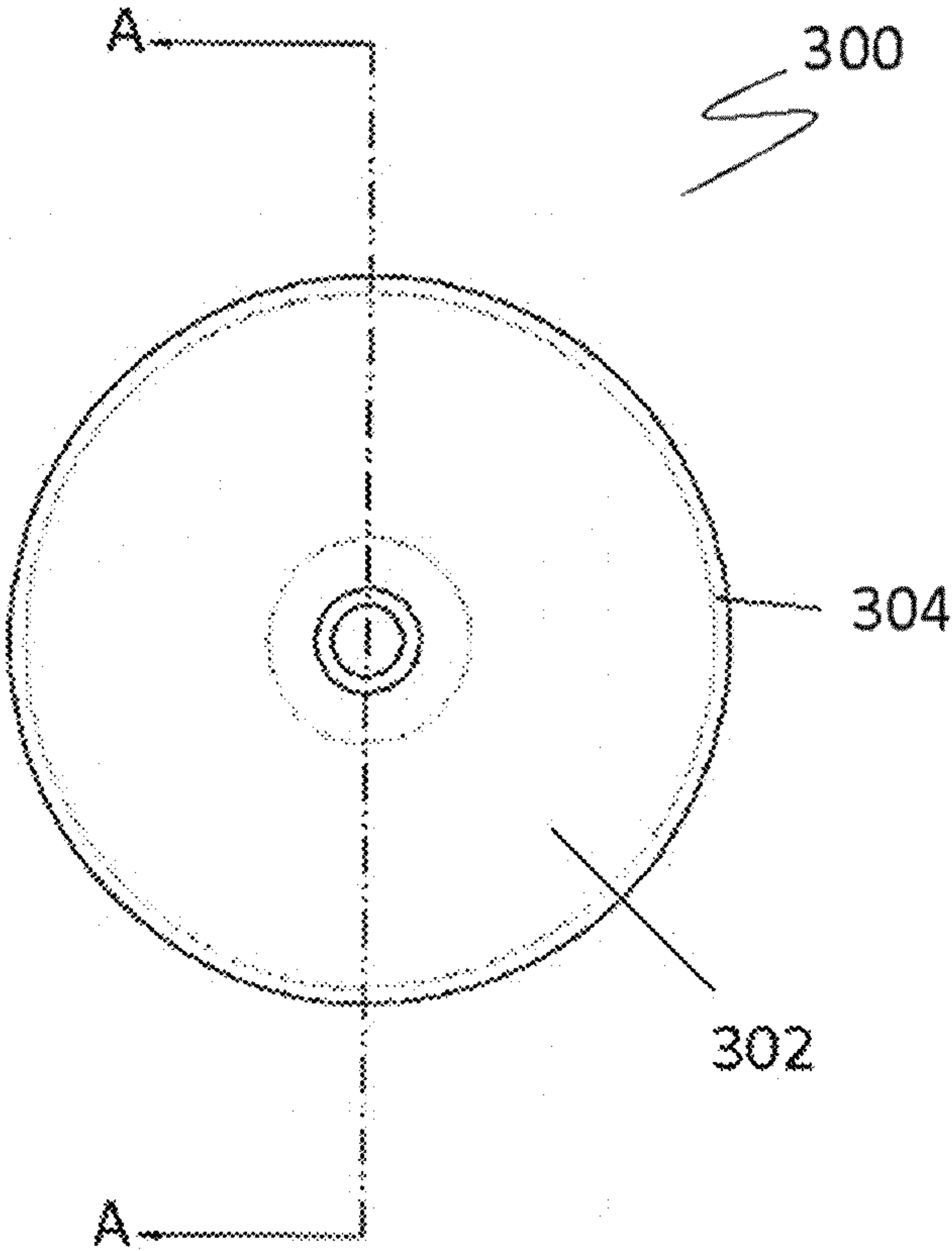
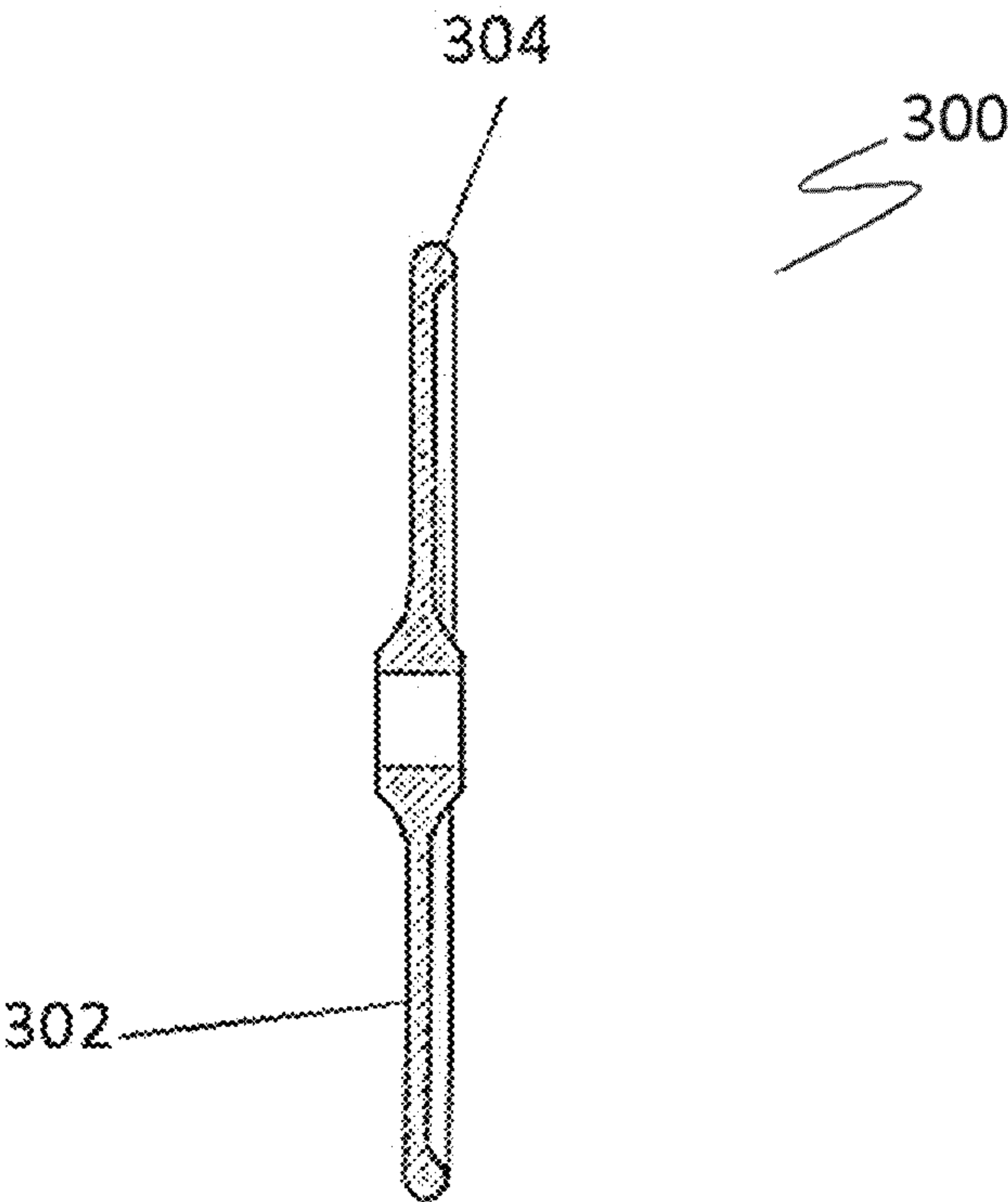


FIG. 12B



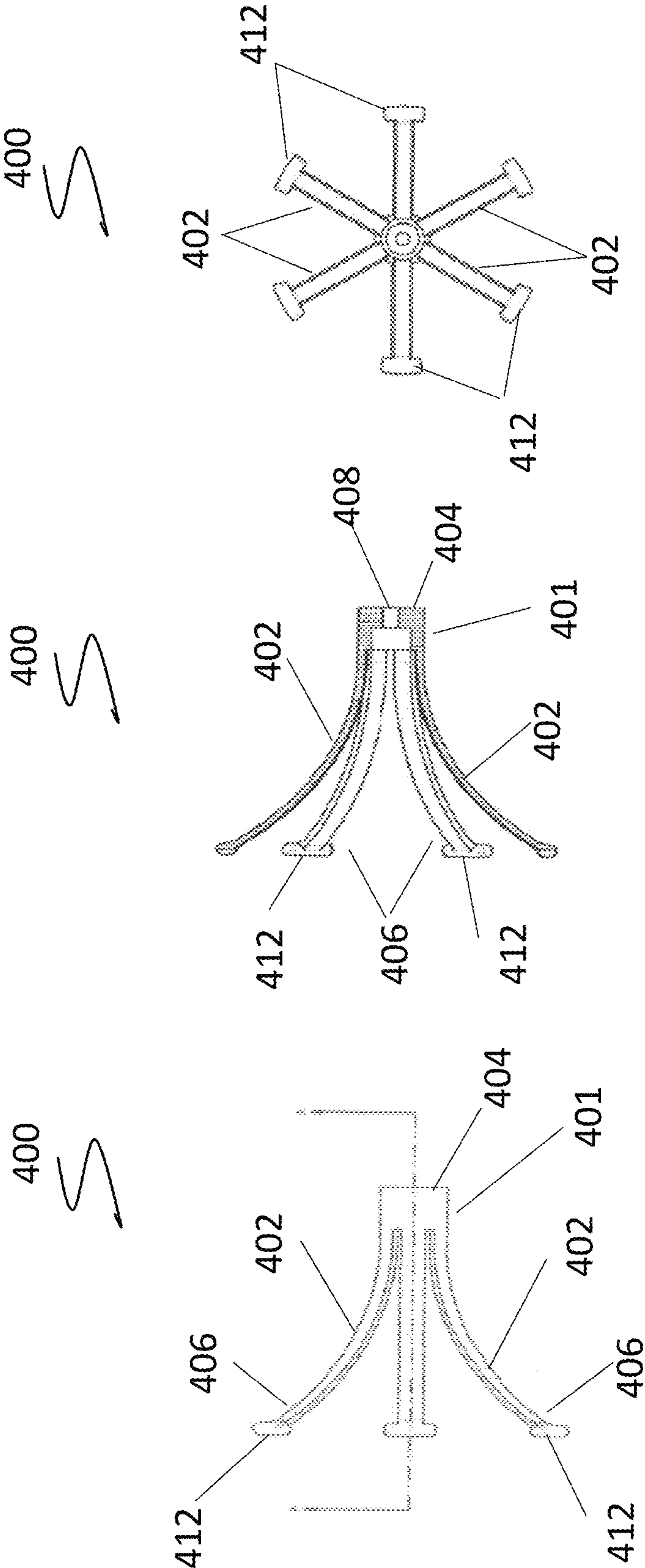


FIG. 13C

FIG. 13B

FIG. 13A

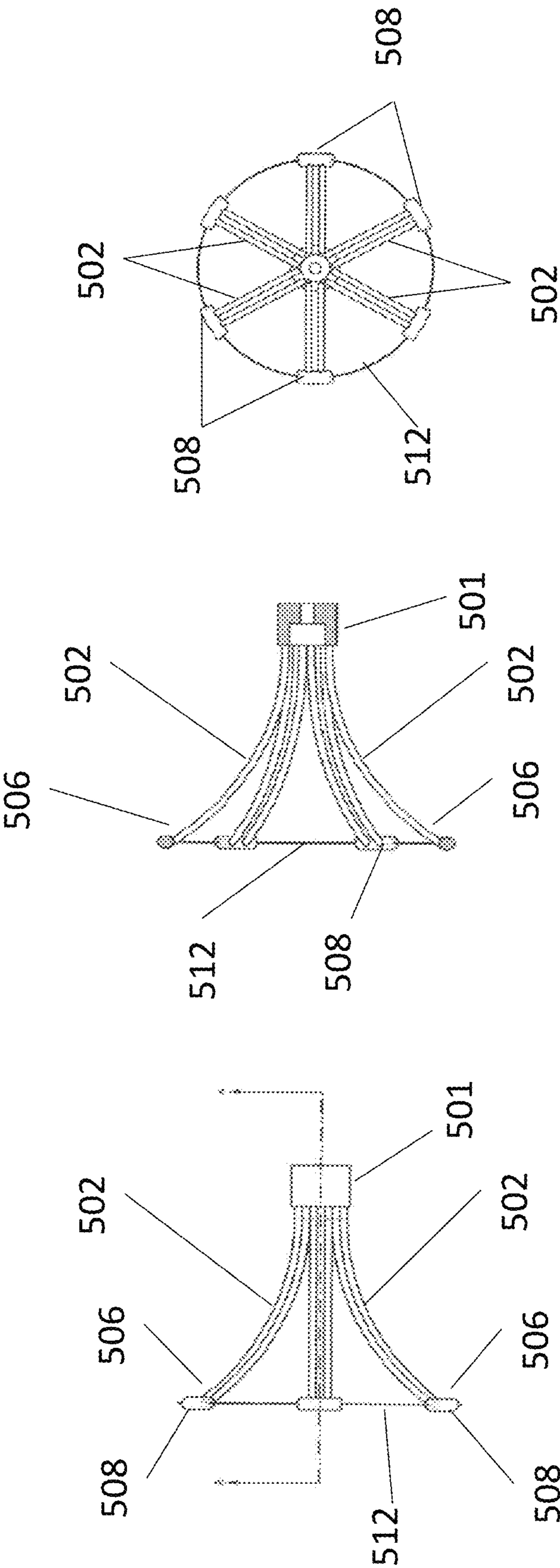


FIG. 14A

FIG. 14B

FIG. 14C

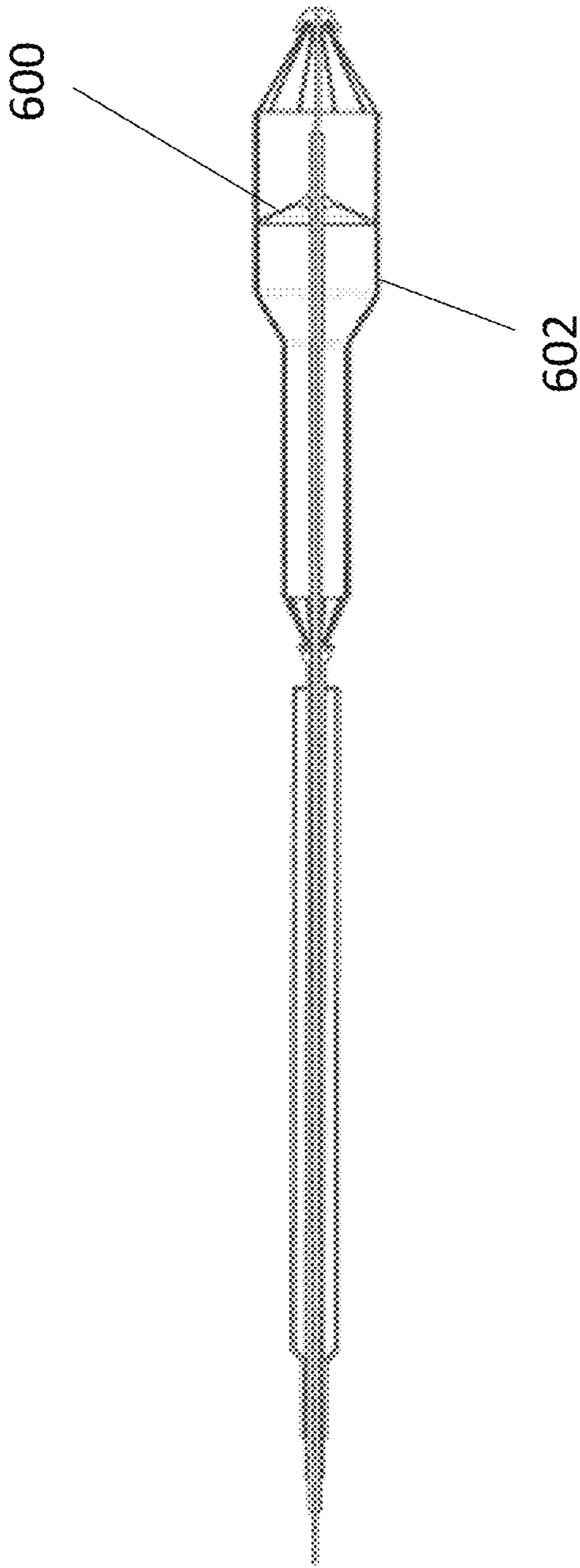


FIG. 15

FIG. 16A

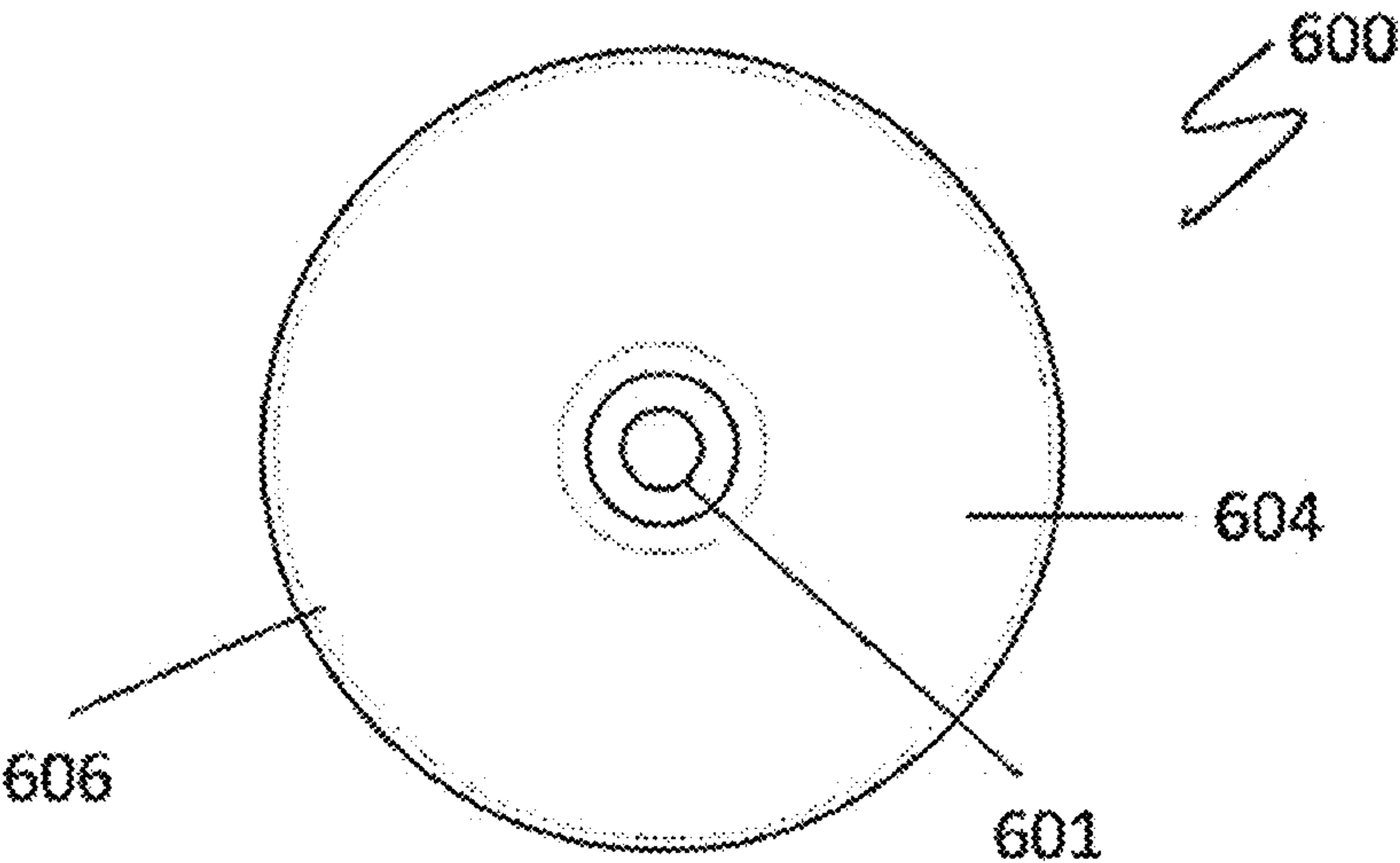


FIG. 16B

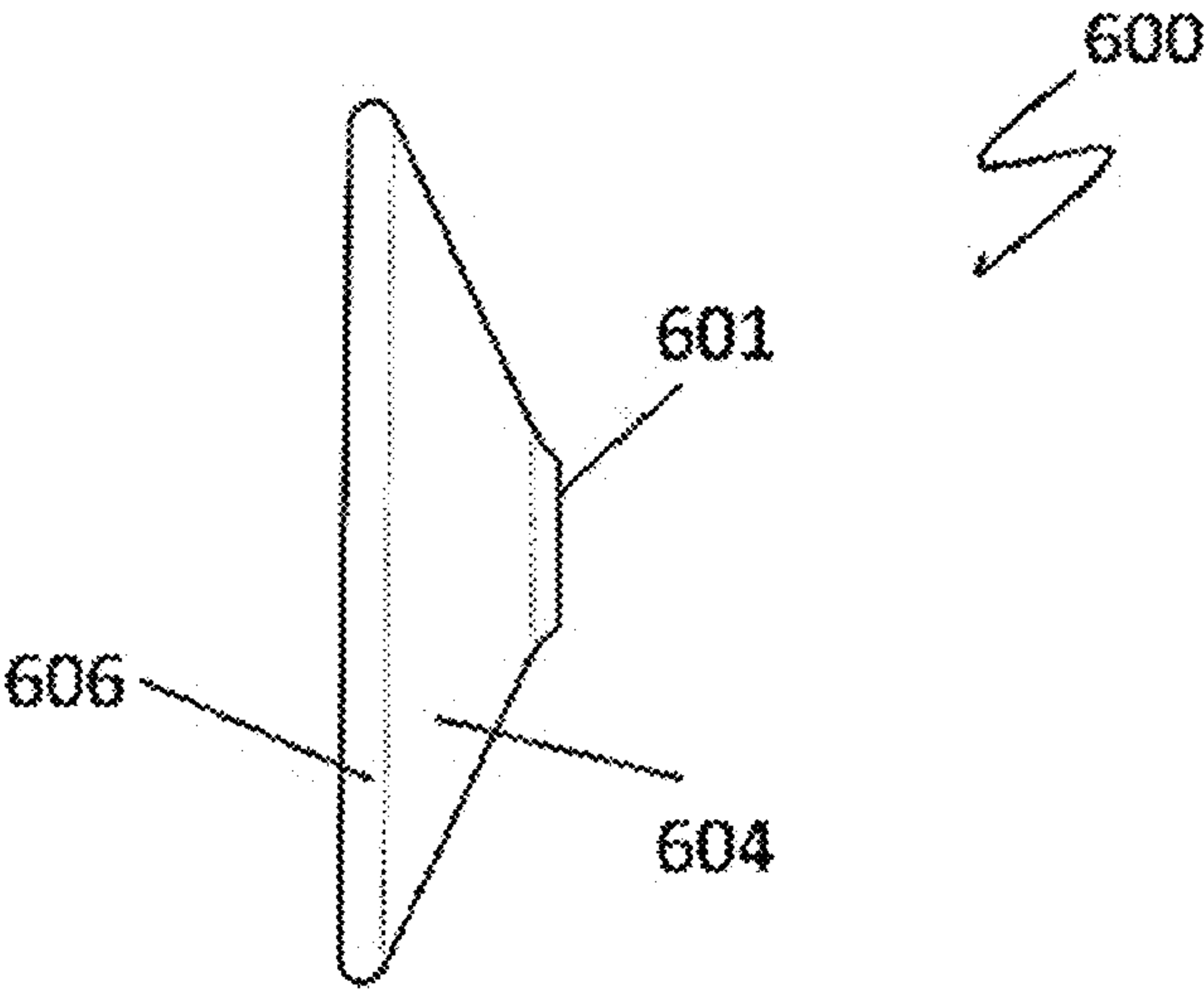
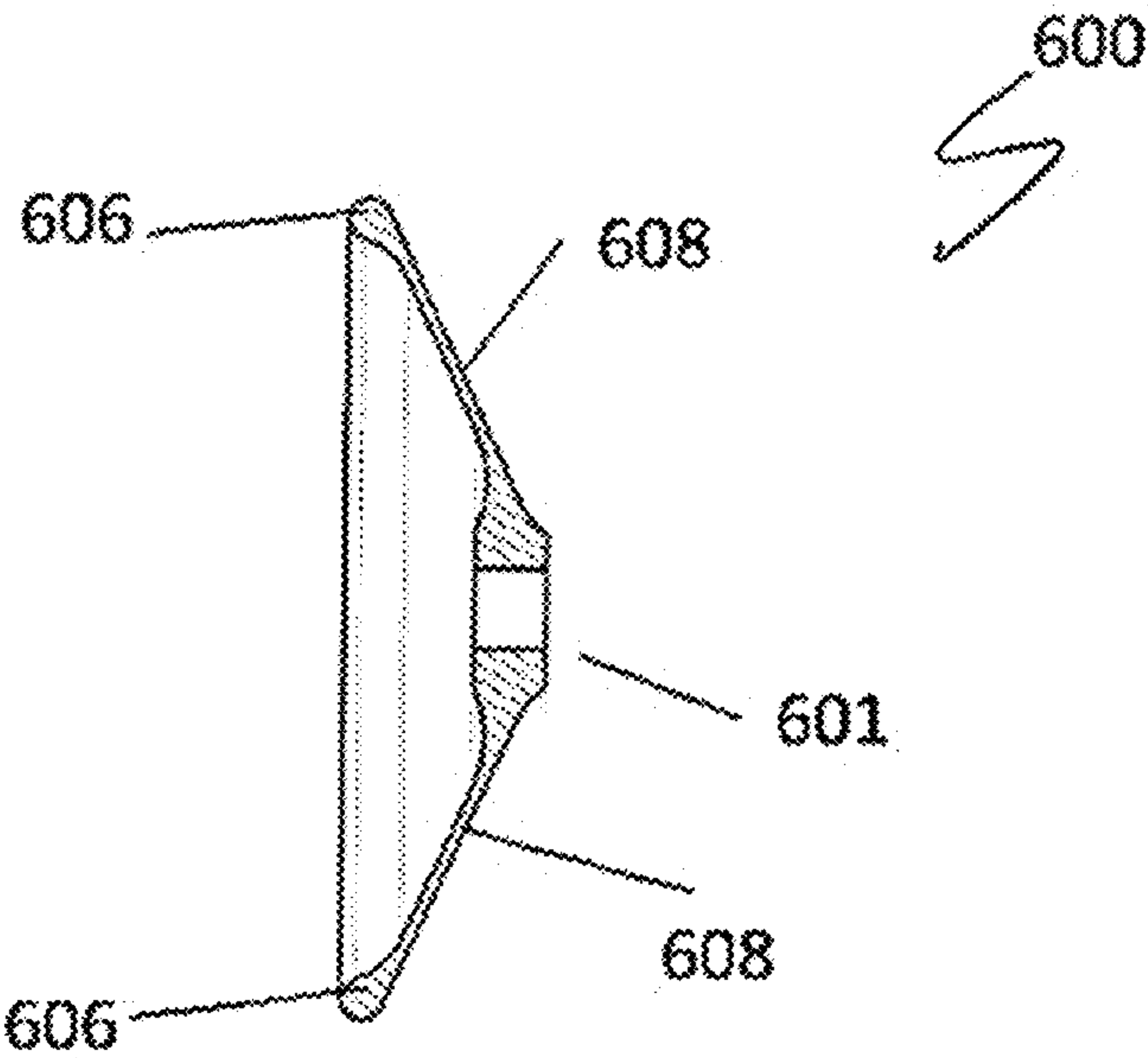


FIG. 16C



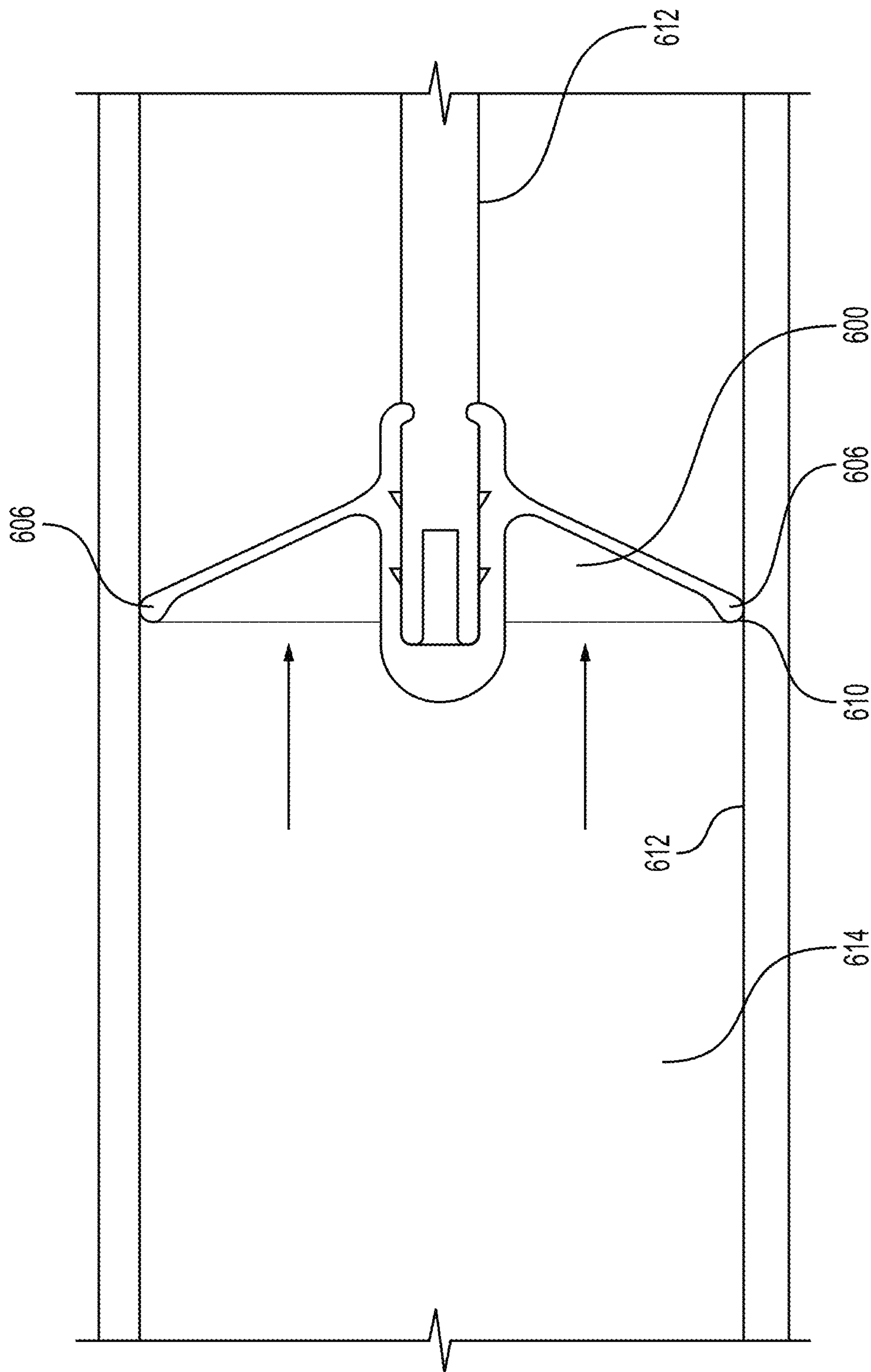


FIG. 17

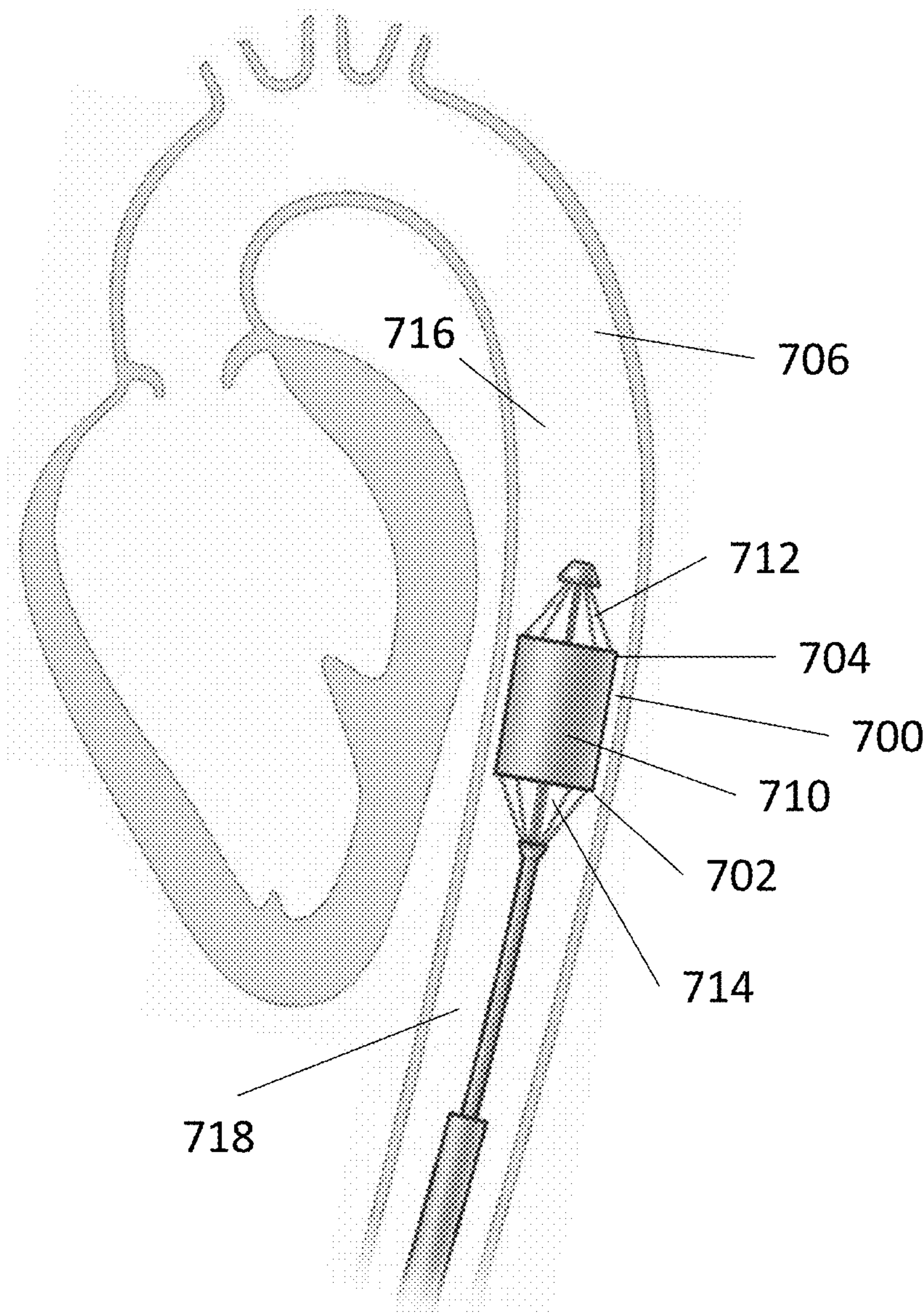


FIG. 18A

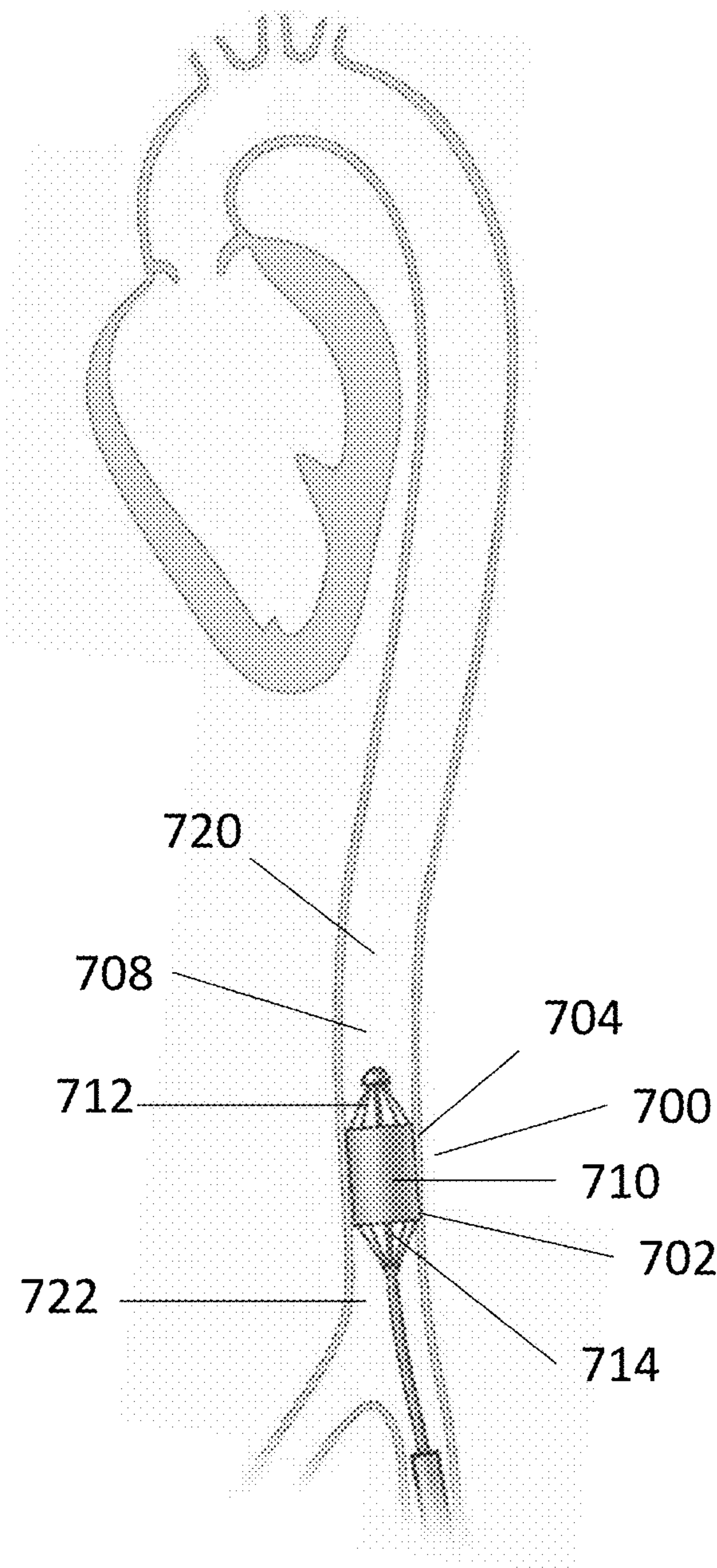


FIG. 18B

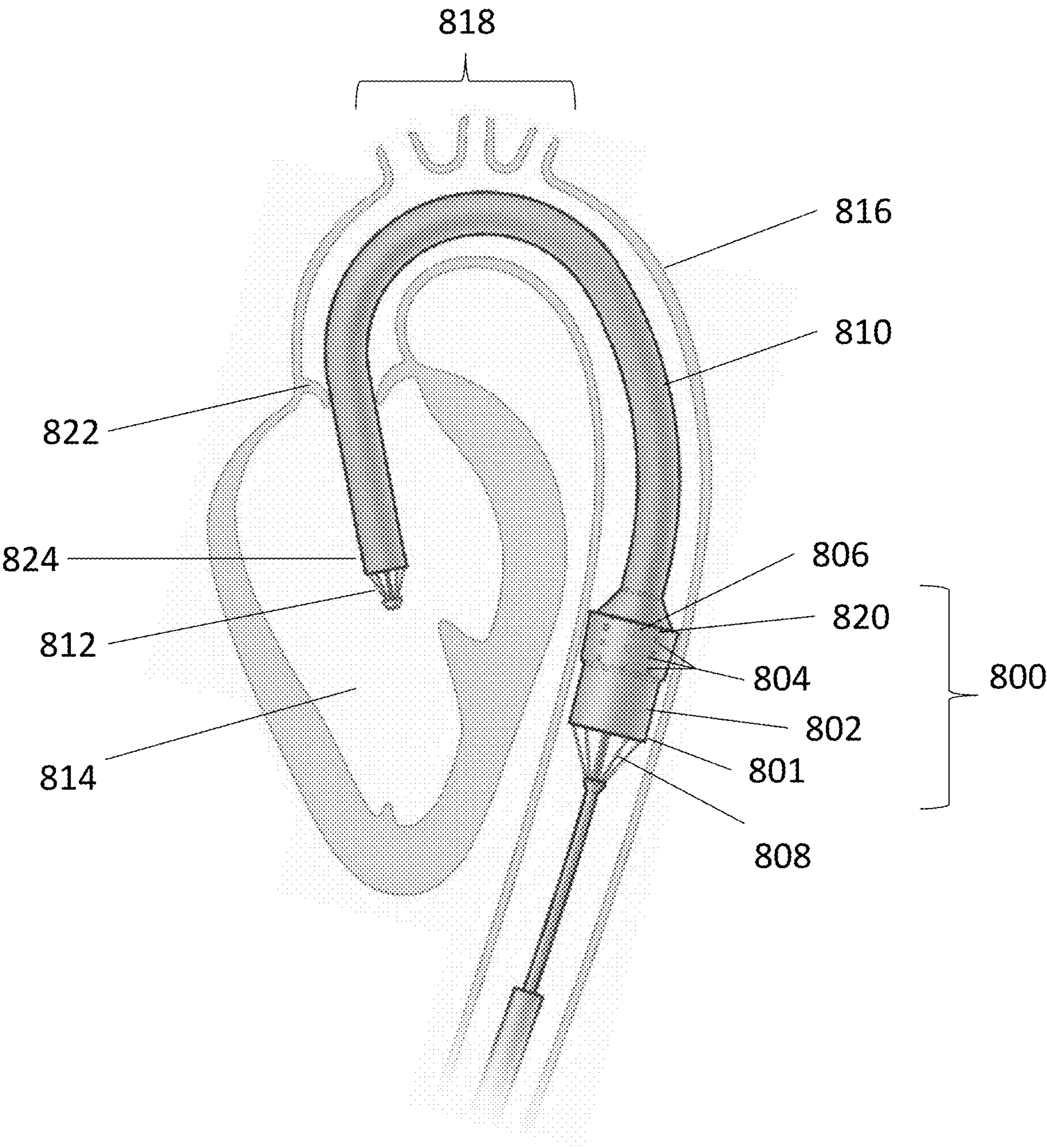


FIG. 19

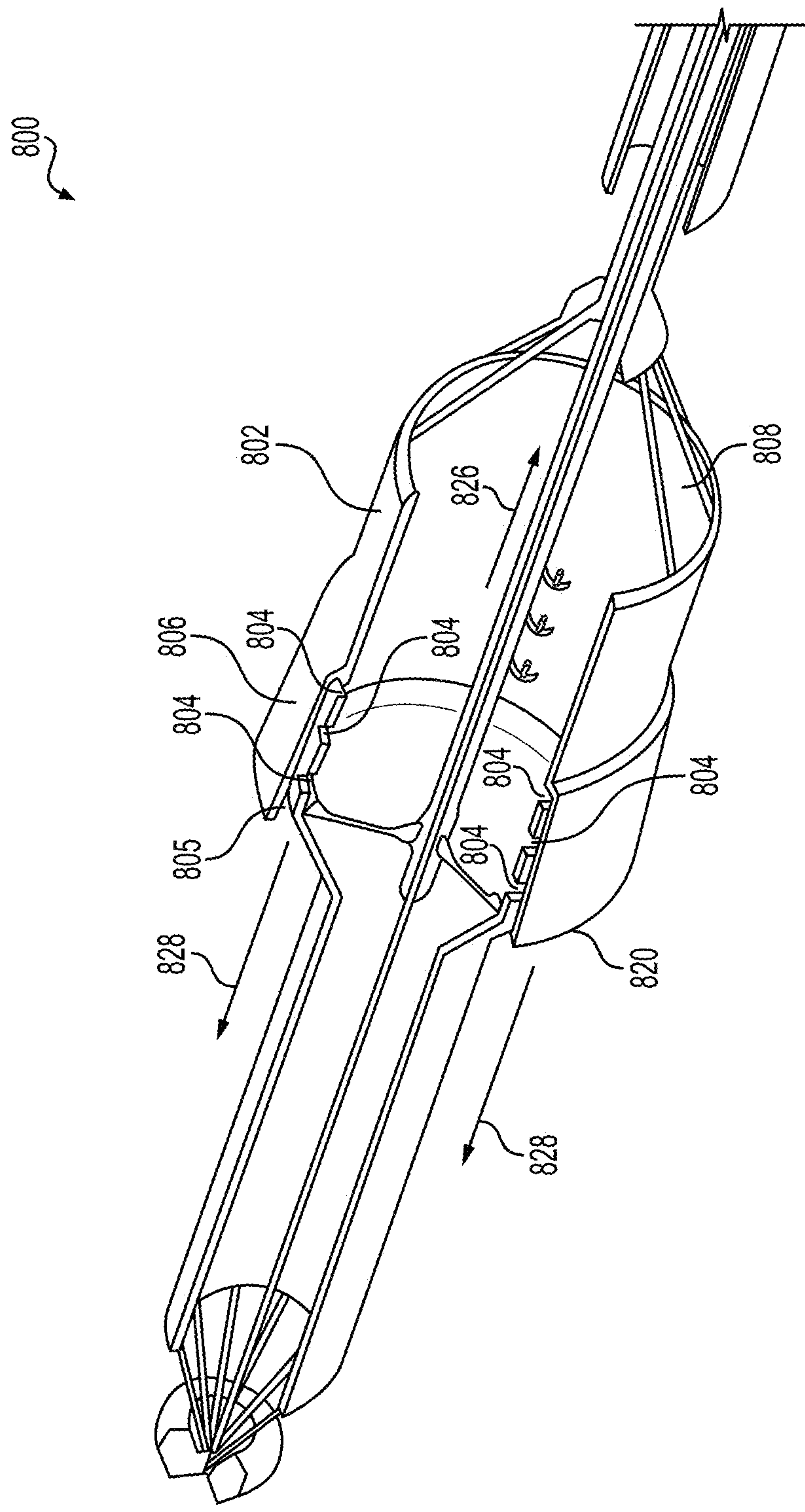


FIG. 20

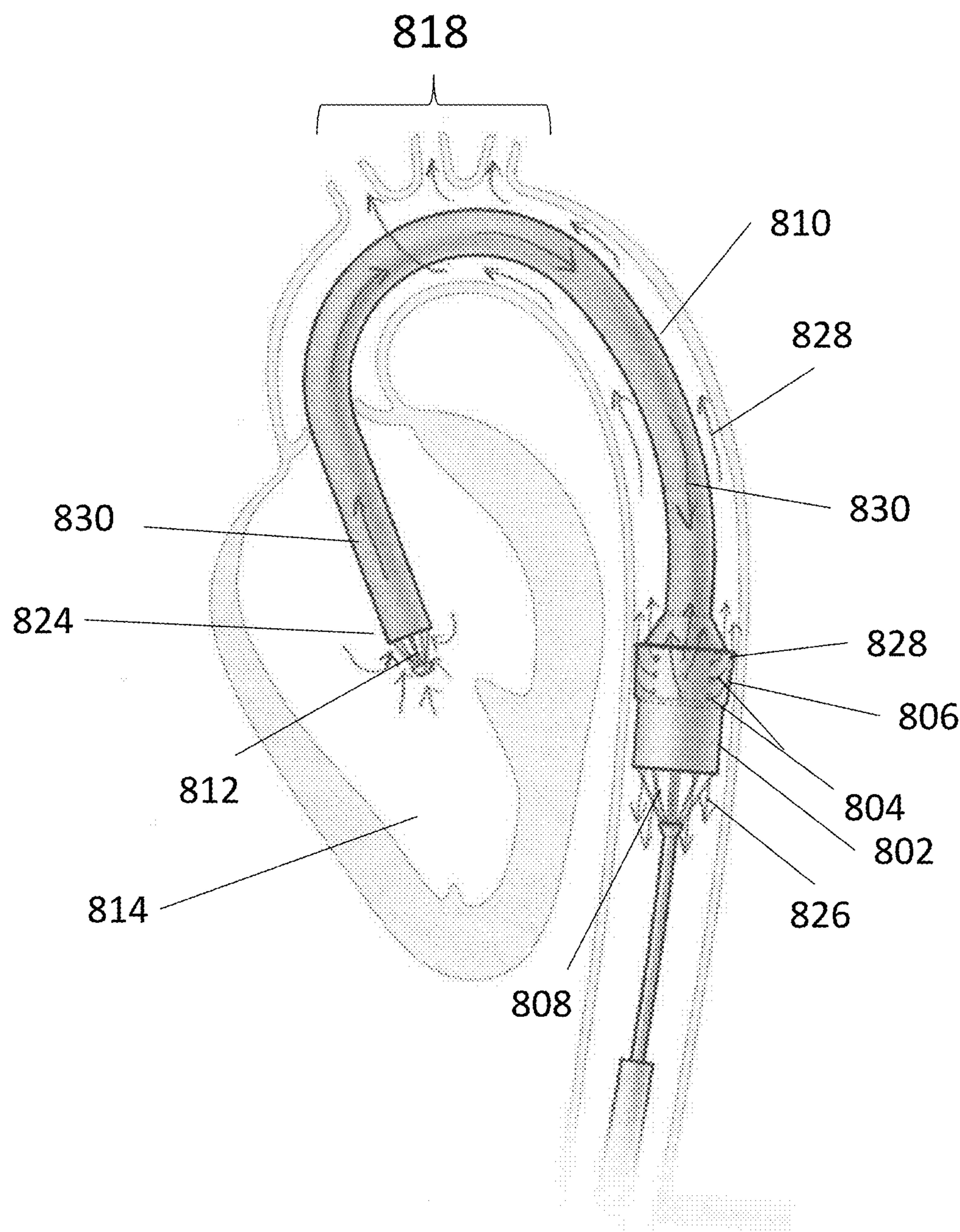


FIG. 21

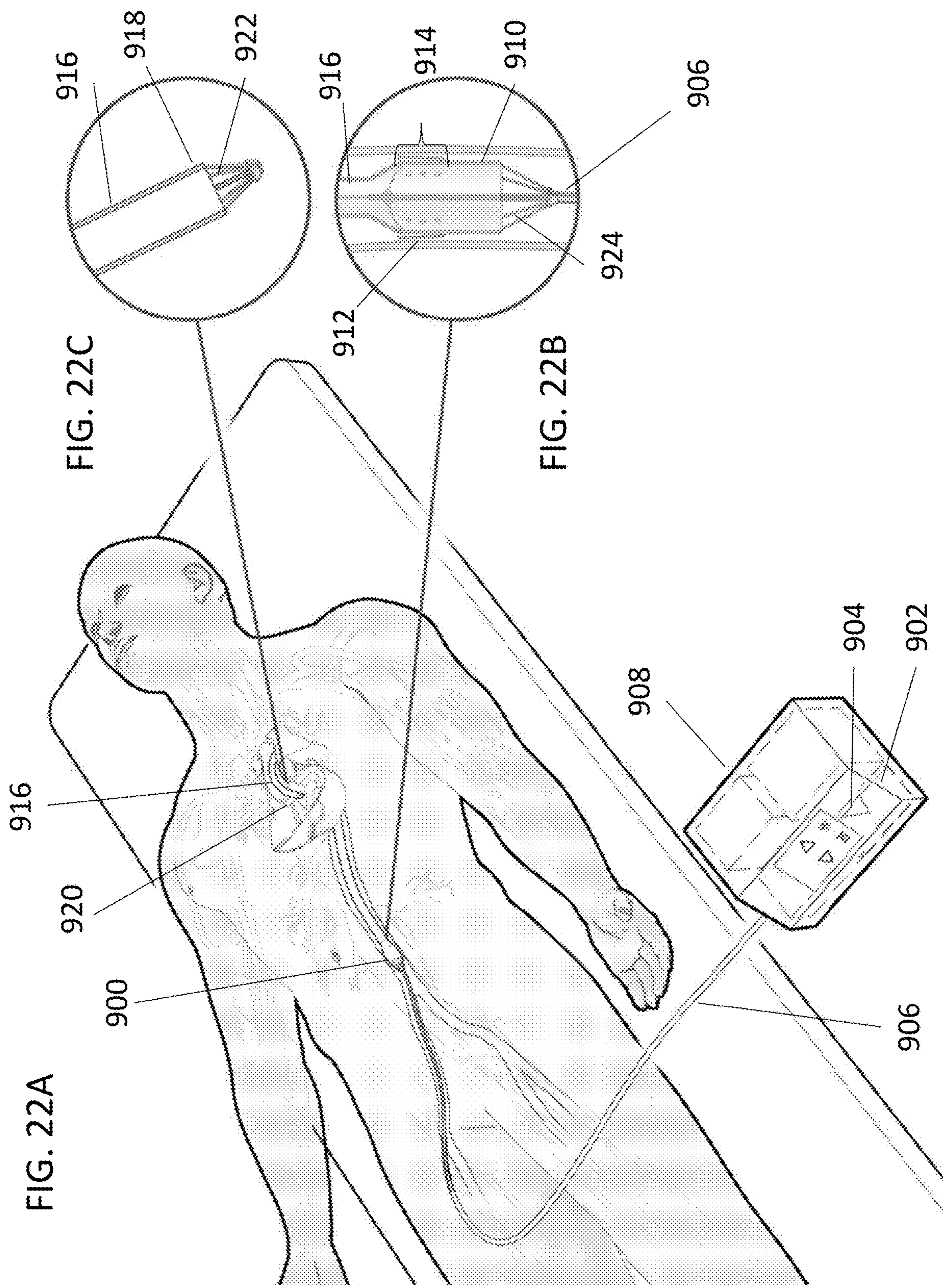


FIG. 23A

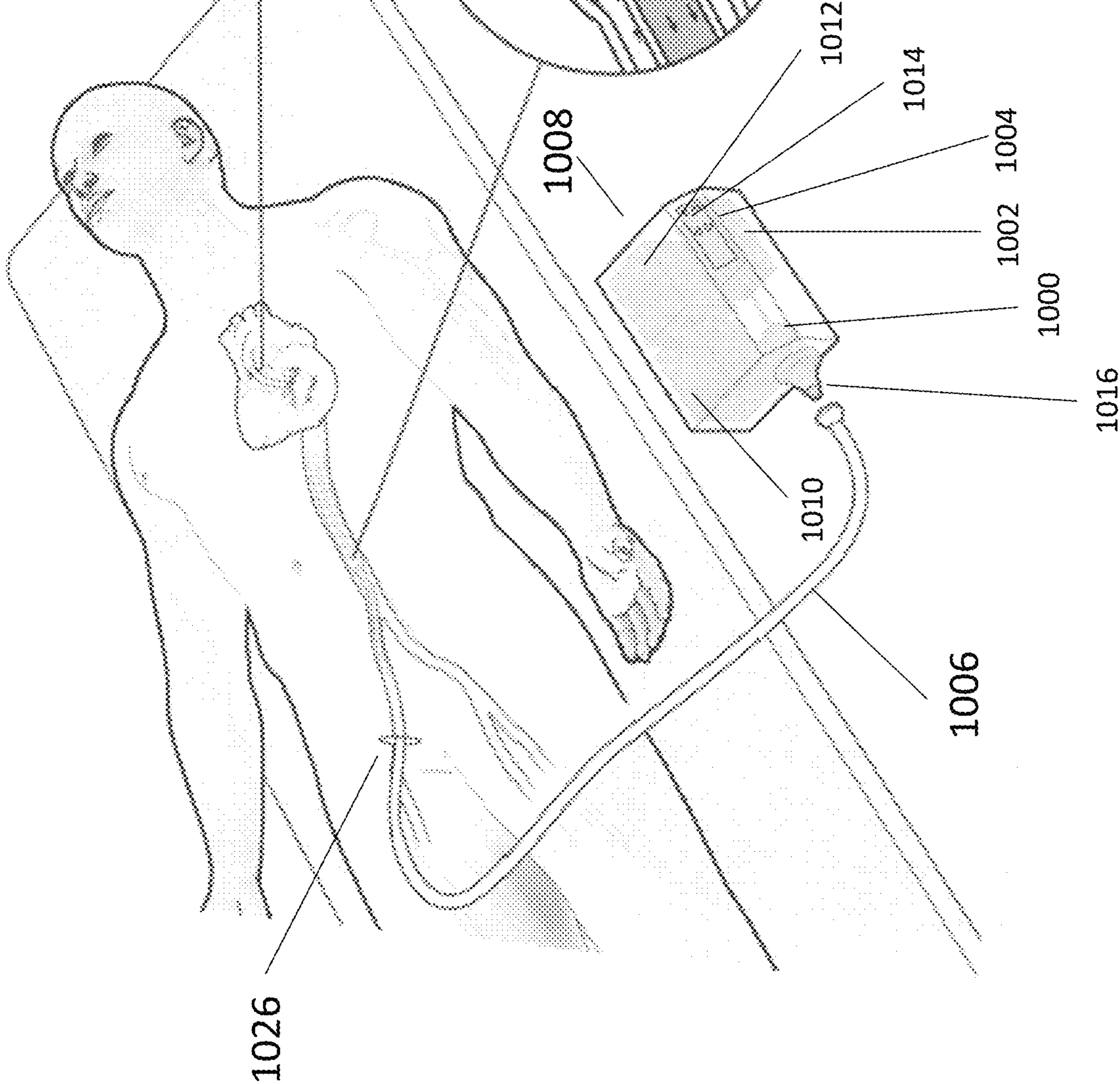


FIG. 23C

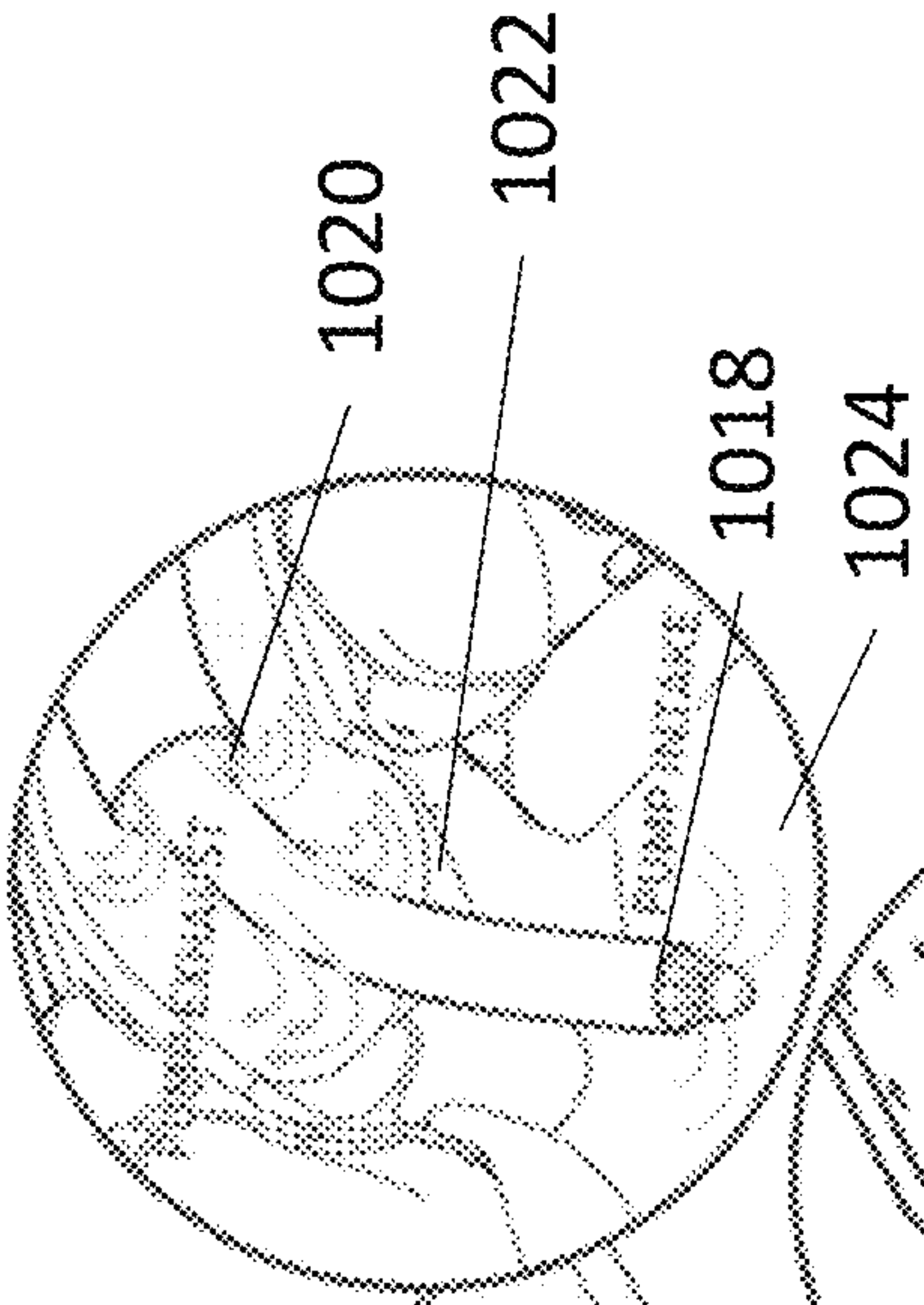
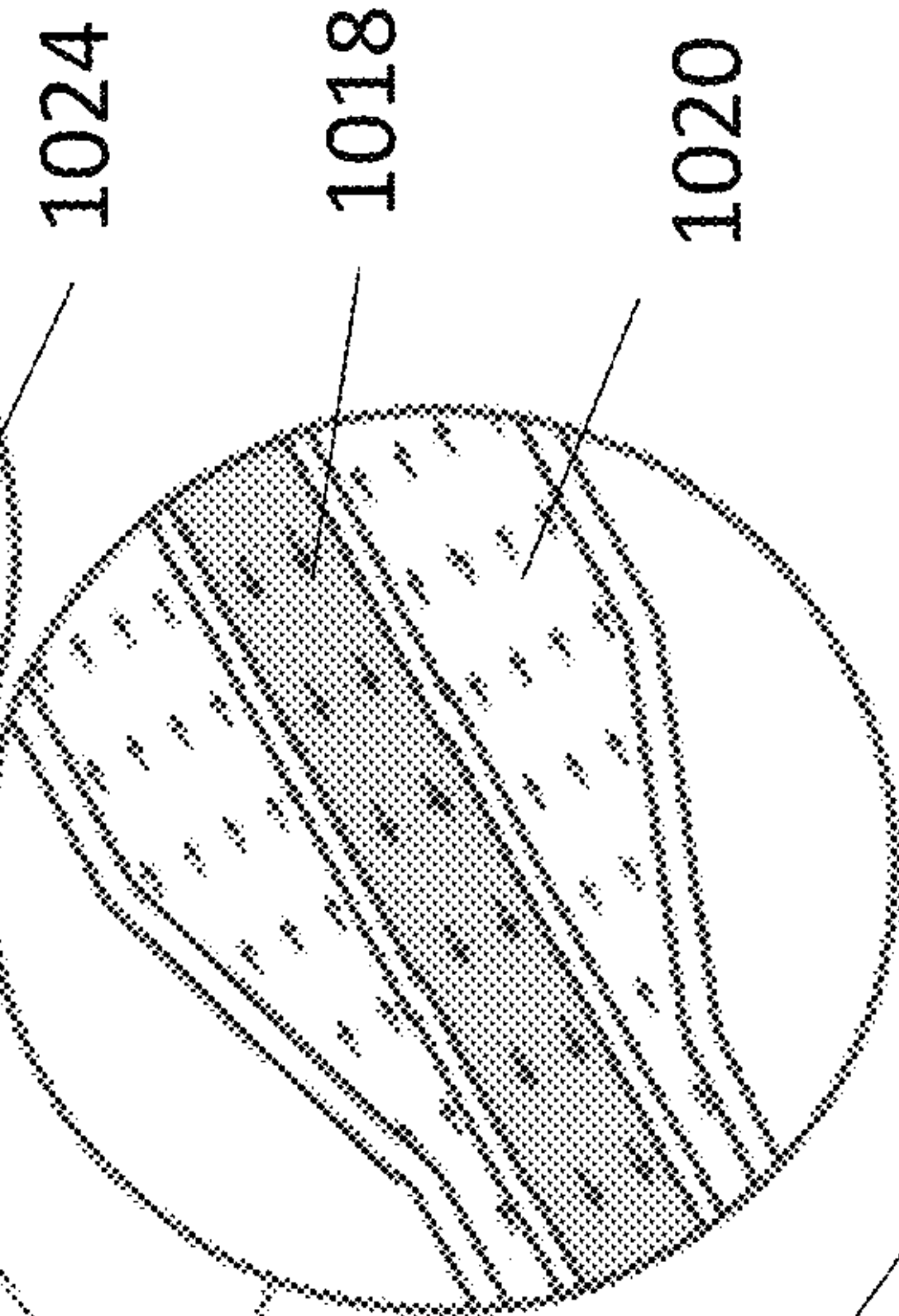


FIG. 23B



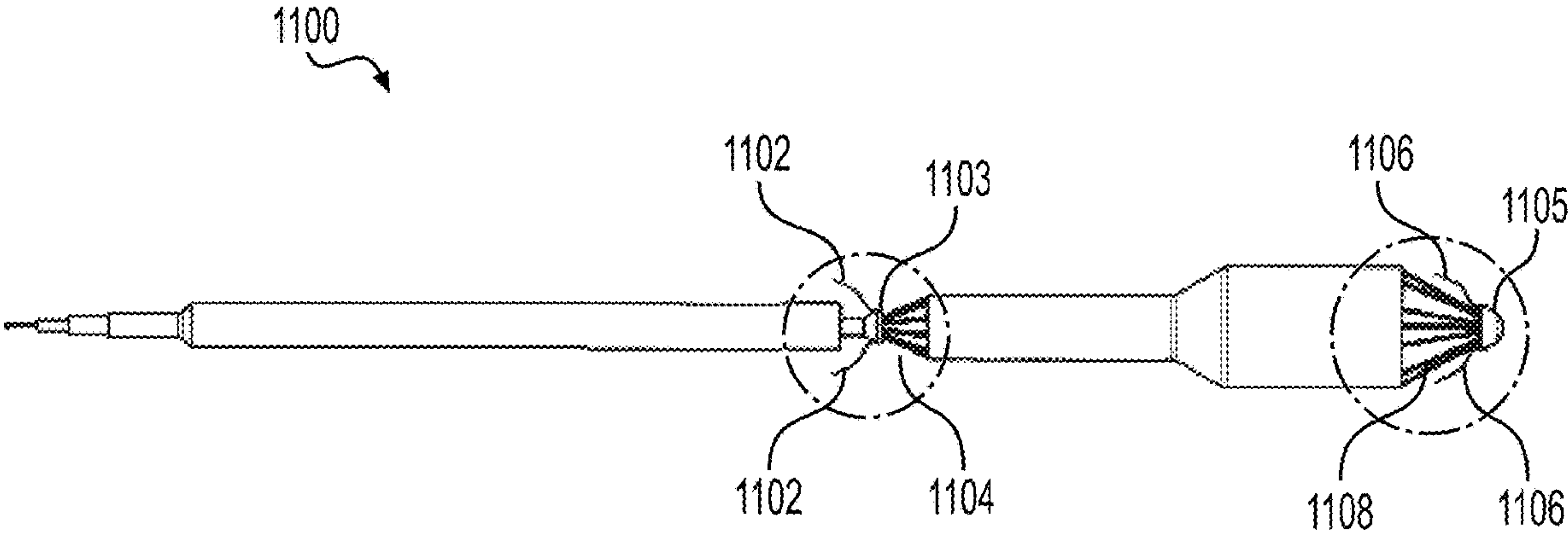


FIG. 24A

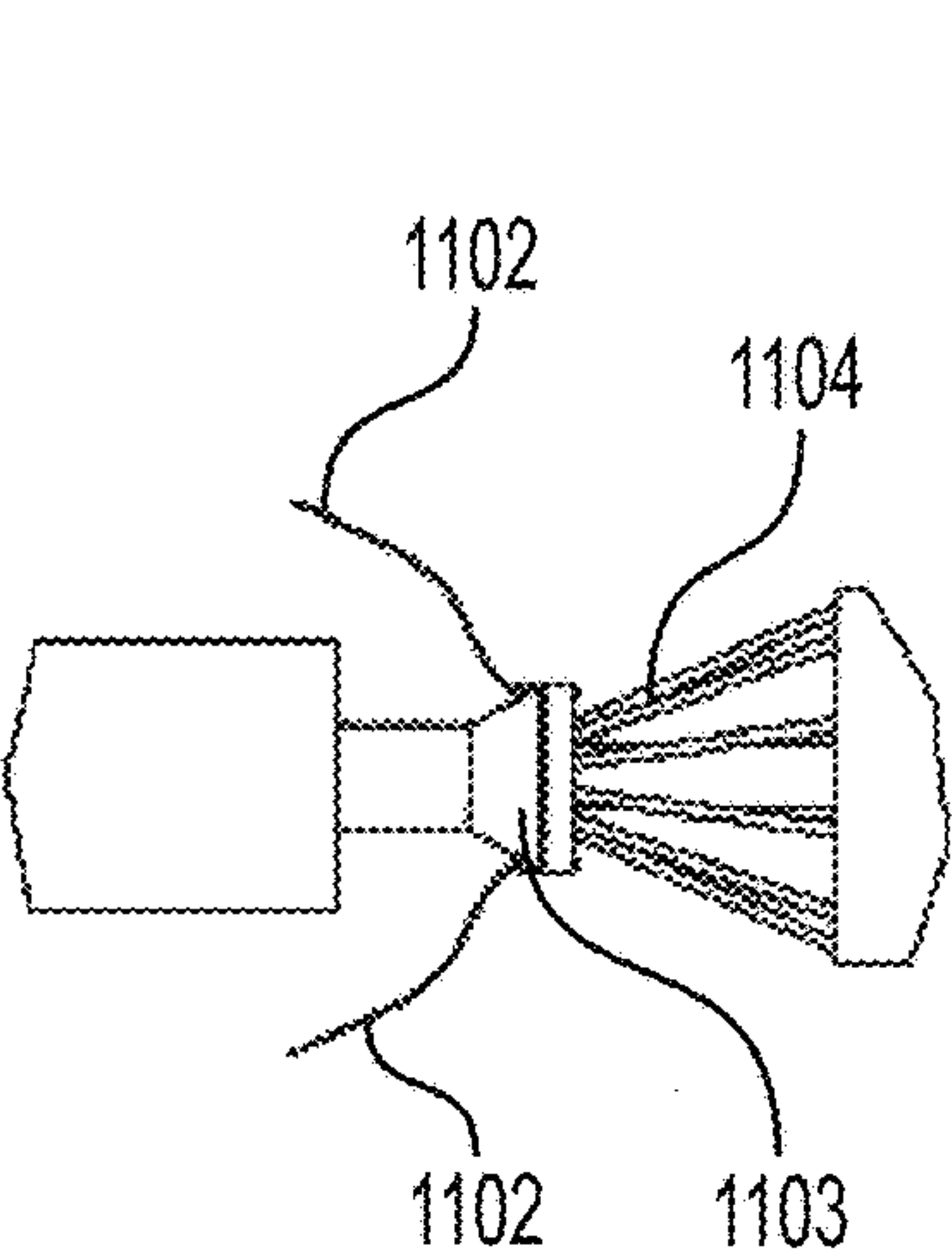


FIG. 24B

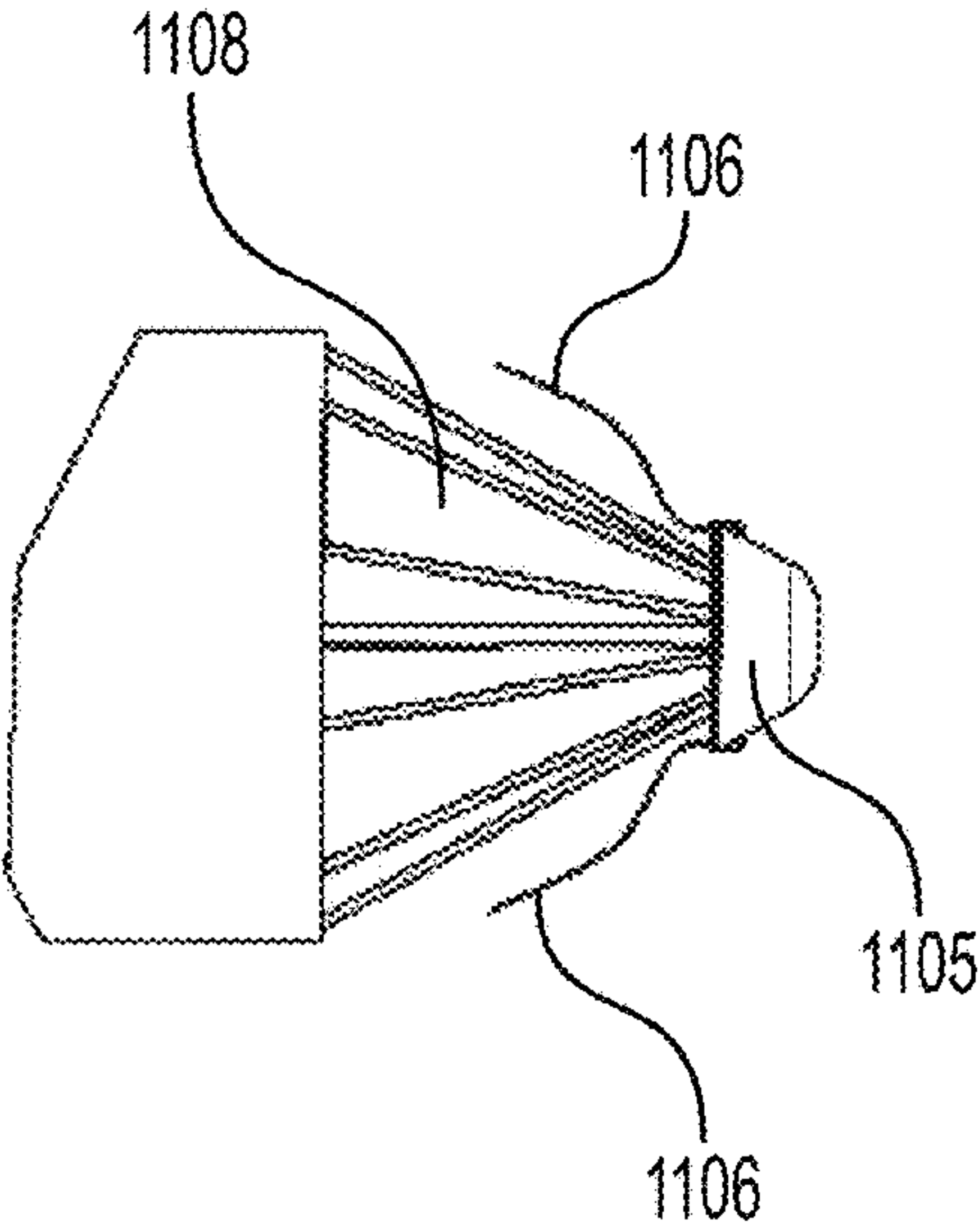


FIG. 24C

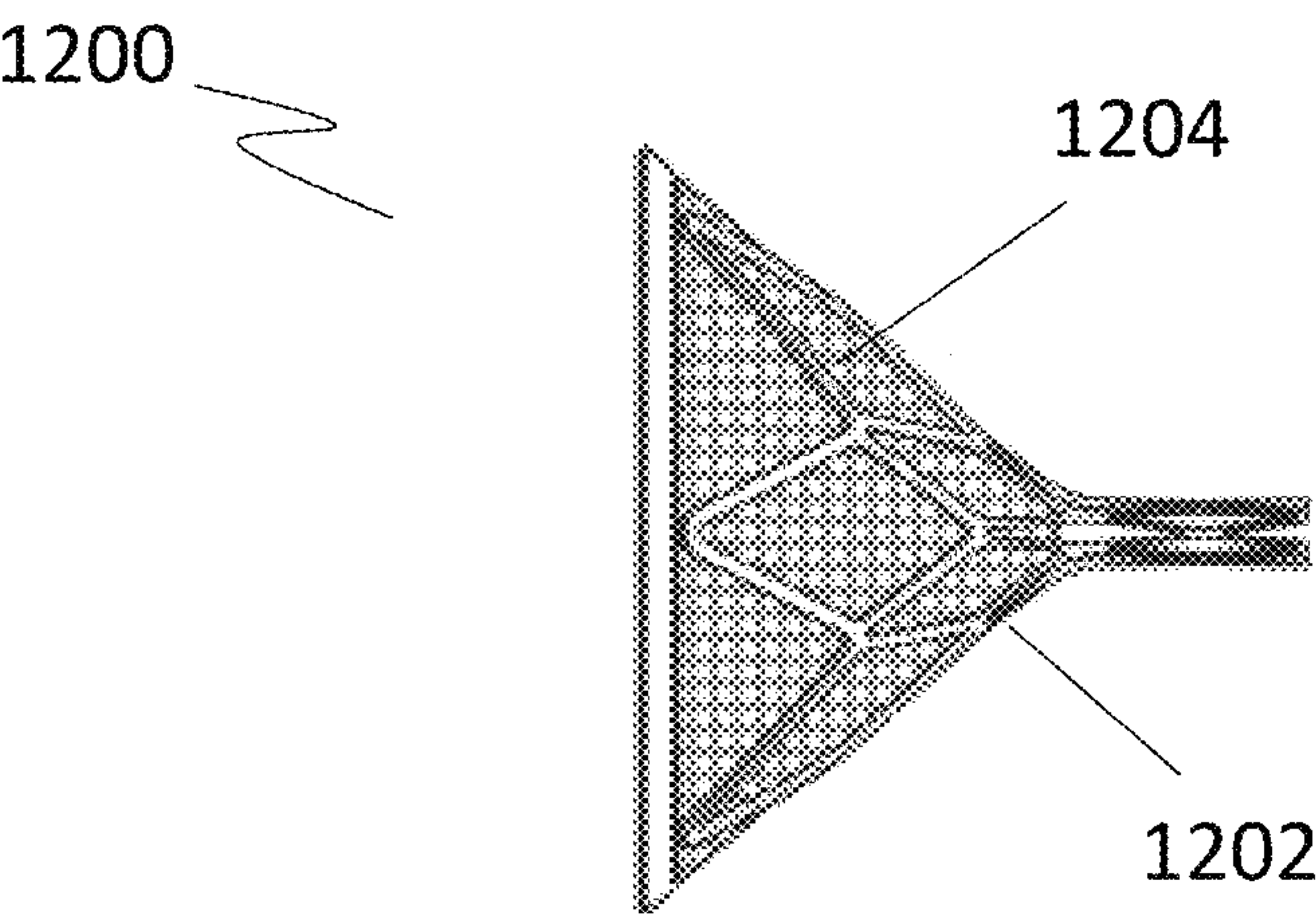


FIG. 25A

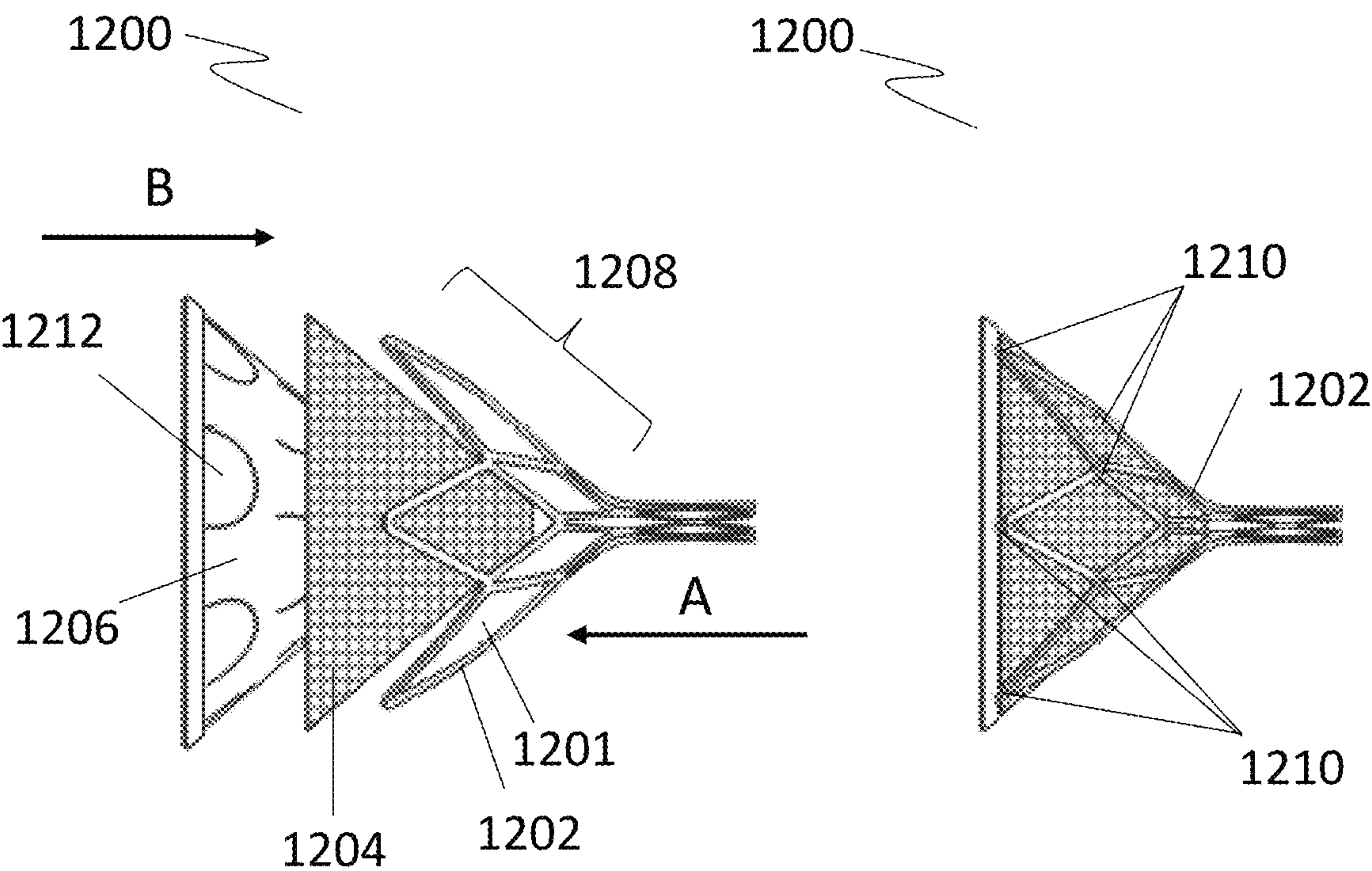


FIG. 25B

FIG. 25C

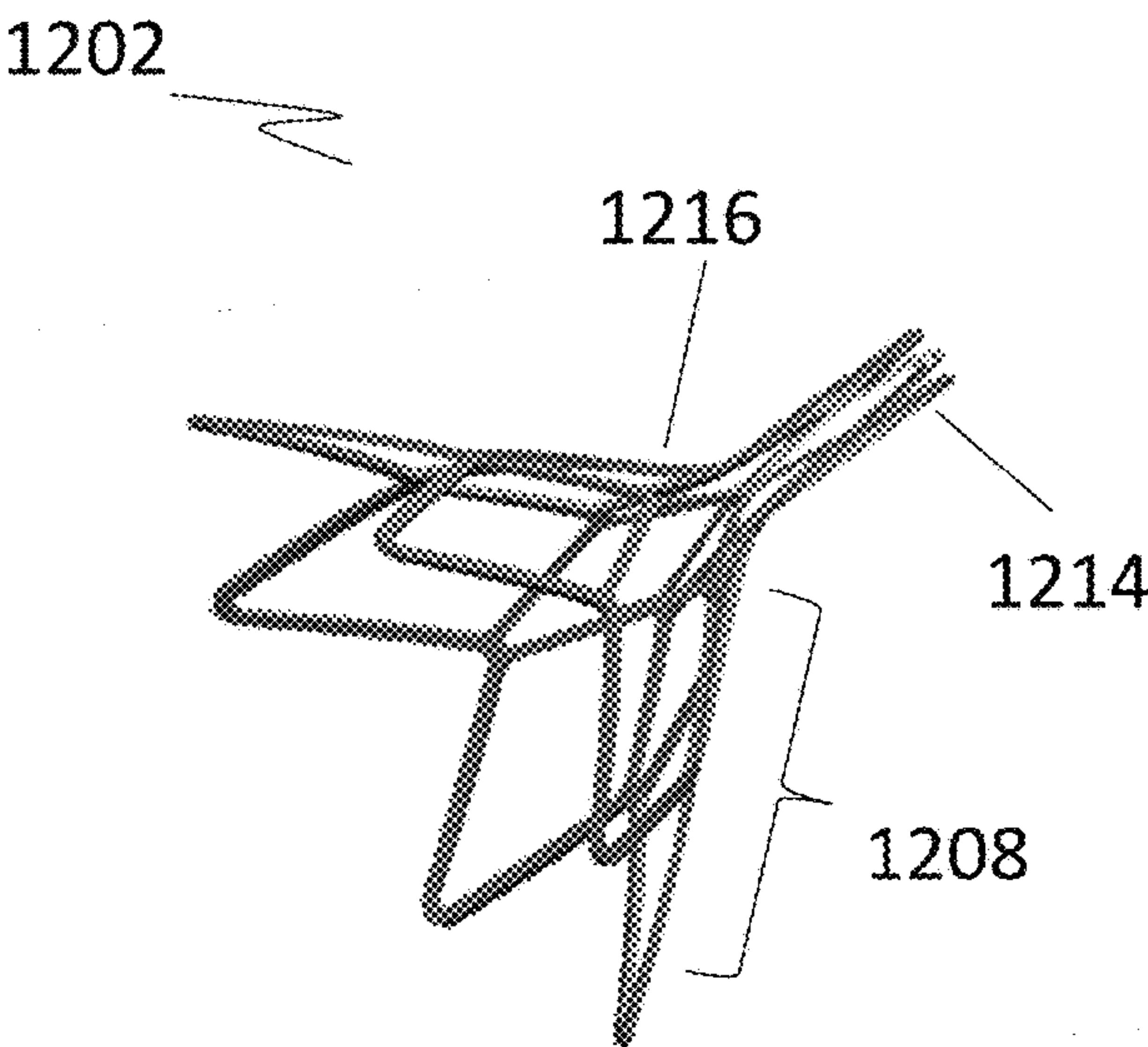


FIG. 26A

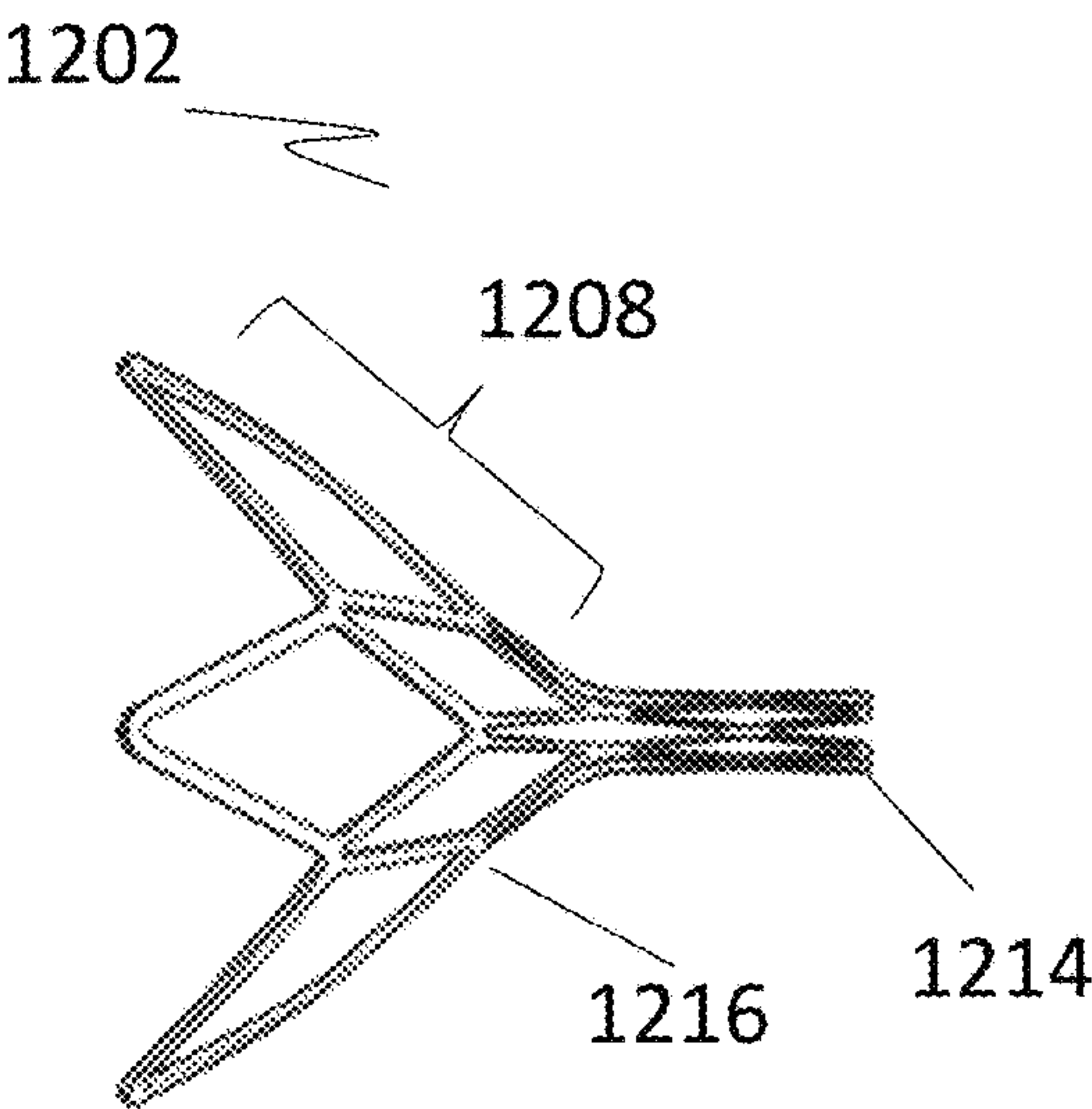


FIG. 26B

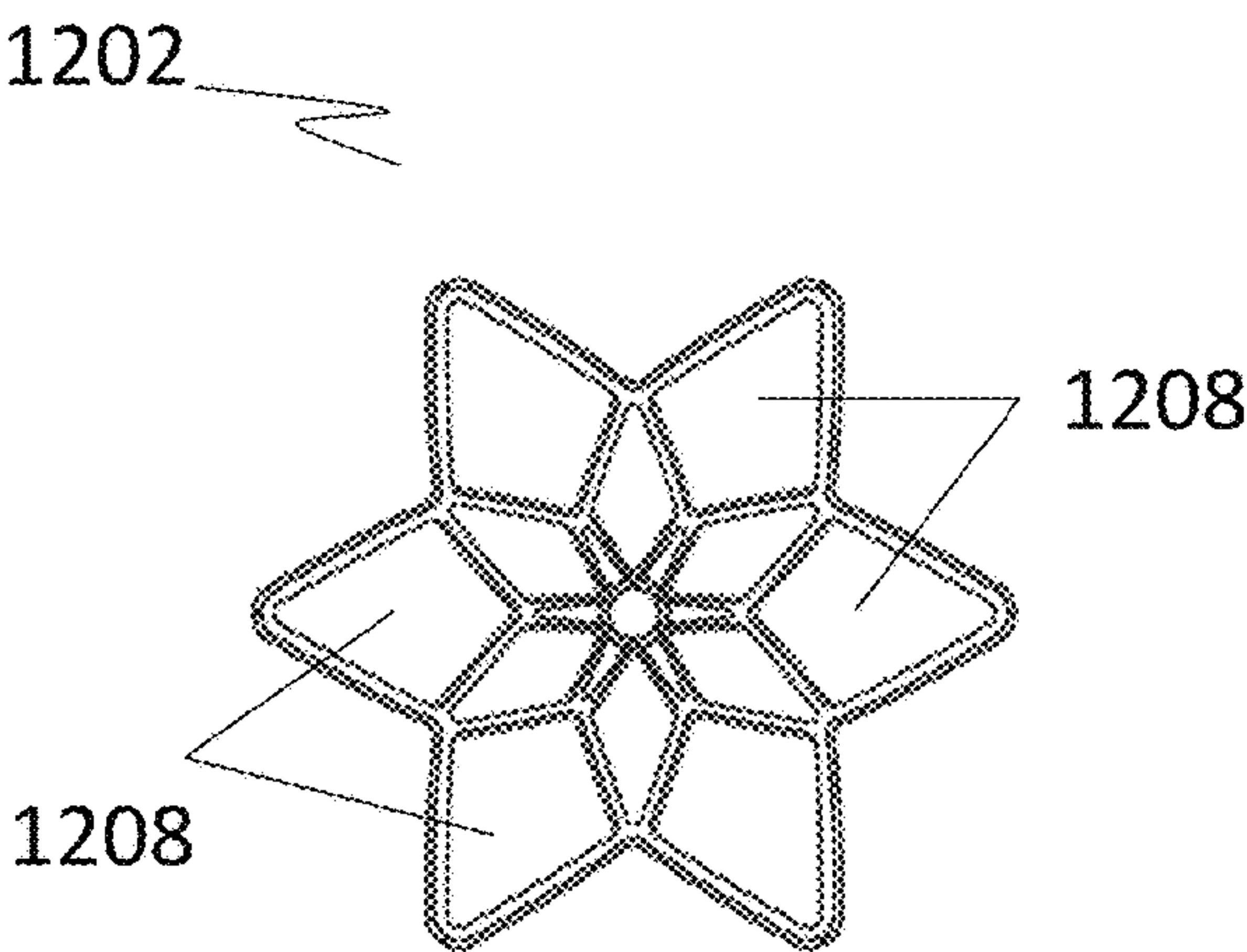


FIG. 26C

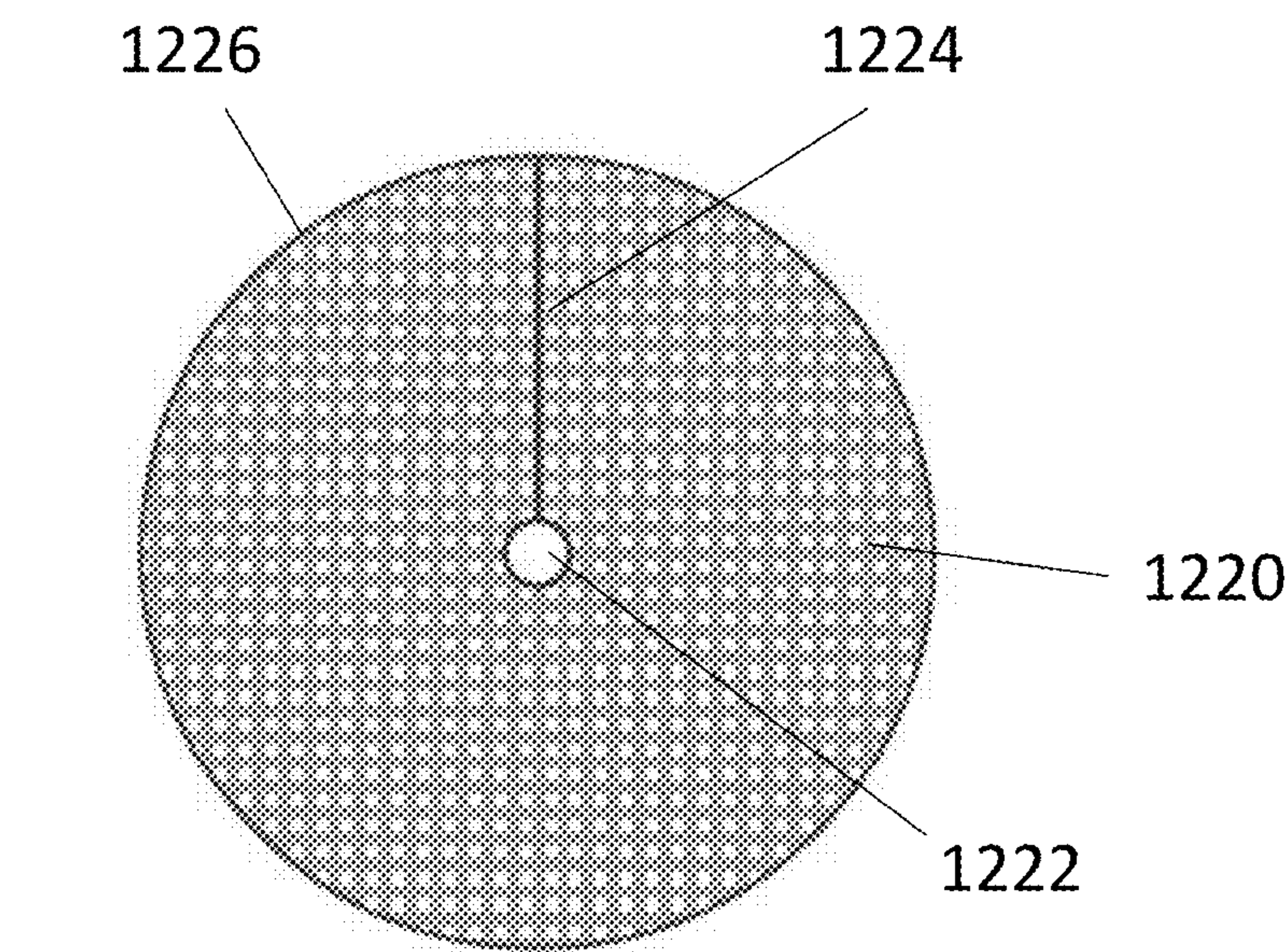


FIG. 27A

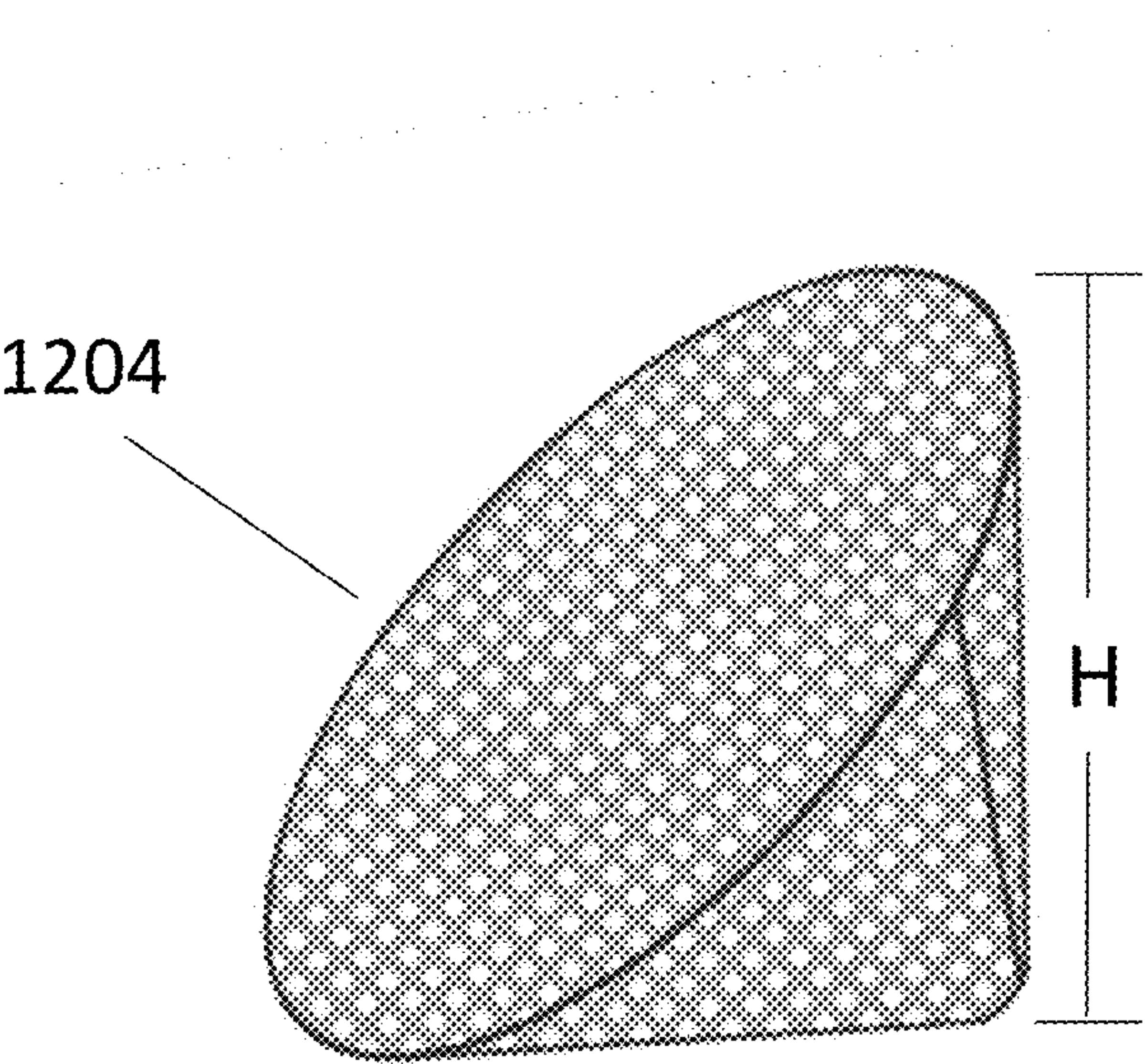


FIG. 27B

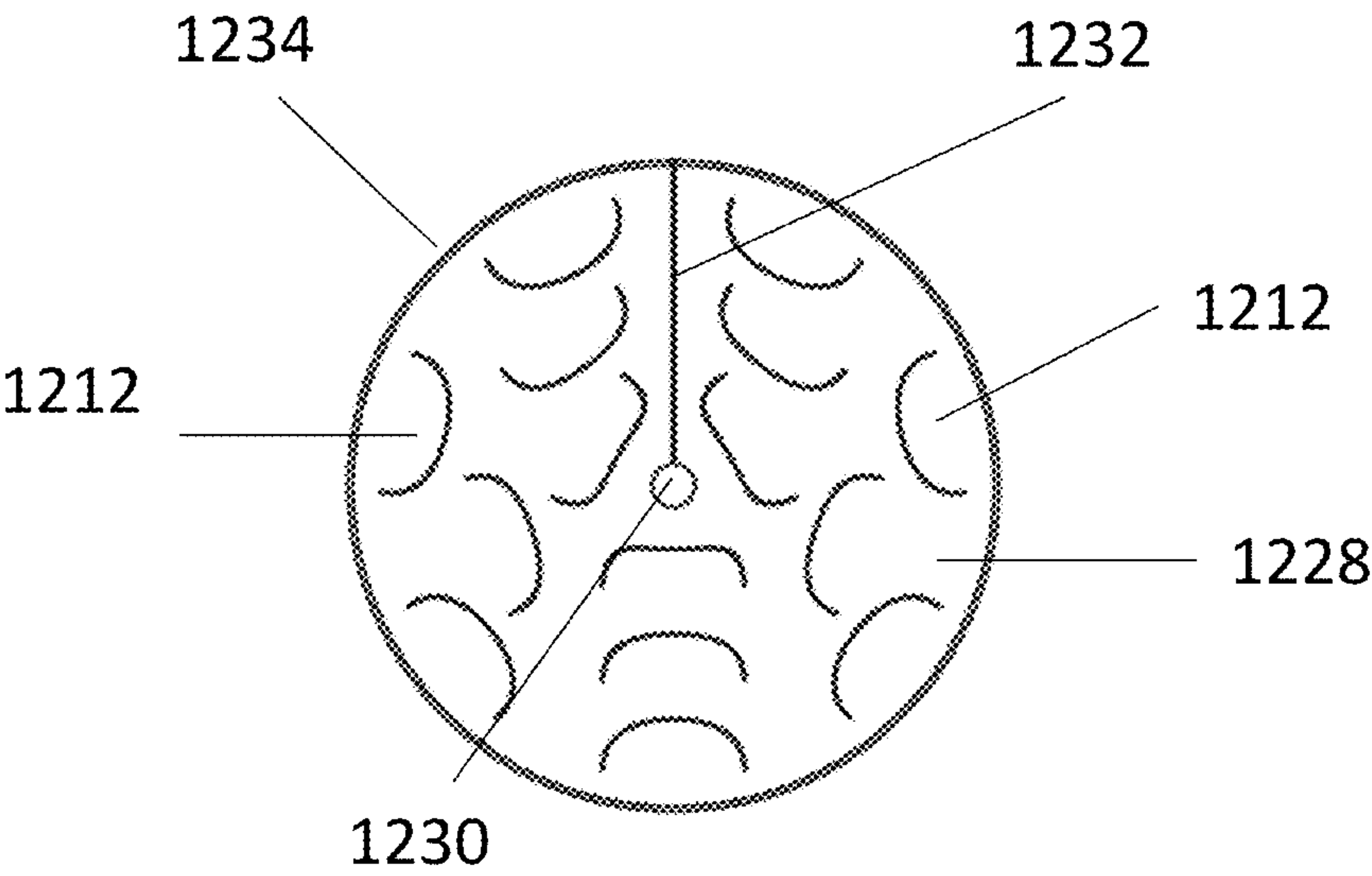


FIG. 28A

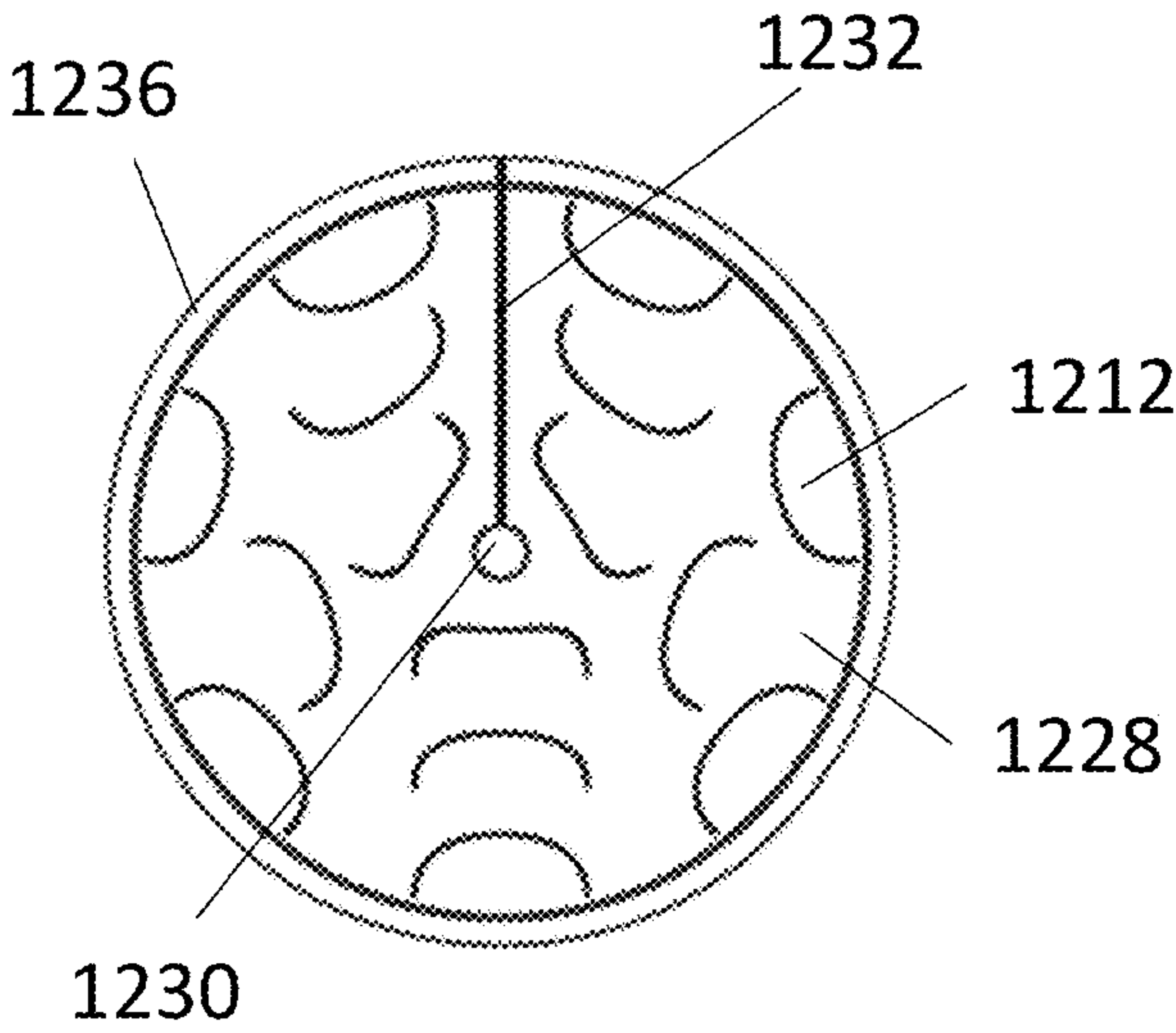


FIG. 28B

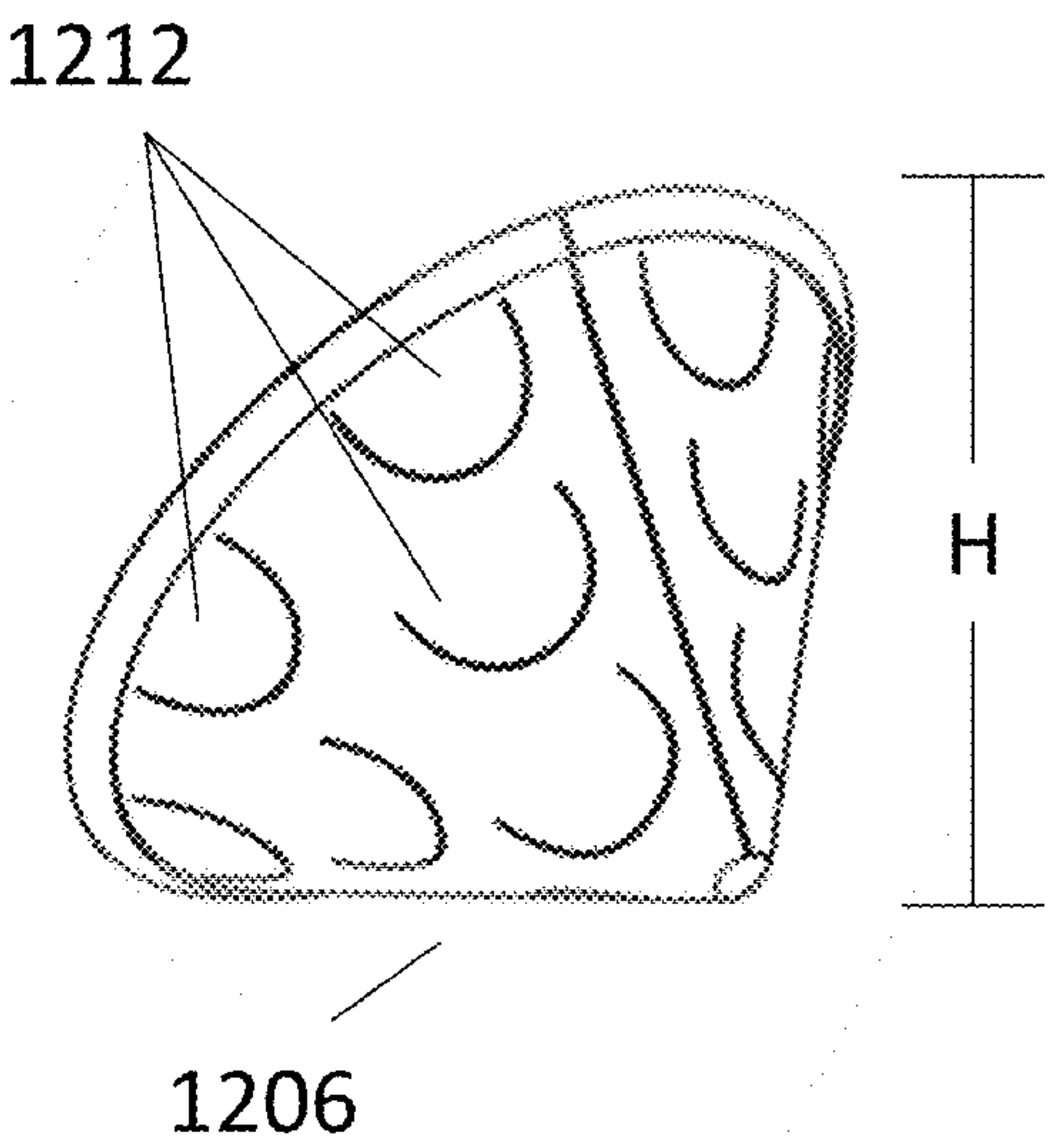


FIG. 28C

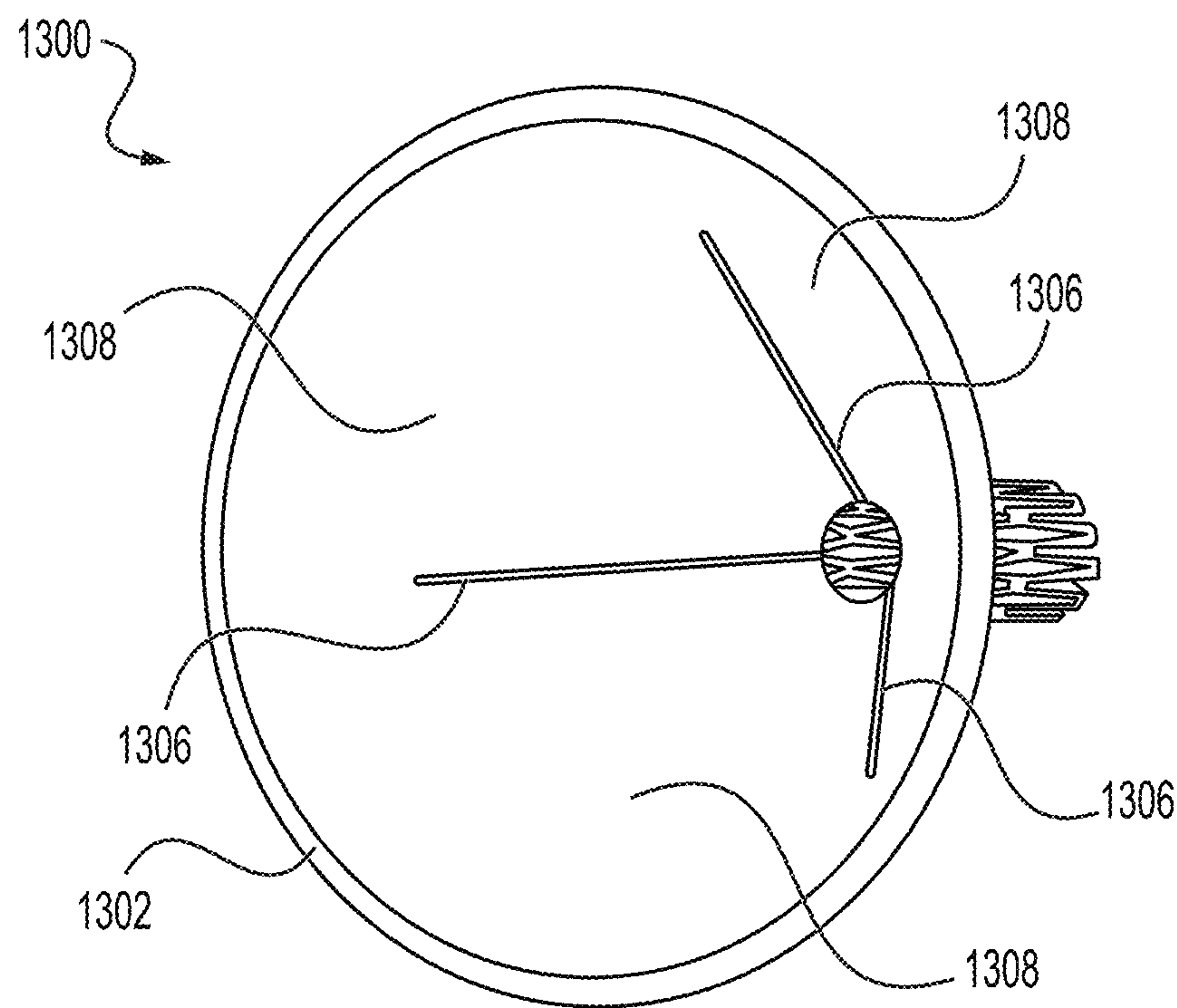


FIG. 29A

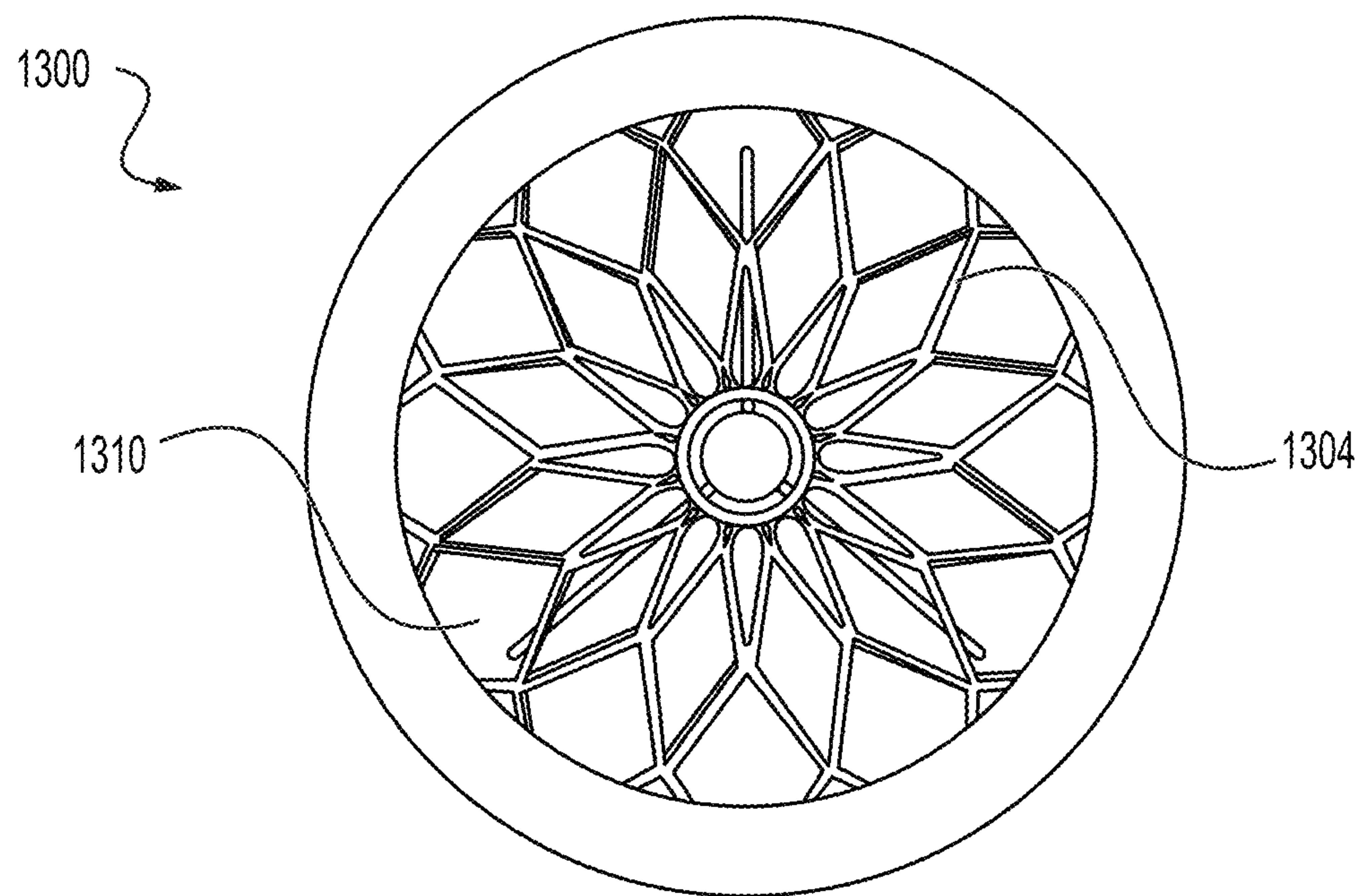


FIG. 29B

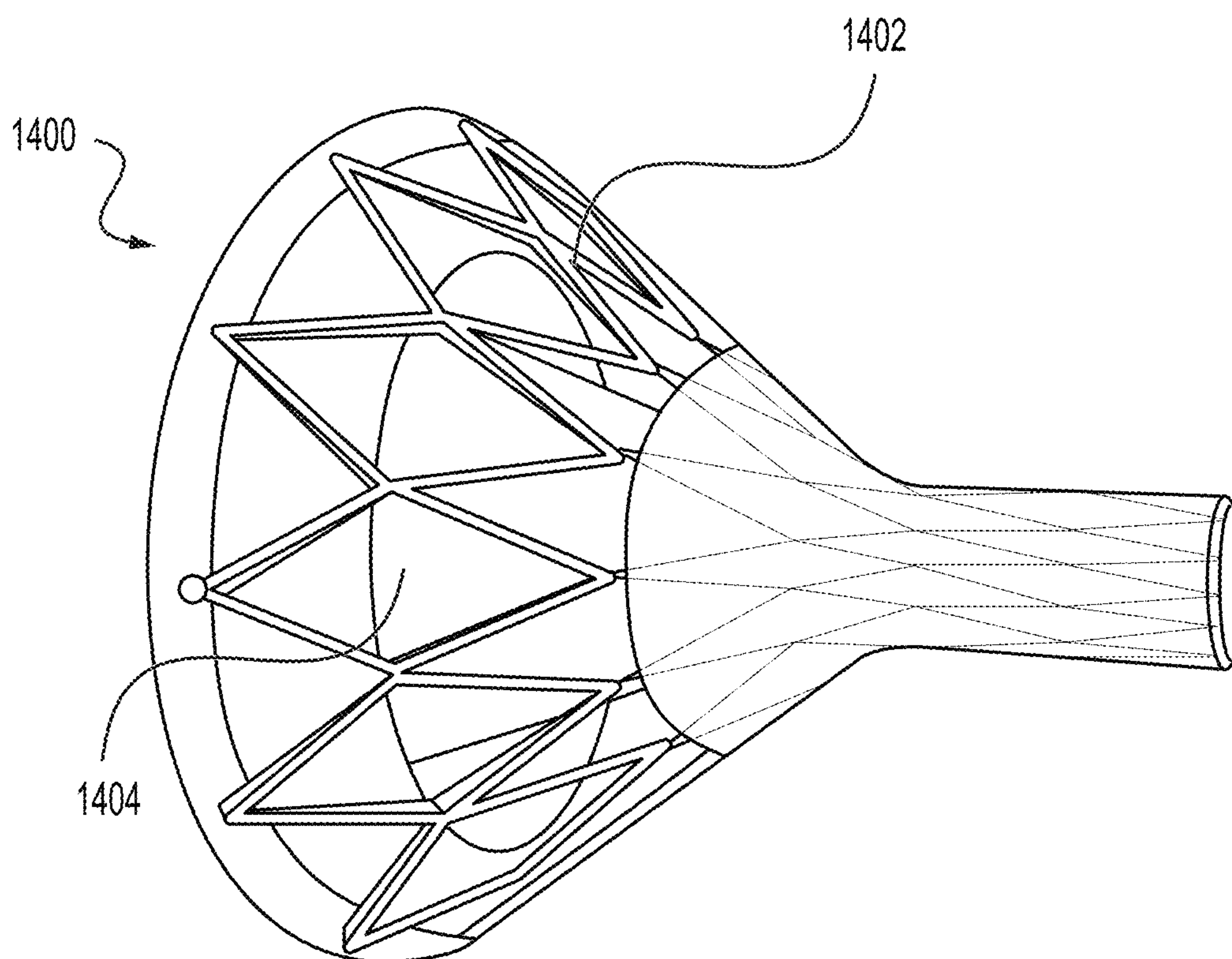


FIG. 30A

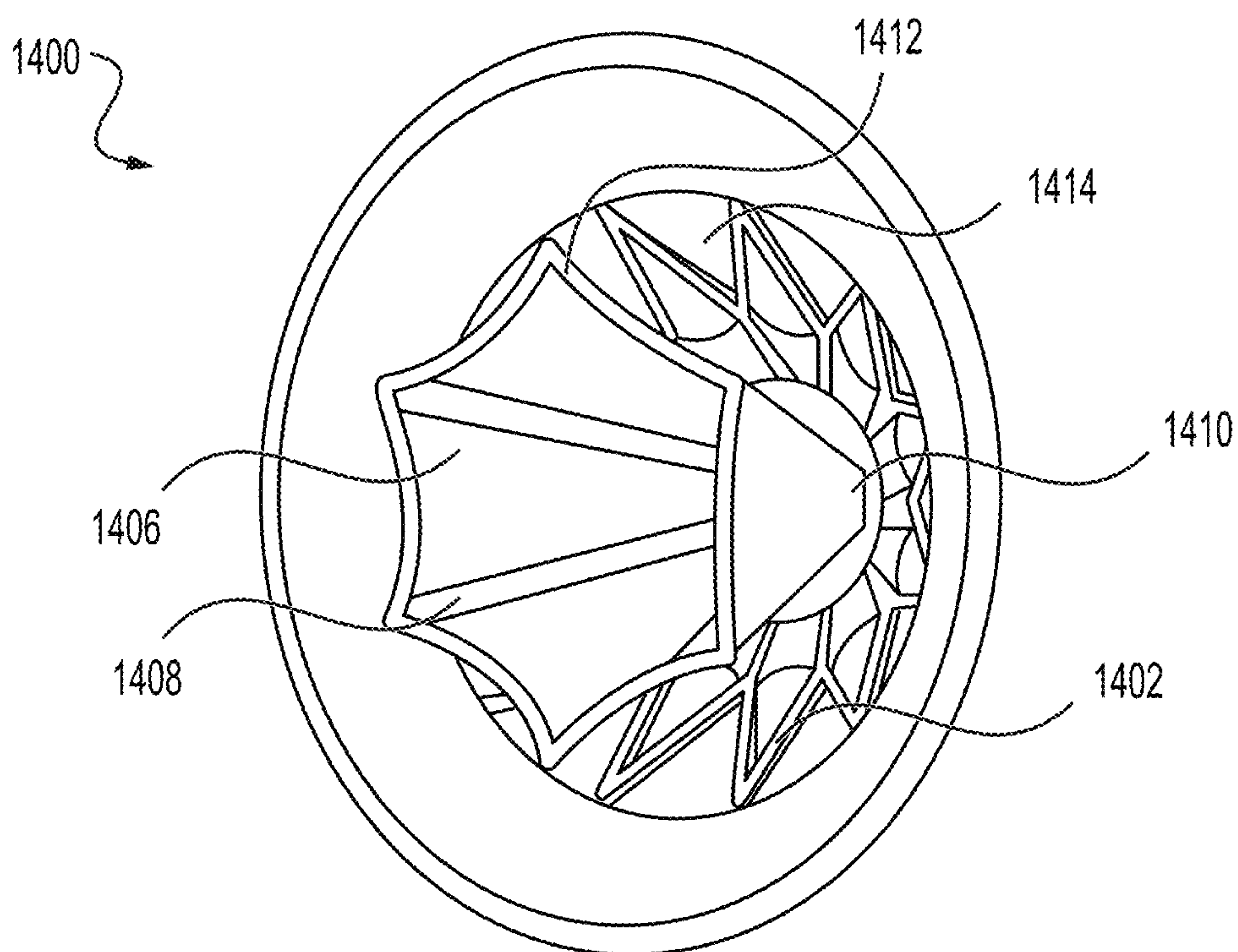


FIG. 30B

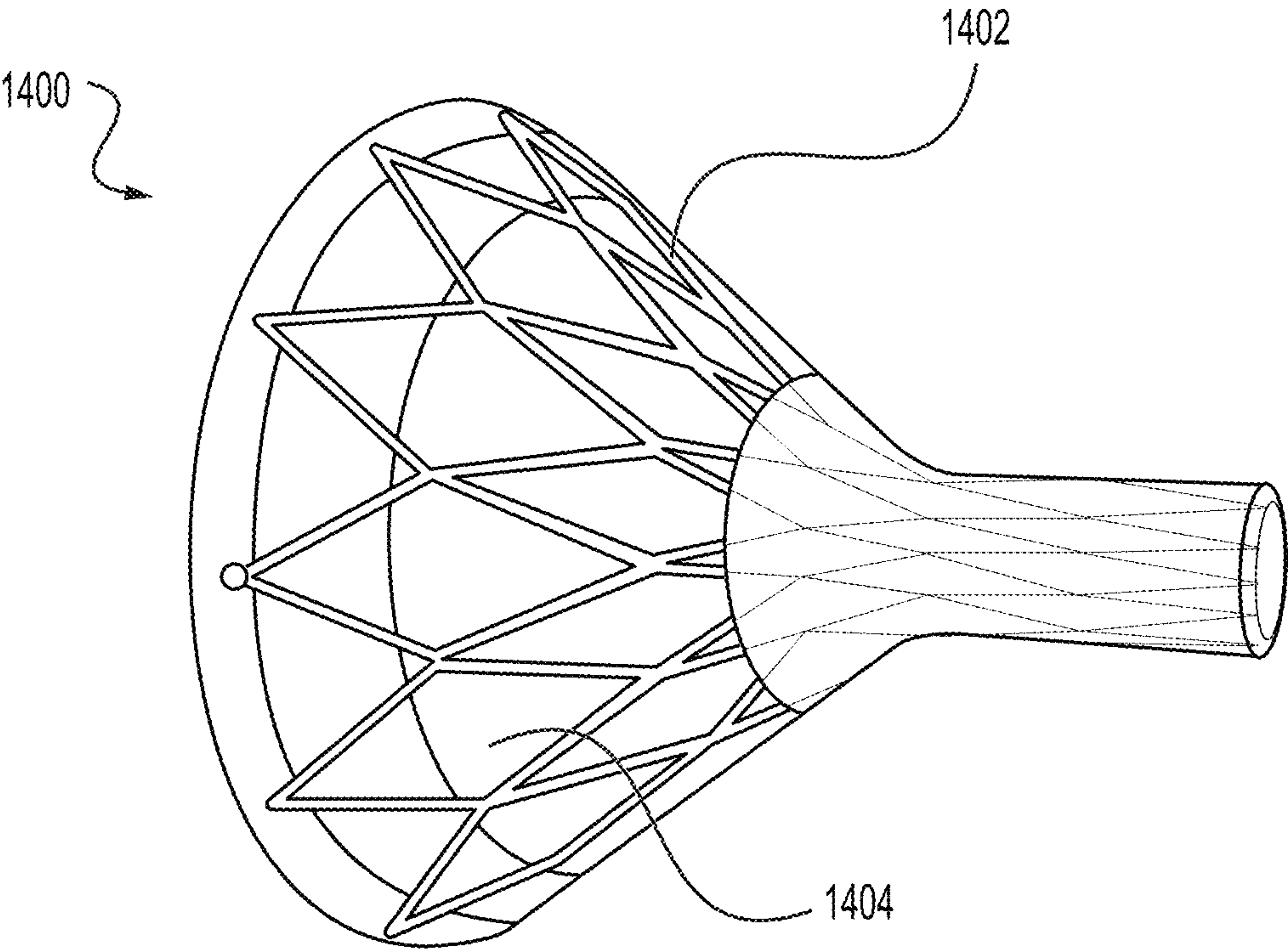


FIG. 30C

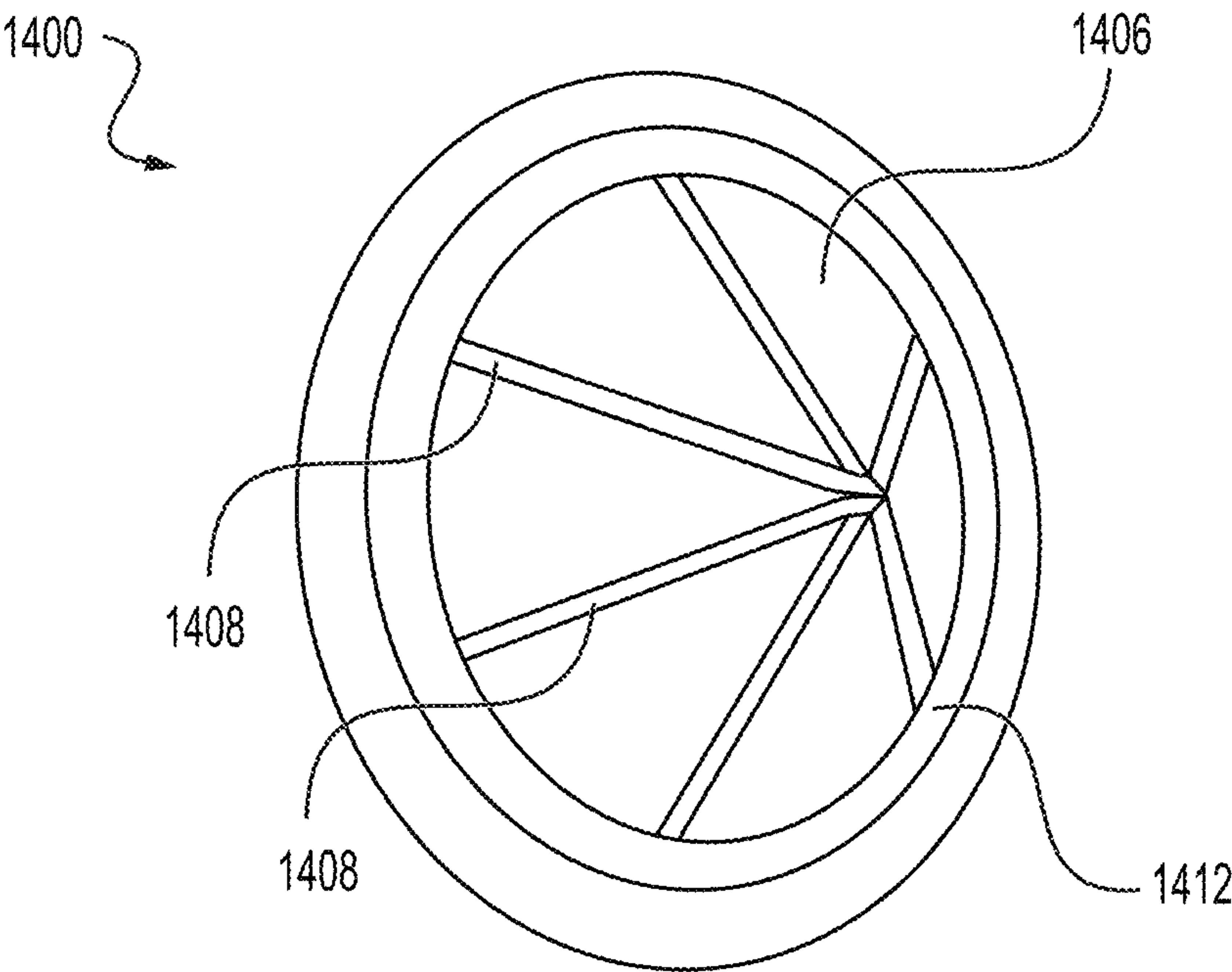


FIG. 30D

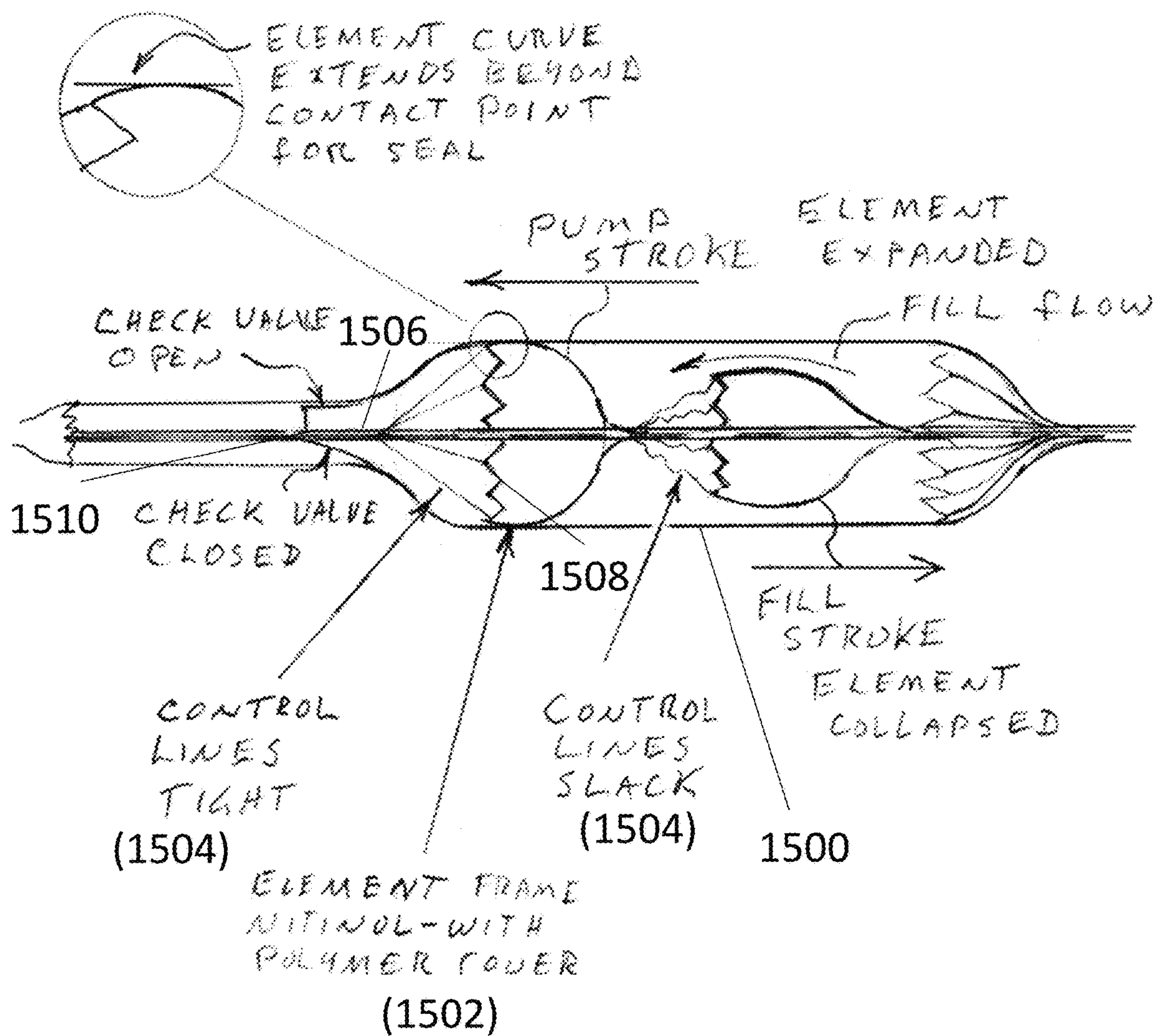


FIG. 31

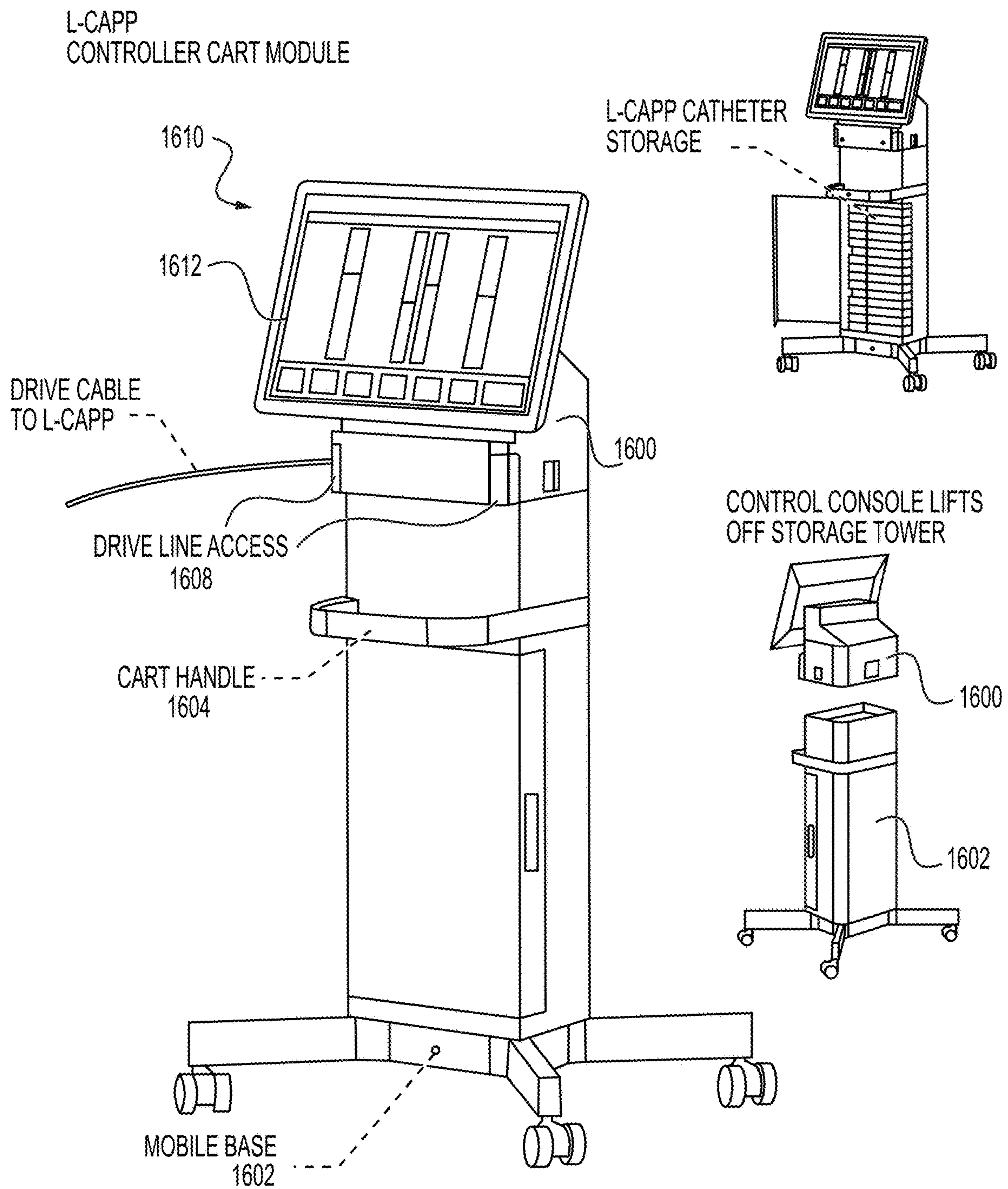
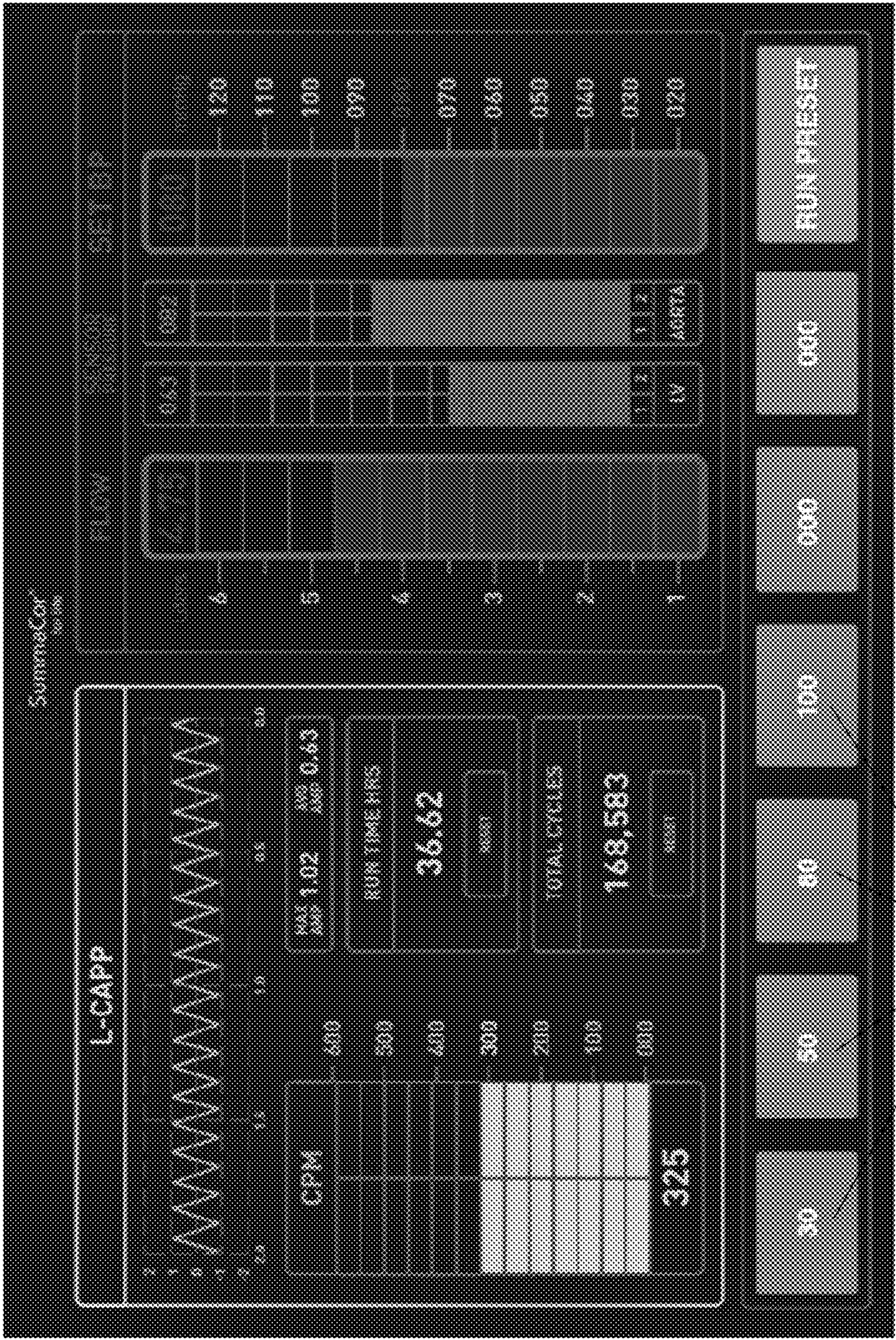


FIG. 32A

1612



1614

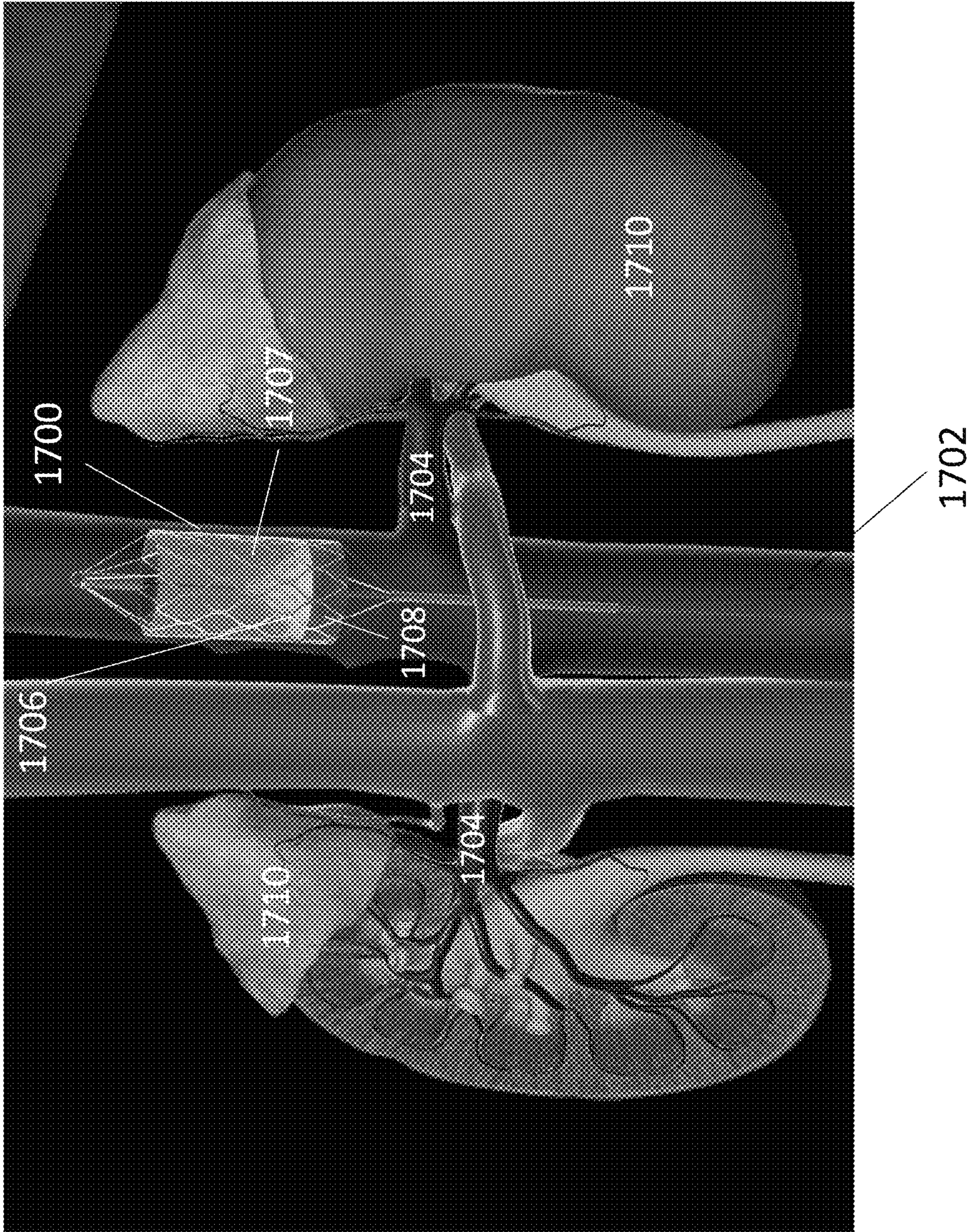


FIG. 33

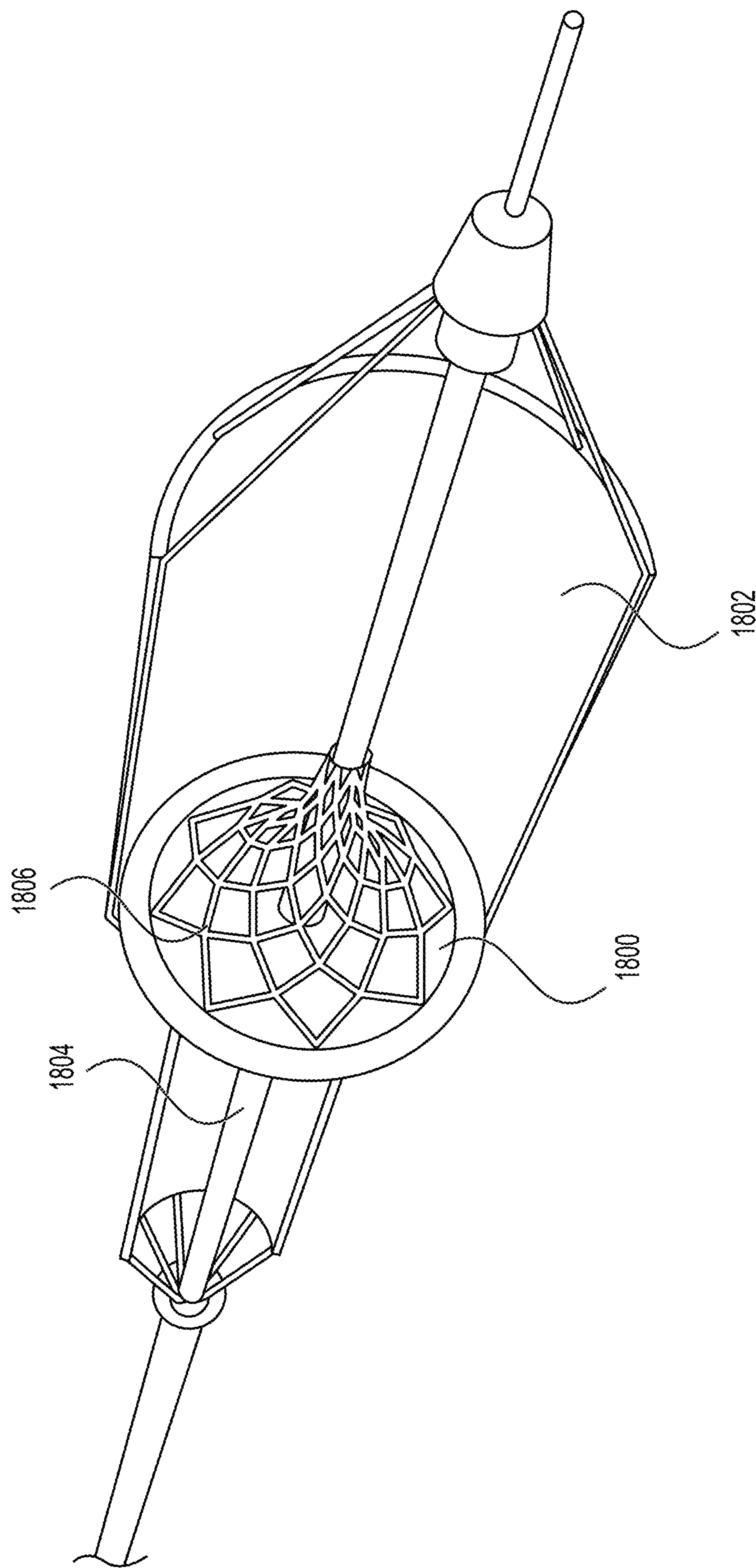


FIG. 34

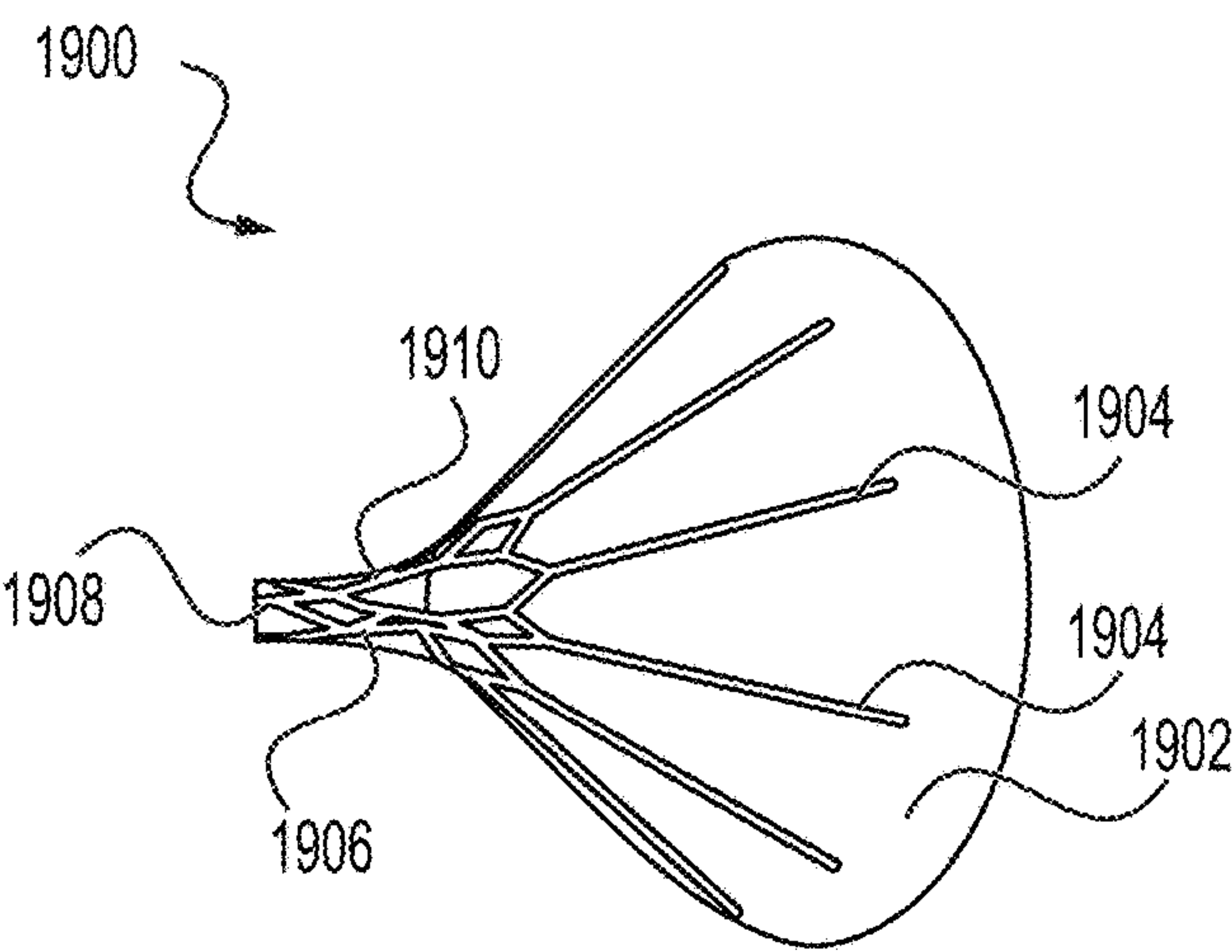


FIG. 35A

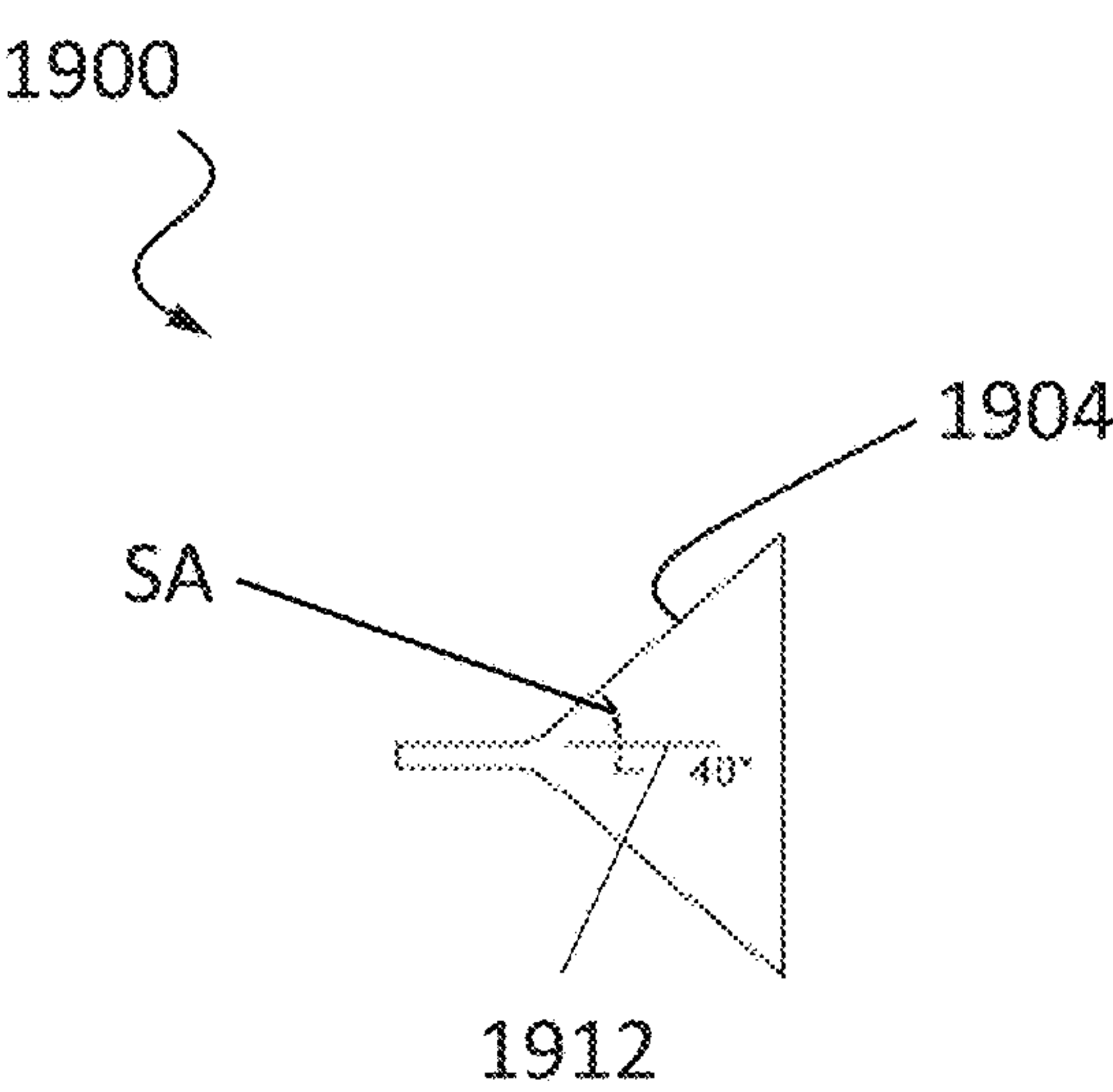


FIG. 35B

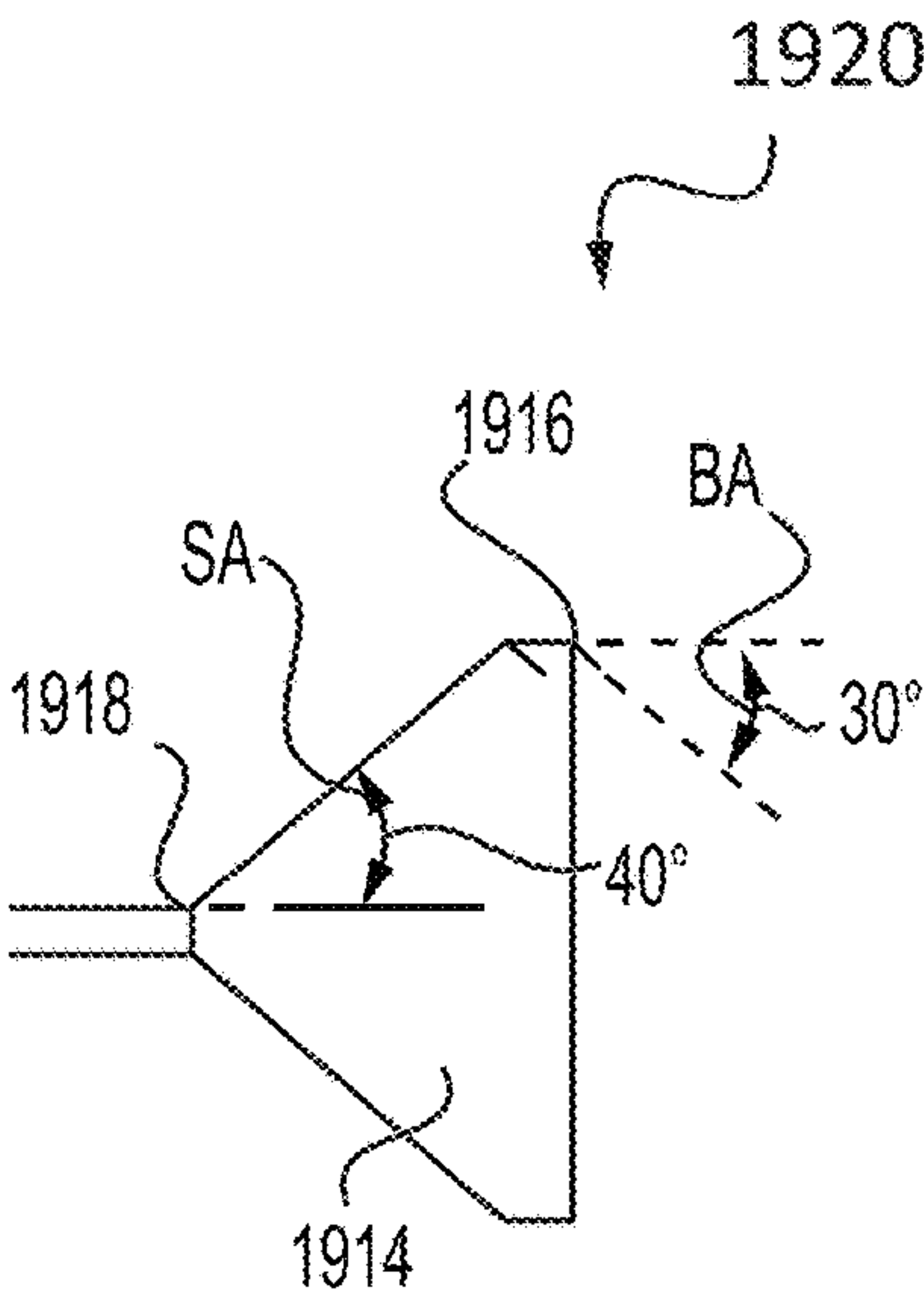


FIG. 35C

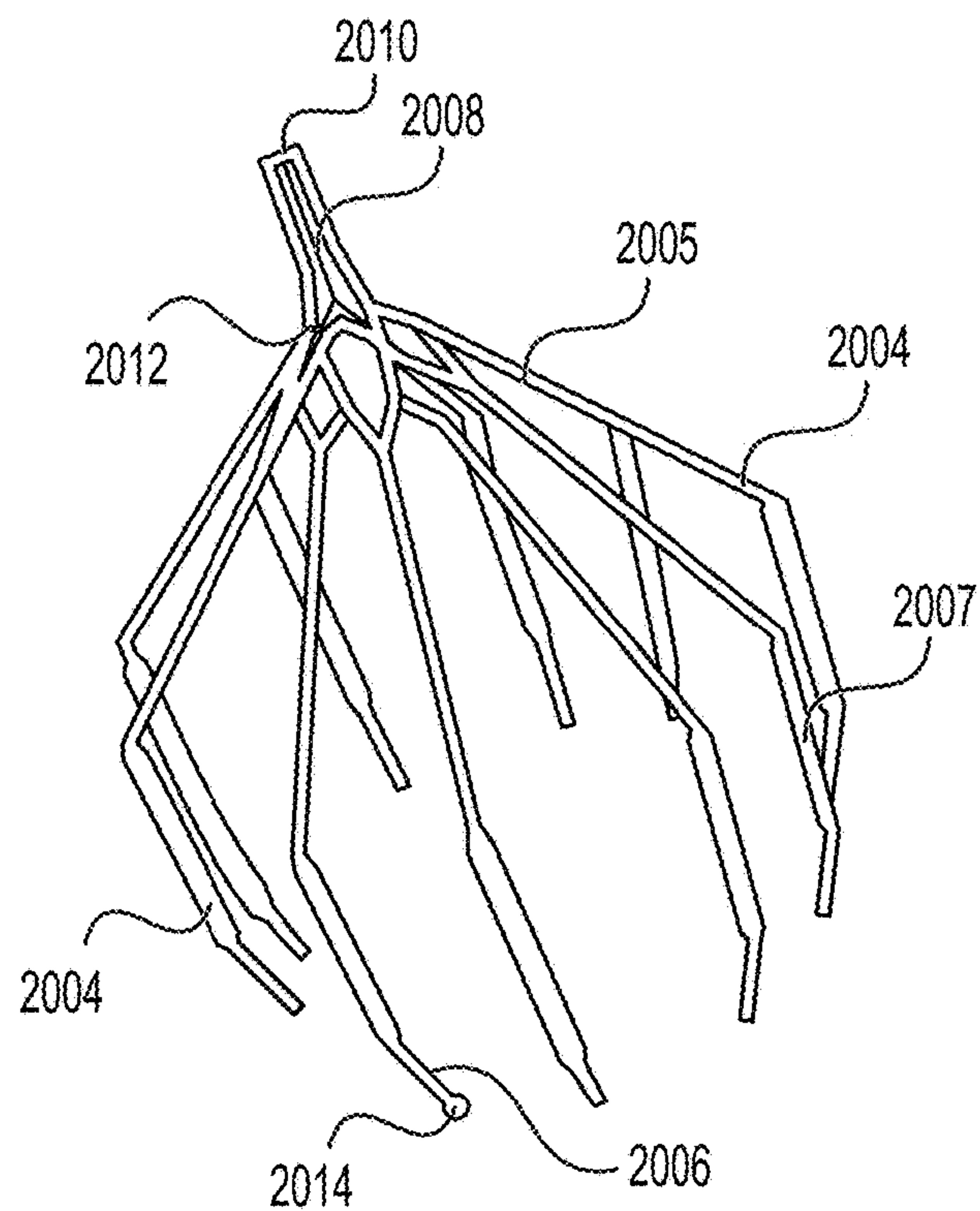


FIG. 36A

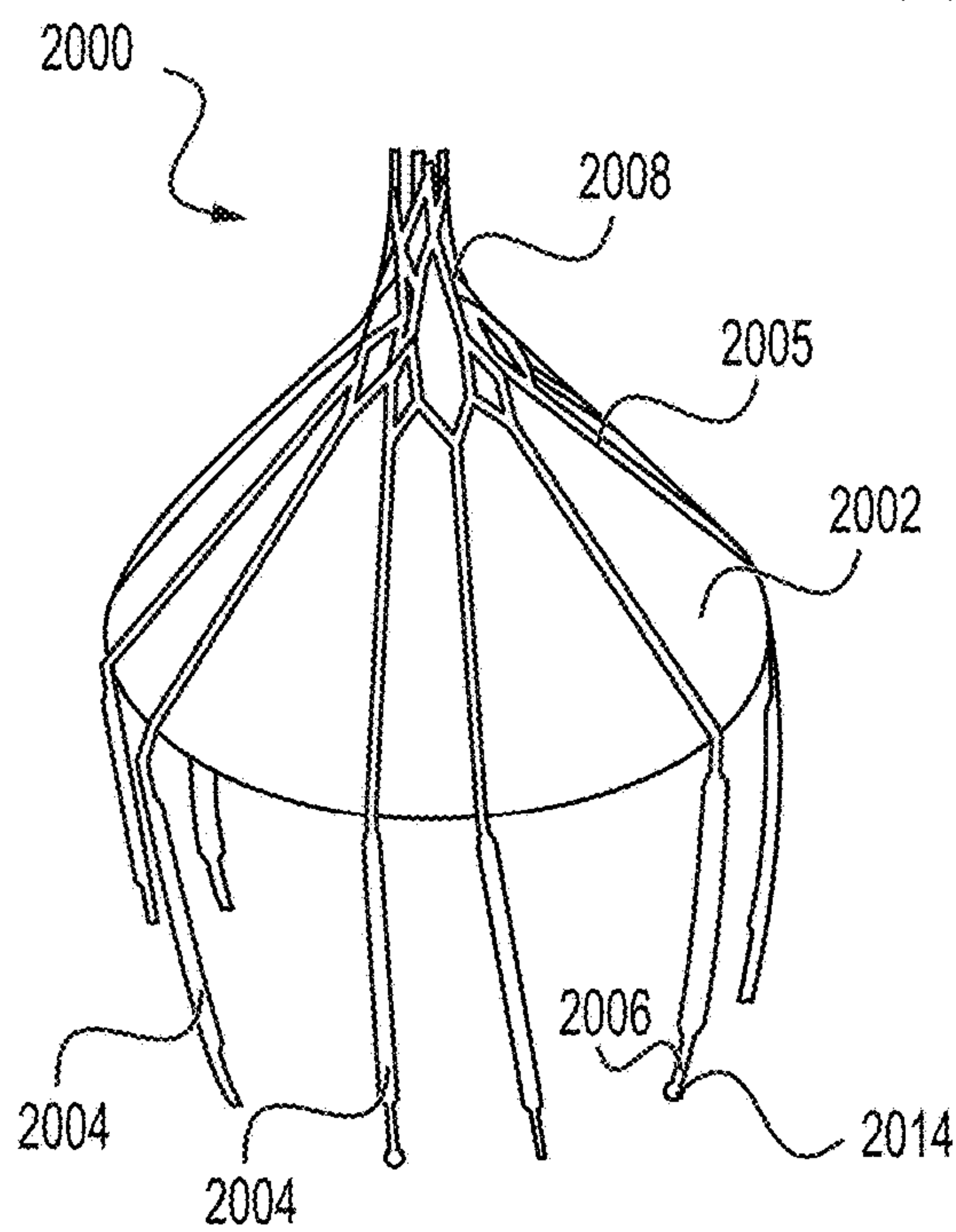


FIG. 36B

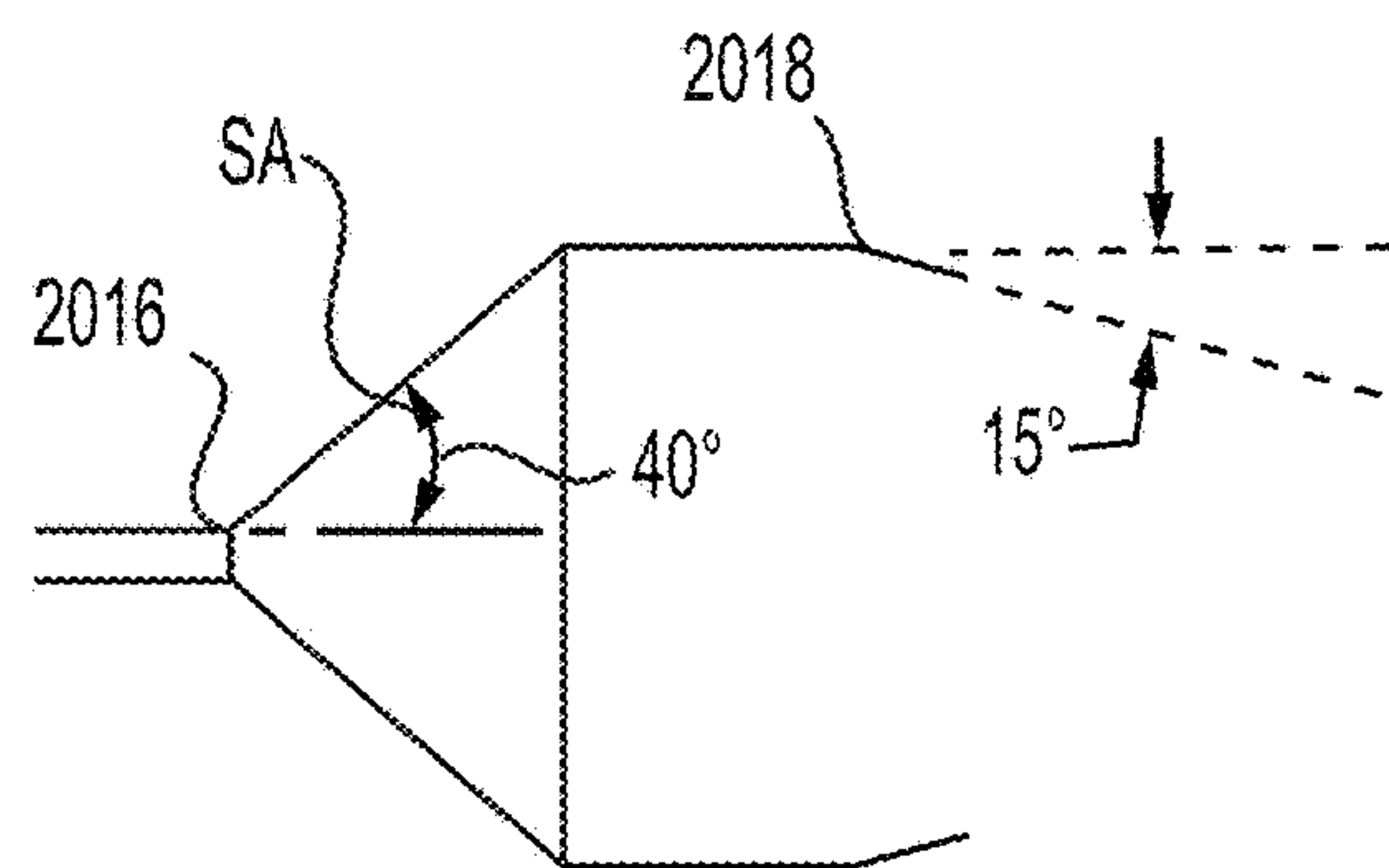


FIG. 36C

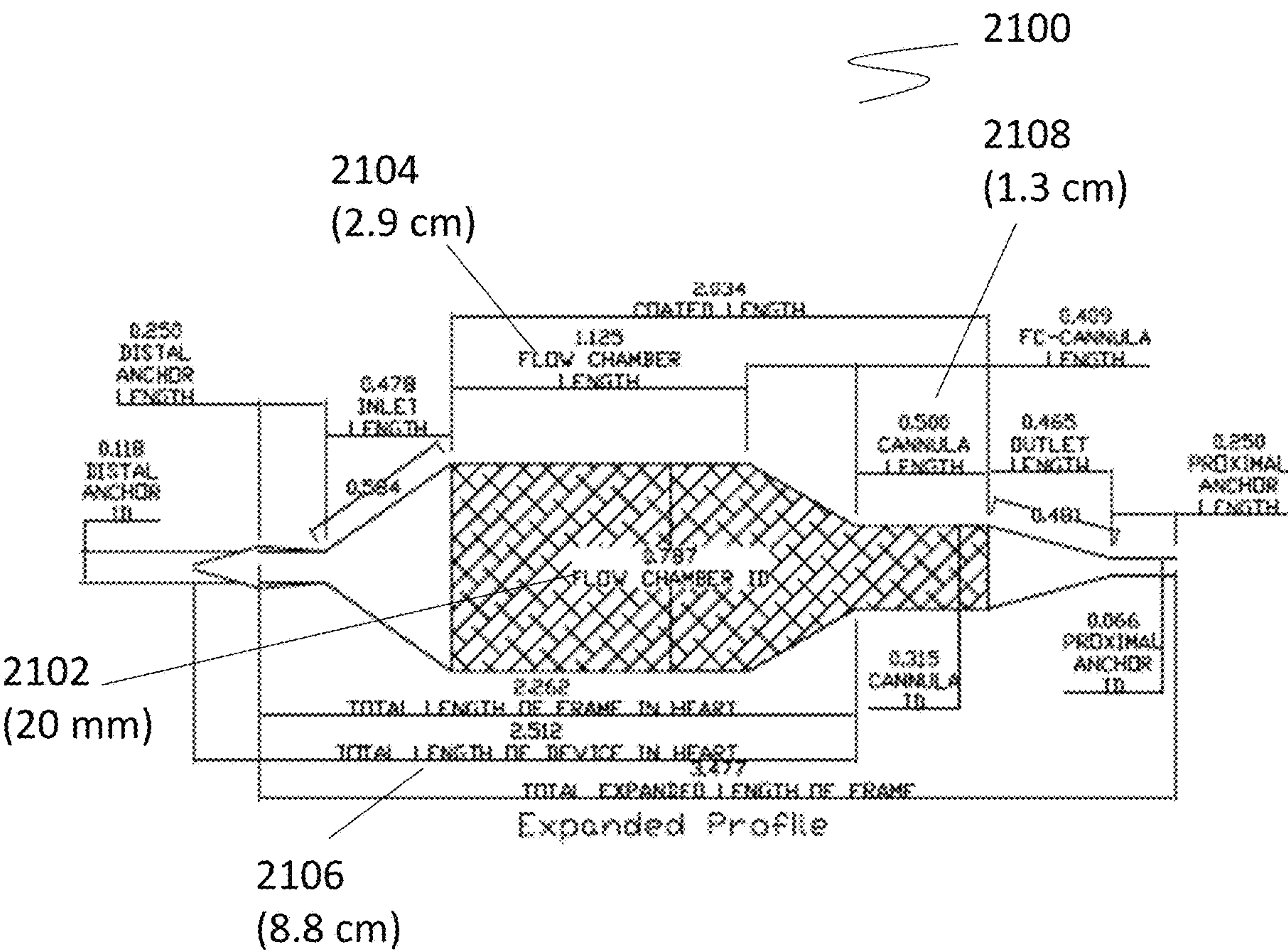


FIG. 37

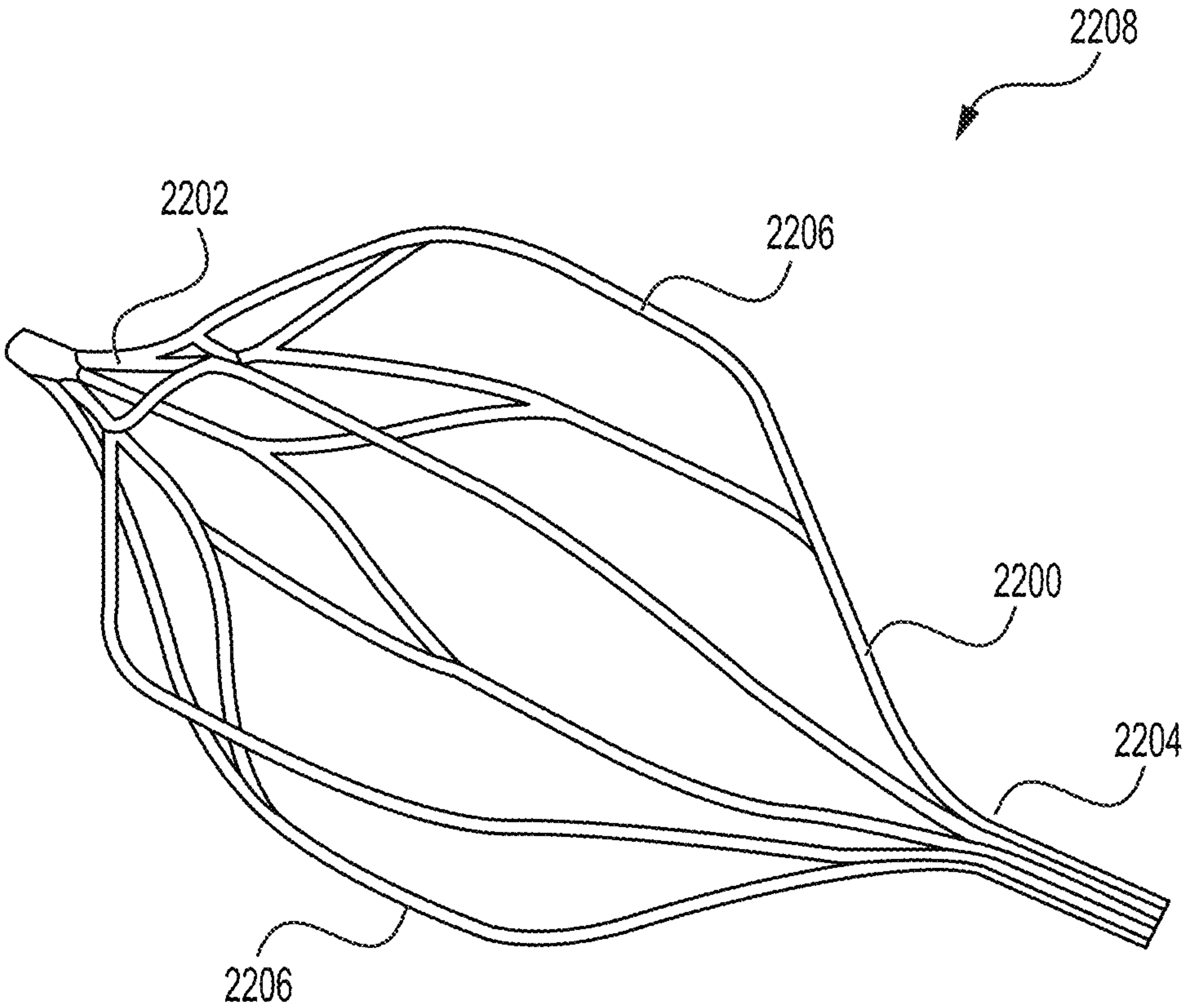


FIG. 38

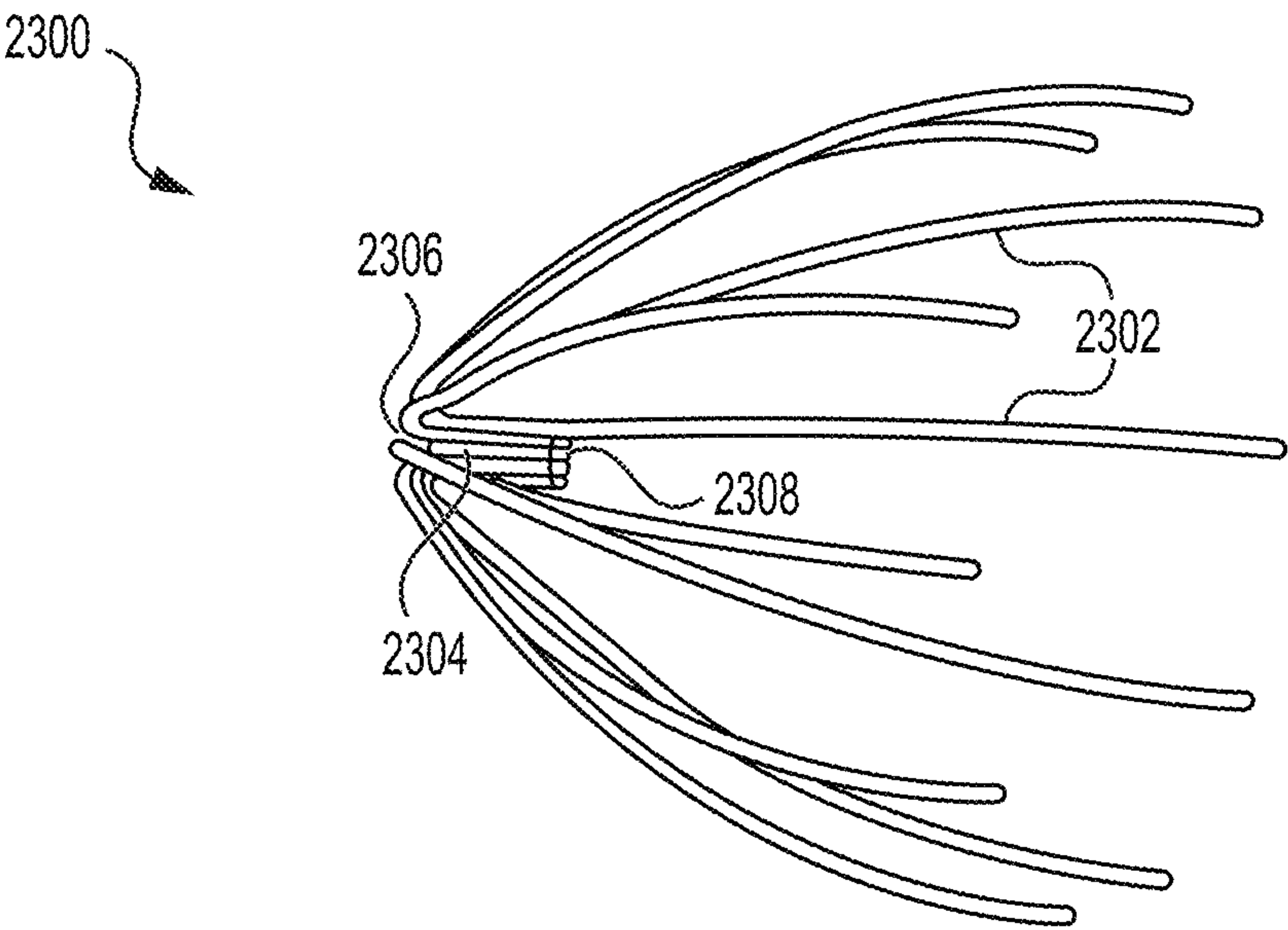


FIG. 39A

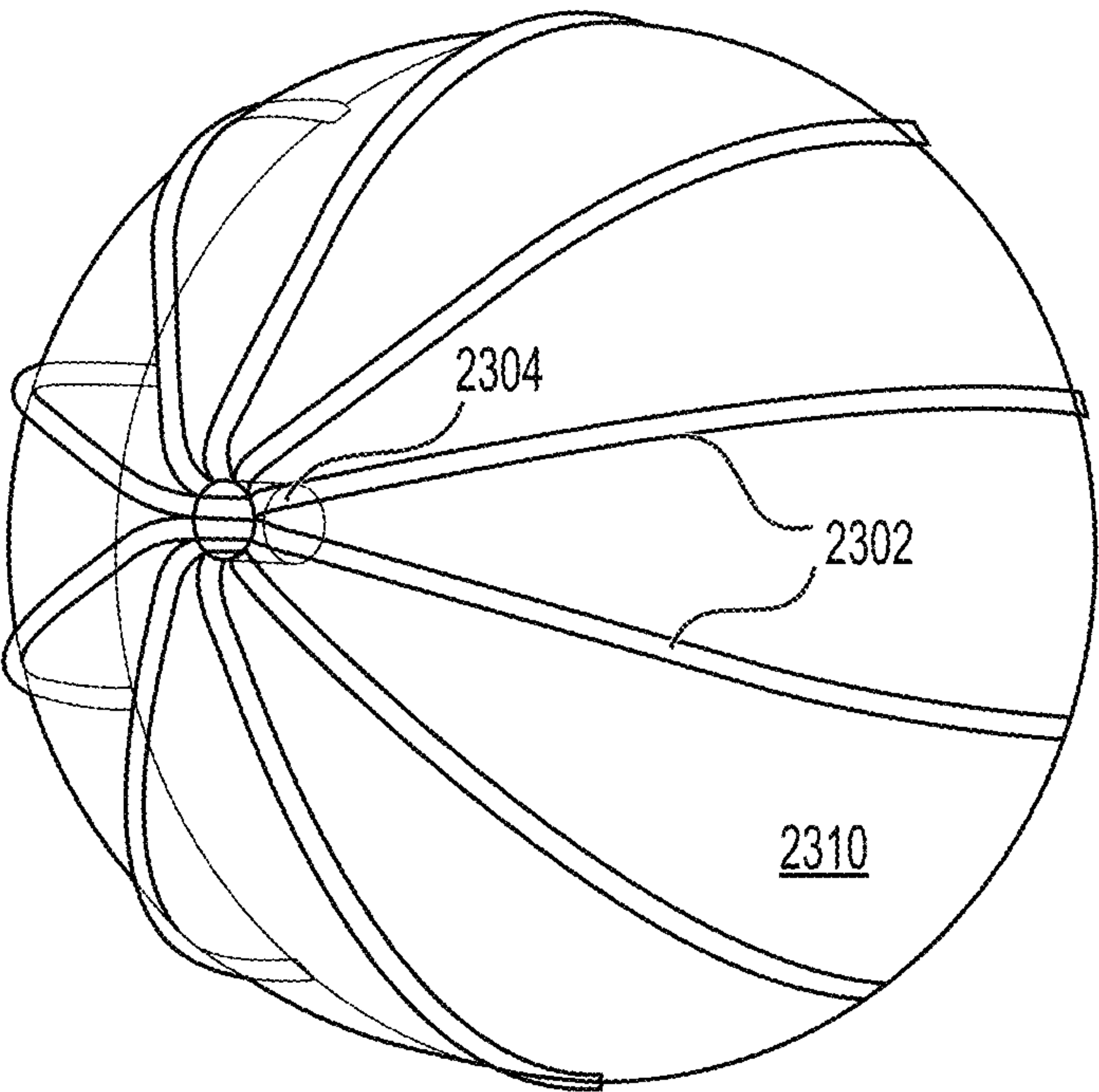


FIG. 39B

2300

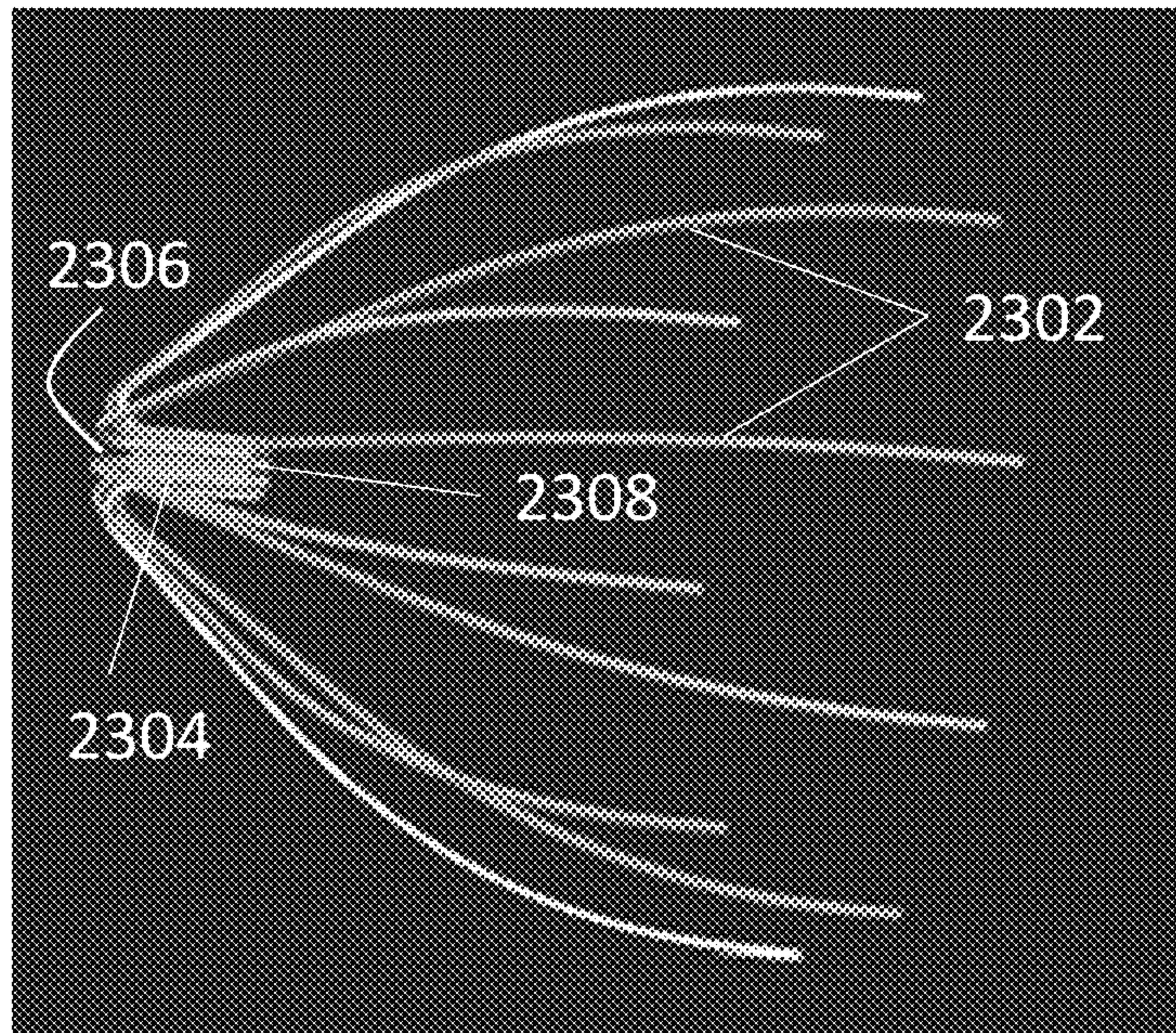


FIG. 39A

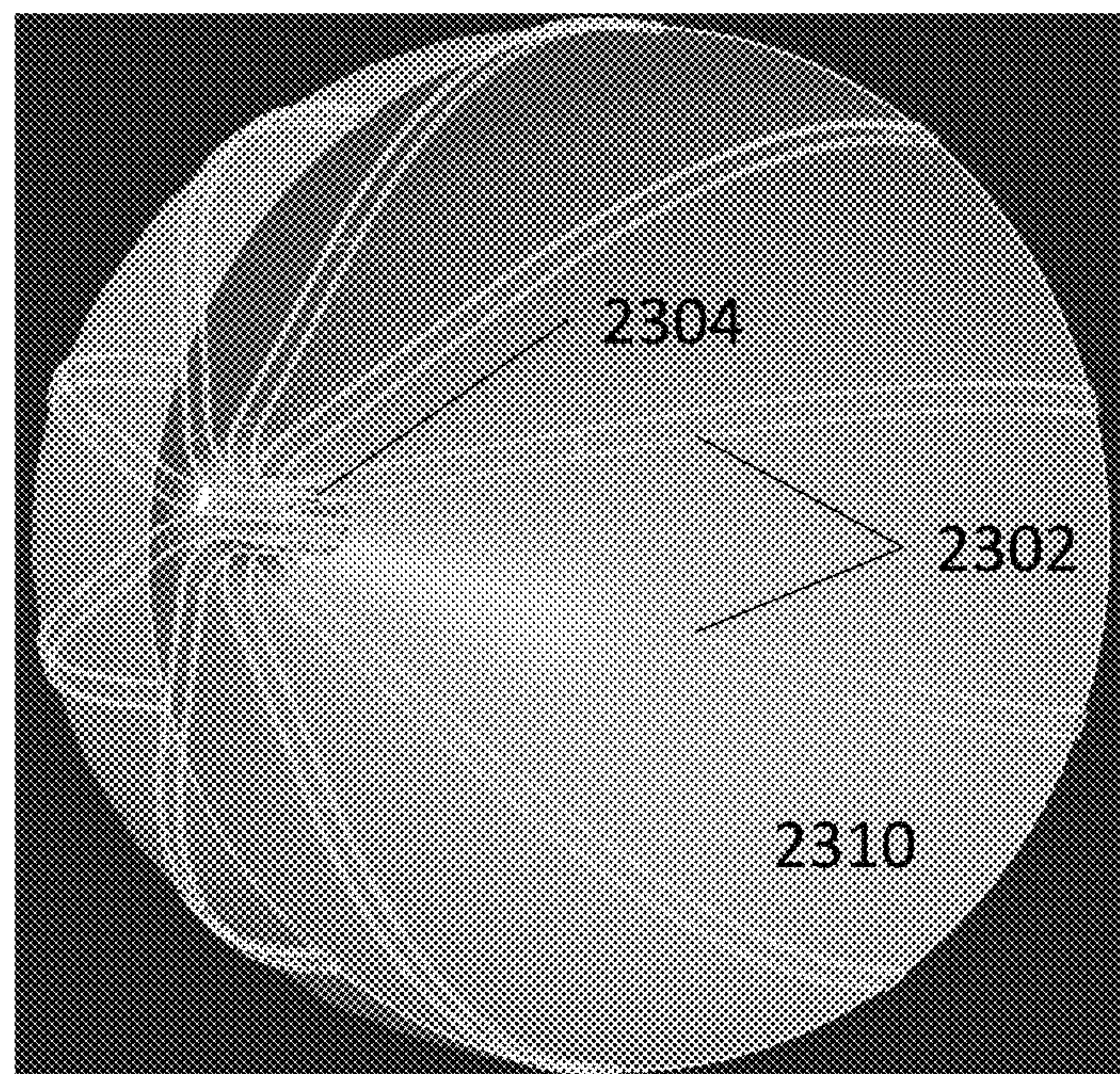


FIG. 39B

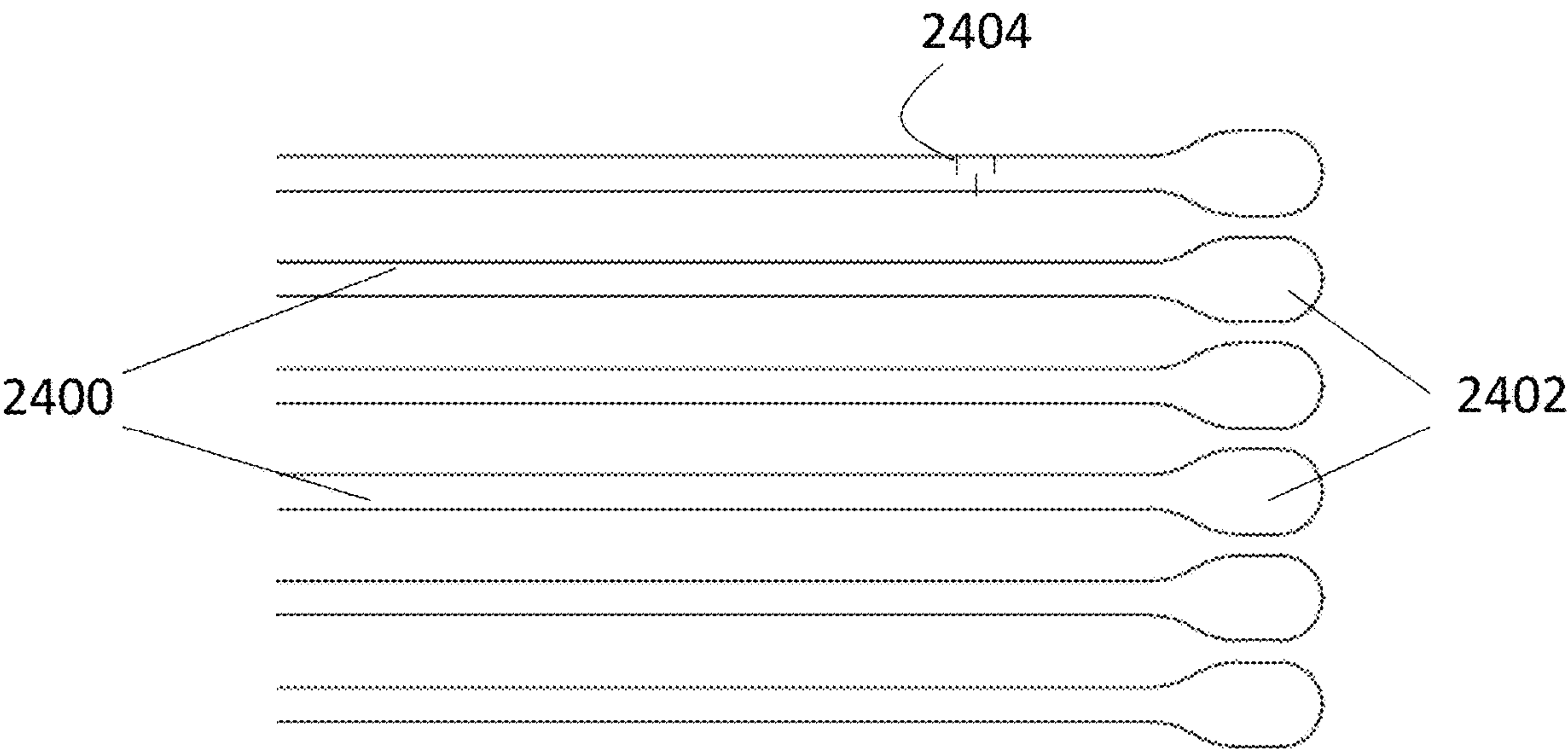


FIG. 40

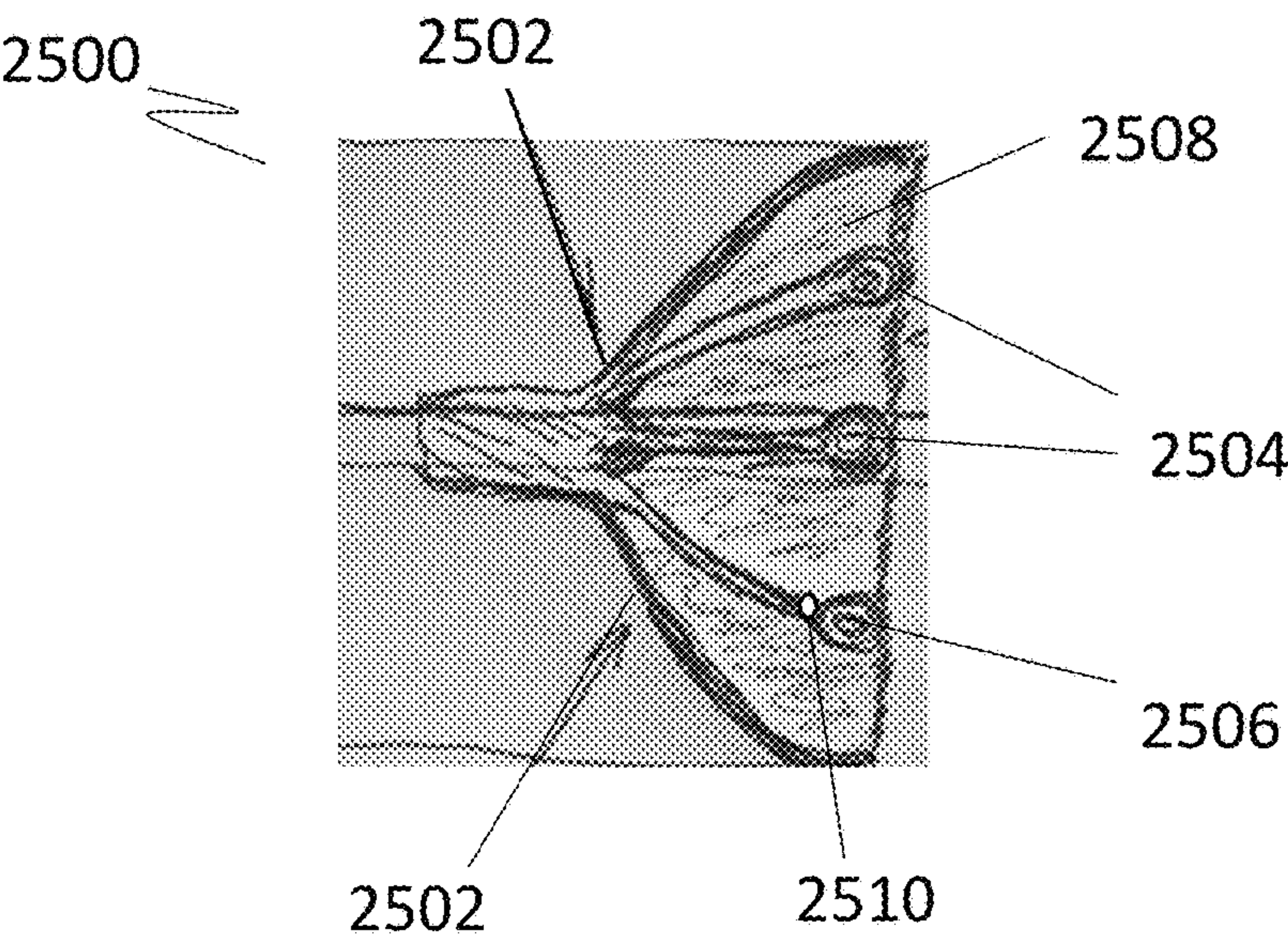


FIG. 41

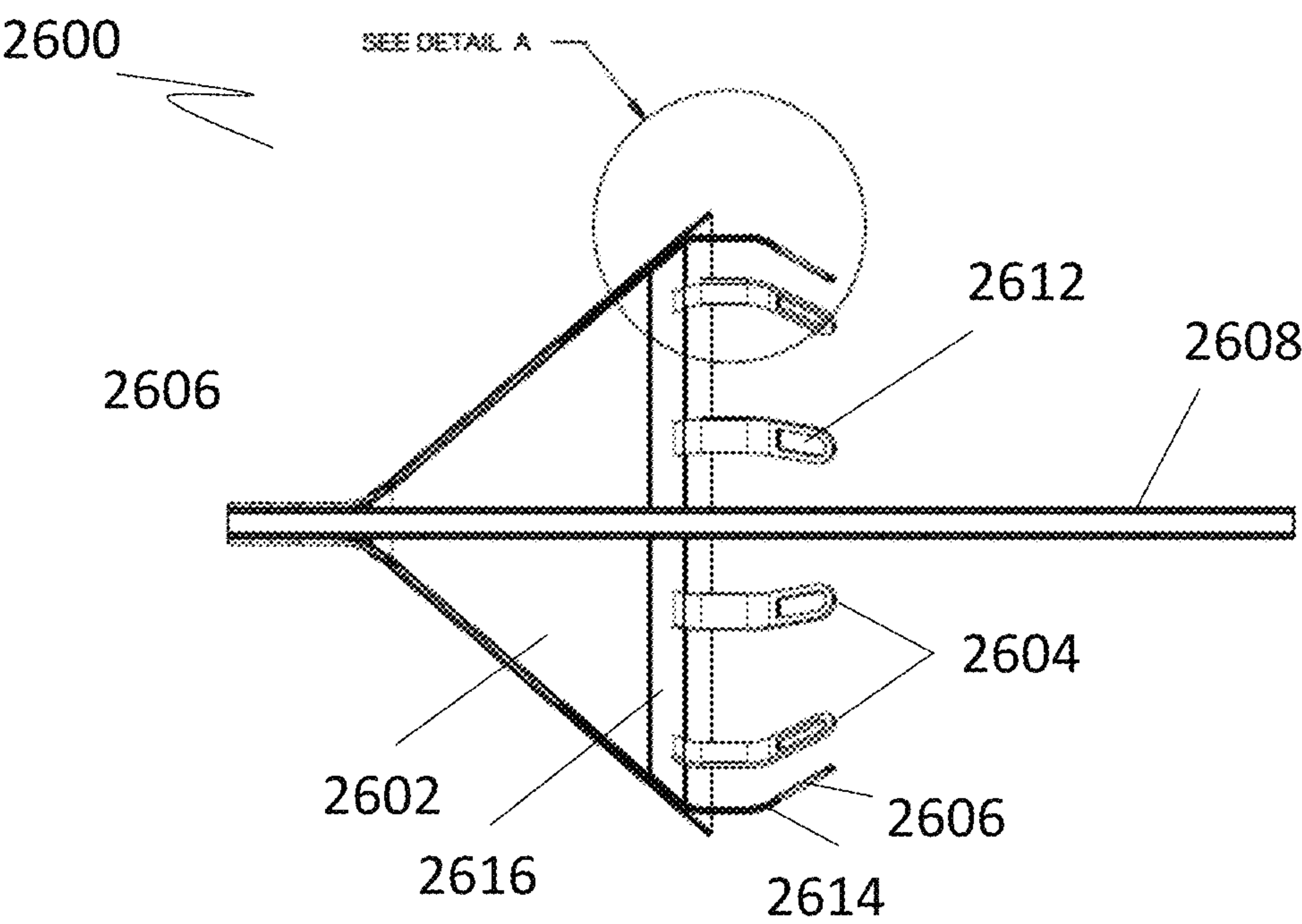


FIG. 42A

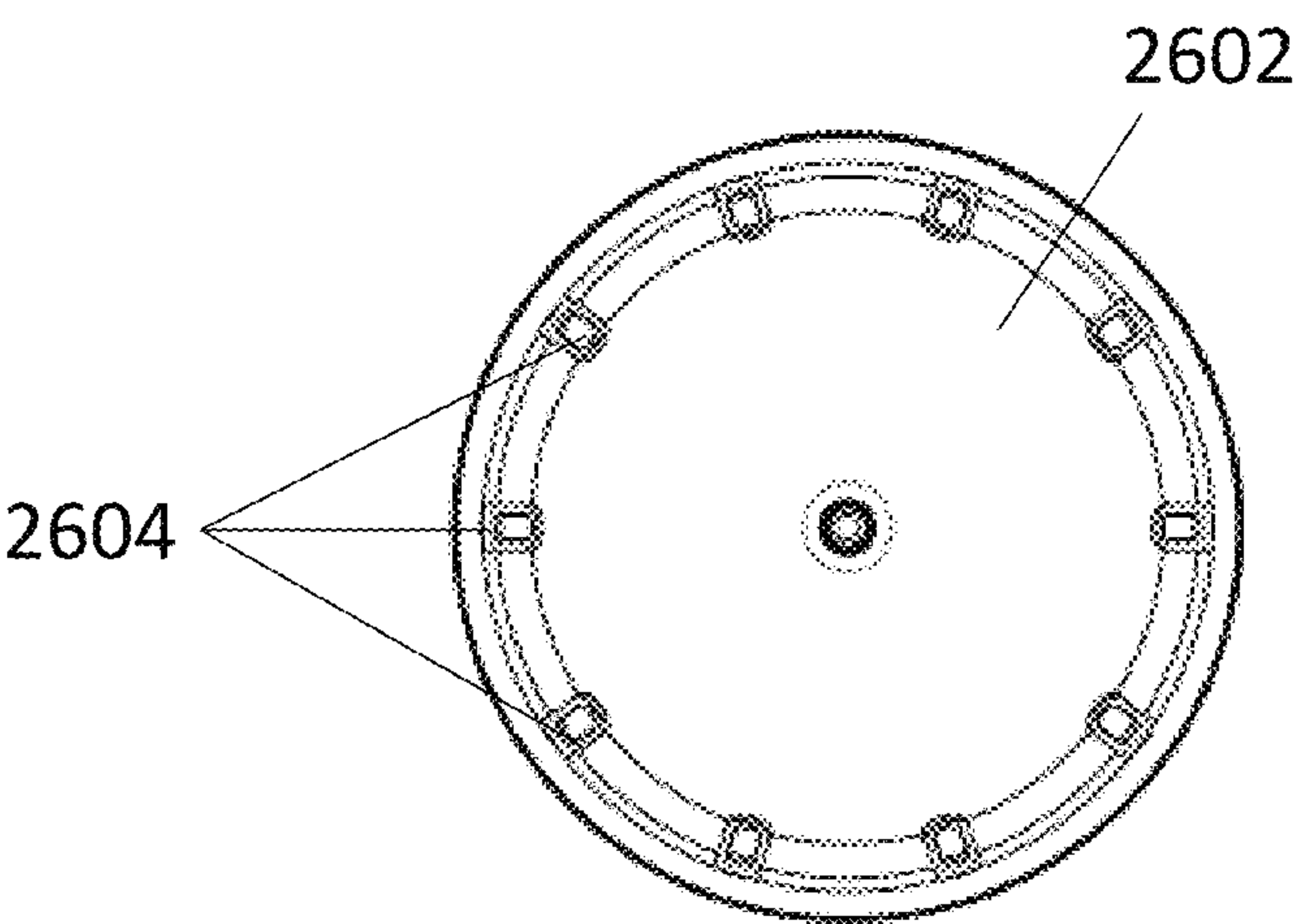


FIG. 42B

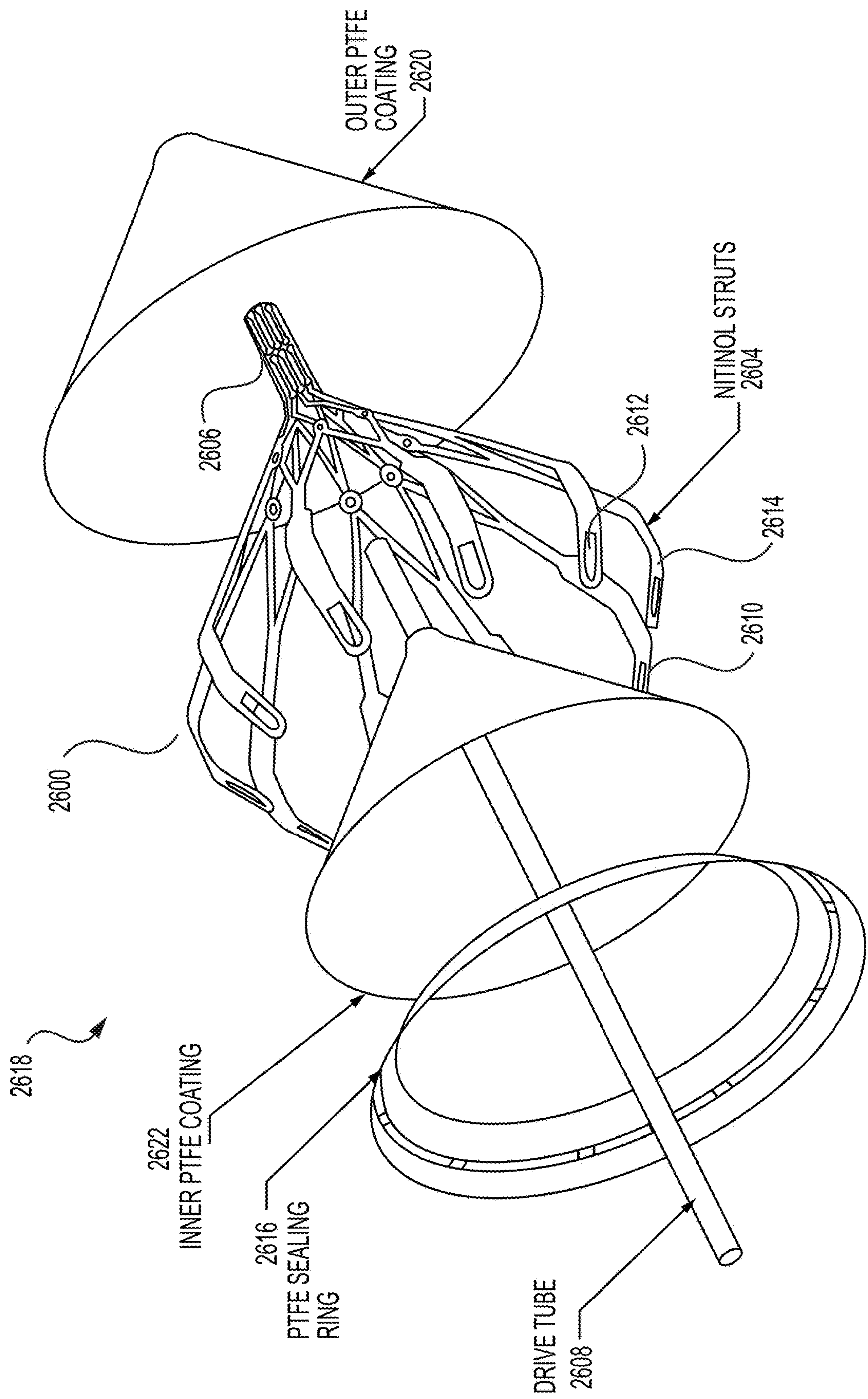


FIG. 42C

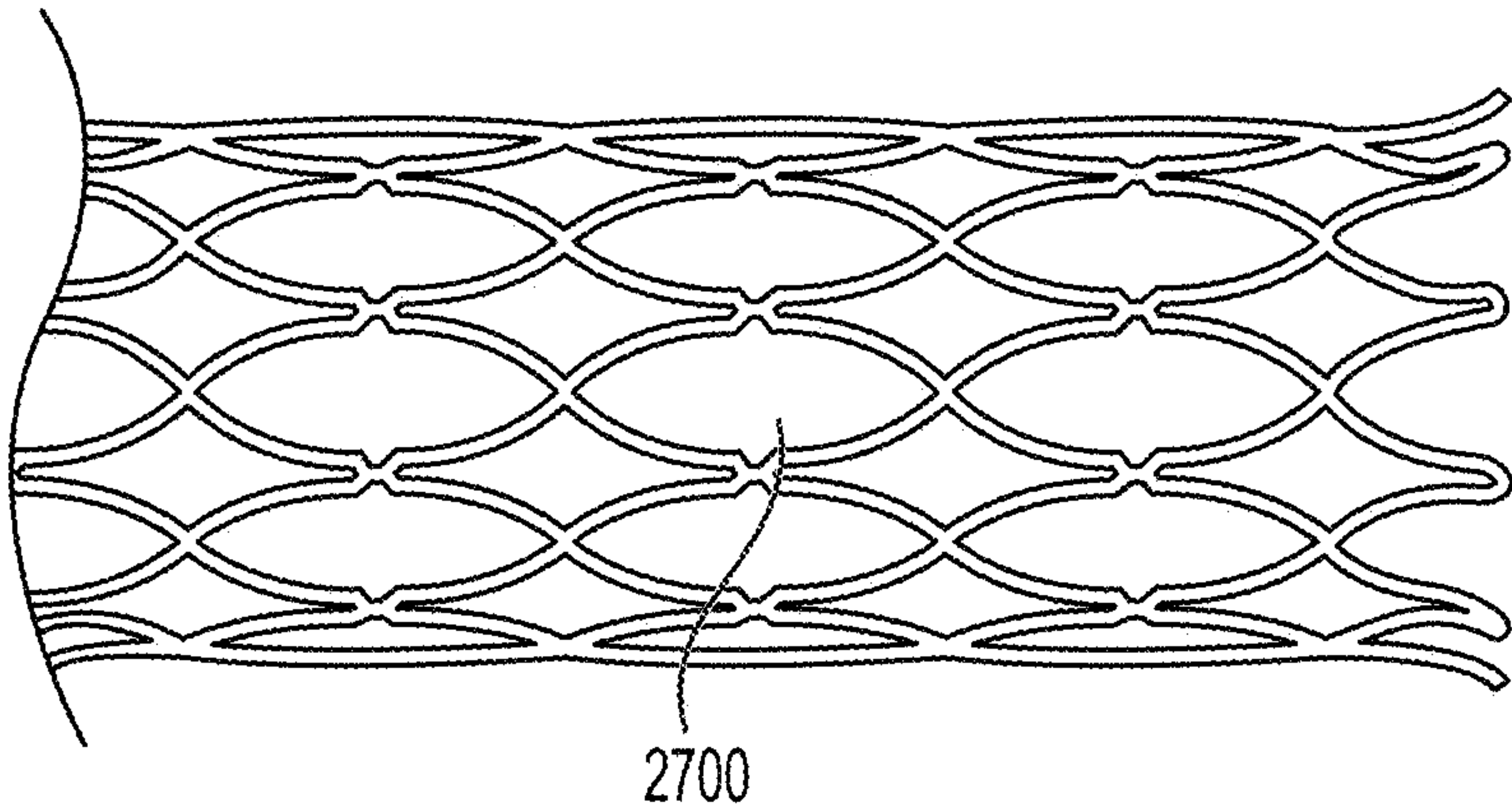


FIG. 43

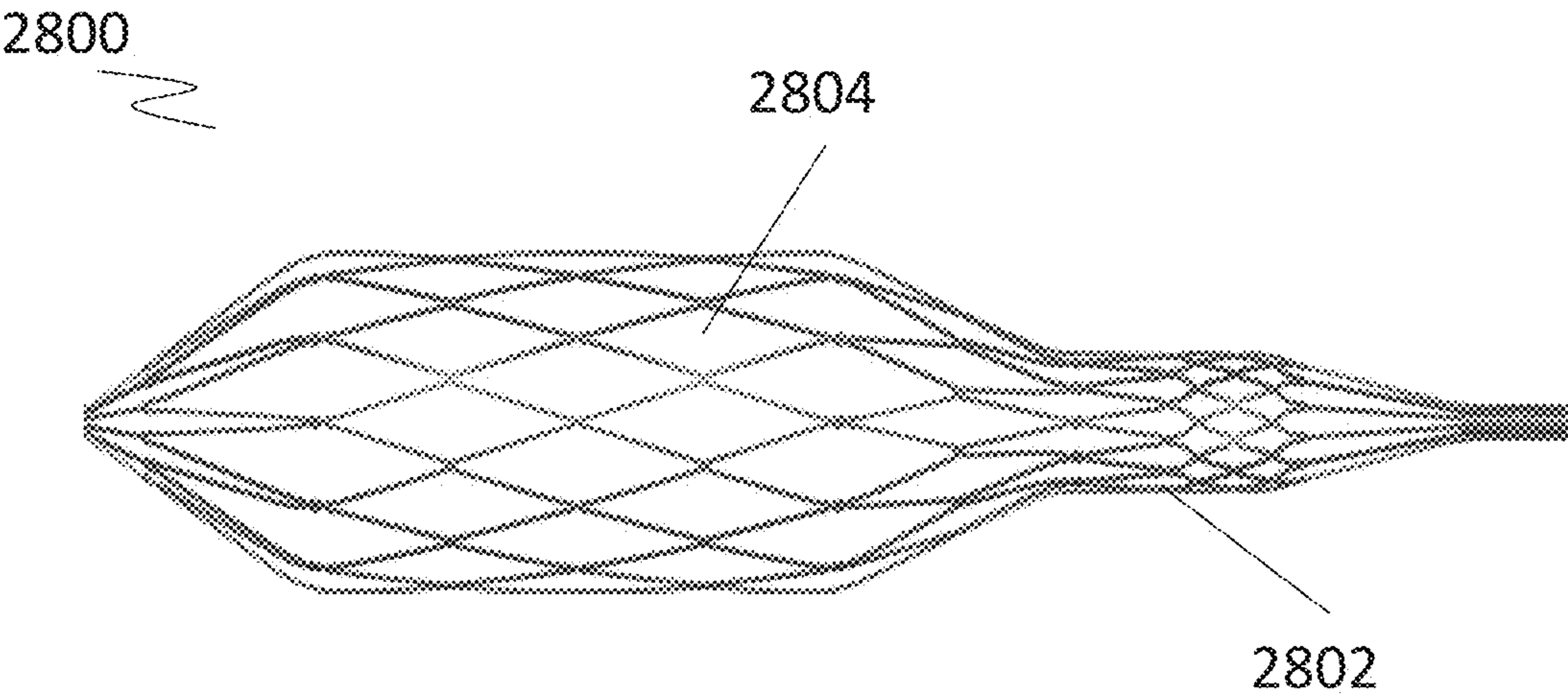


FIG. 44

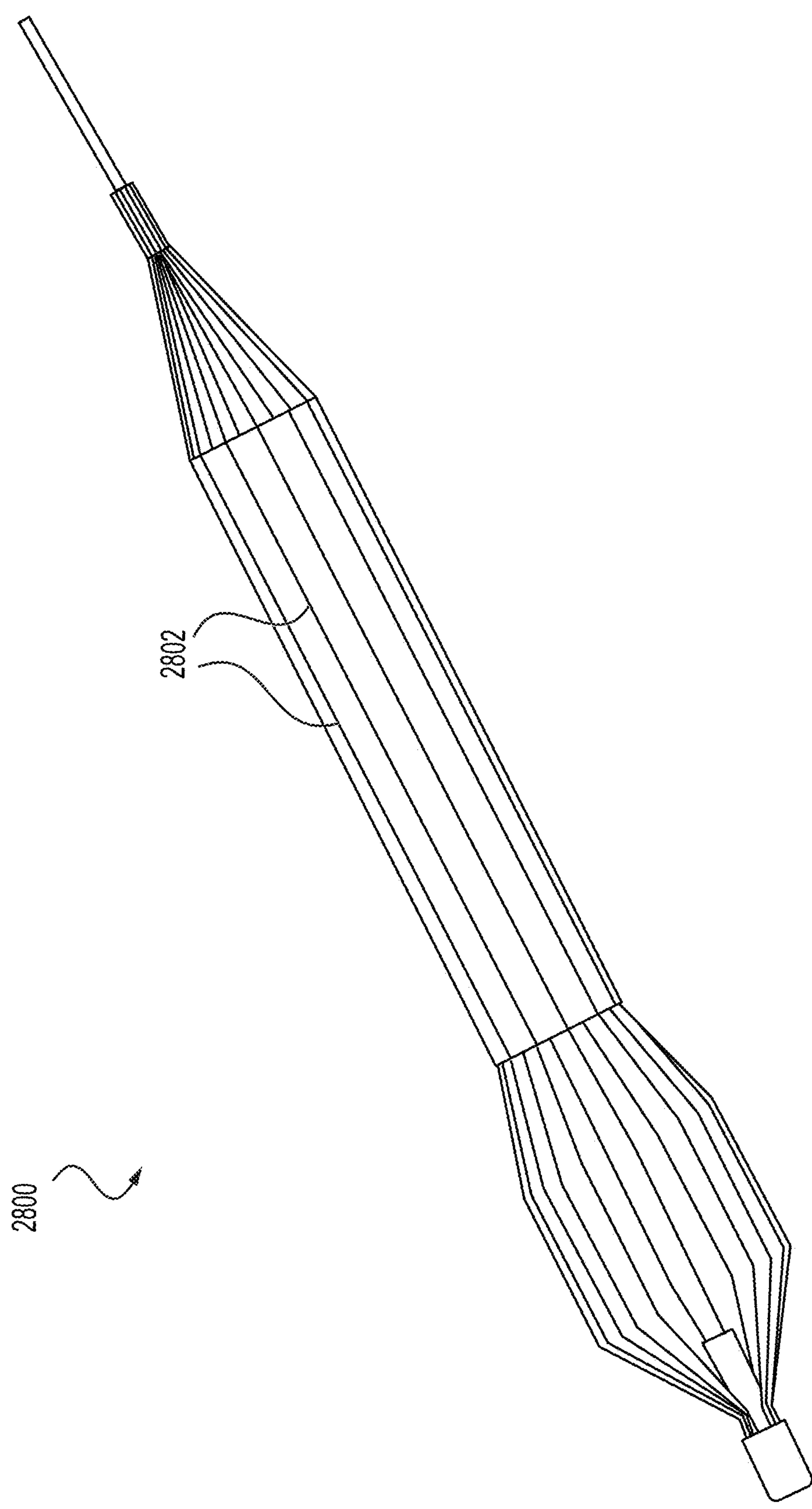


FIG. 45

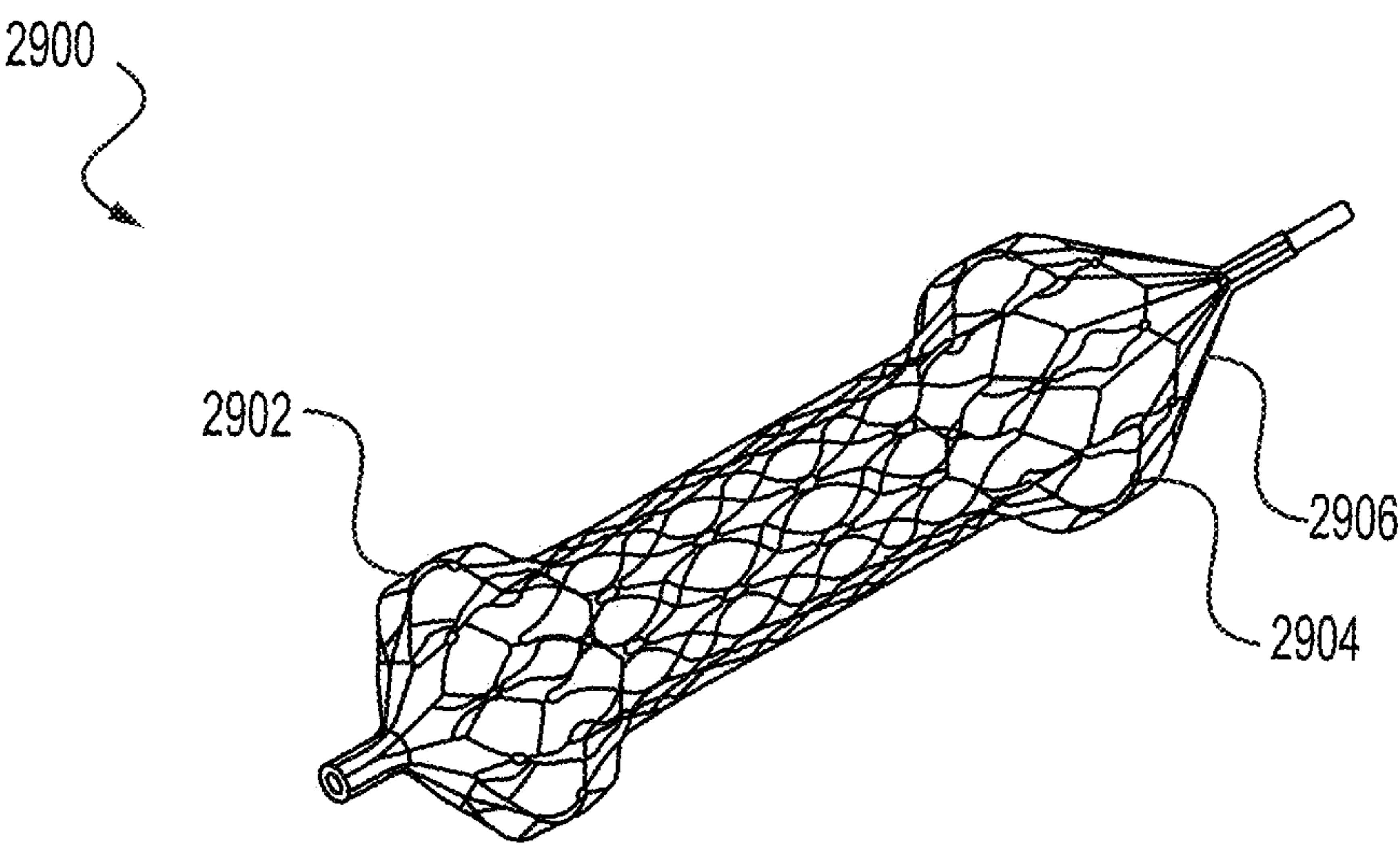


FIG. 46A

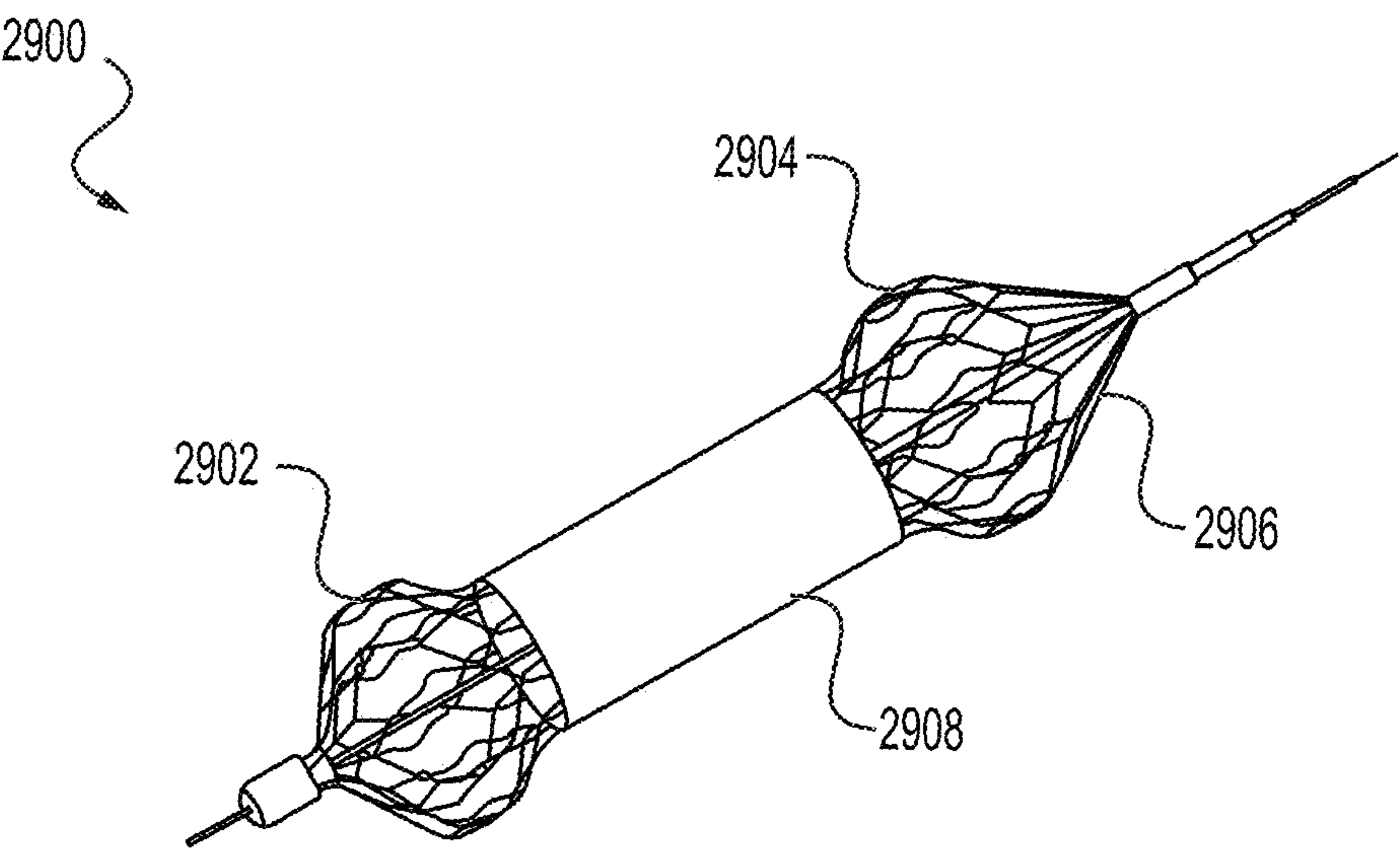


FIG. 46B

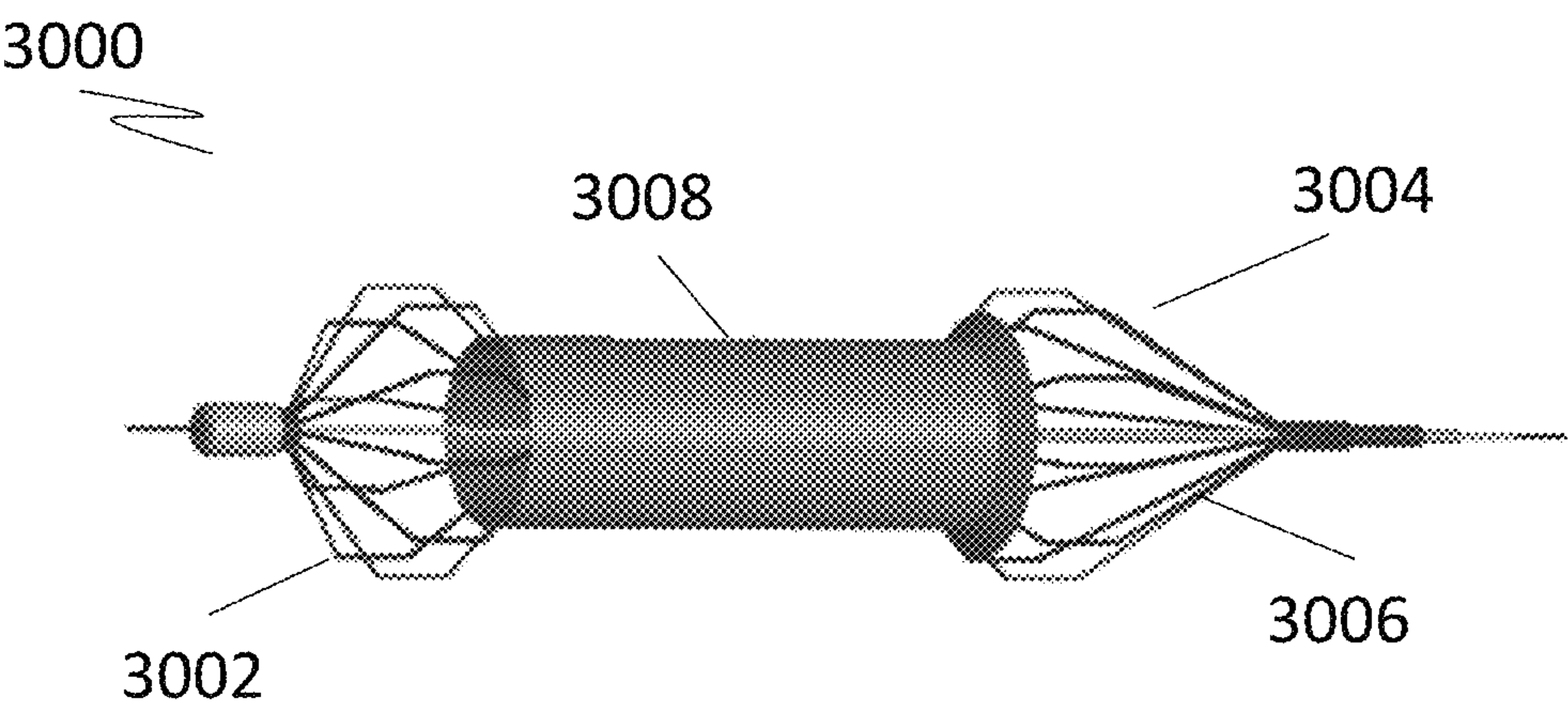


FIG. 47A

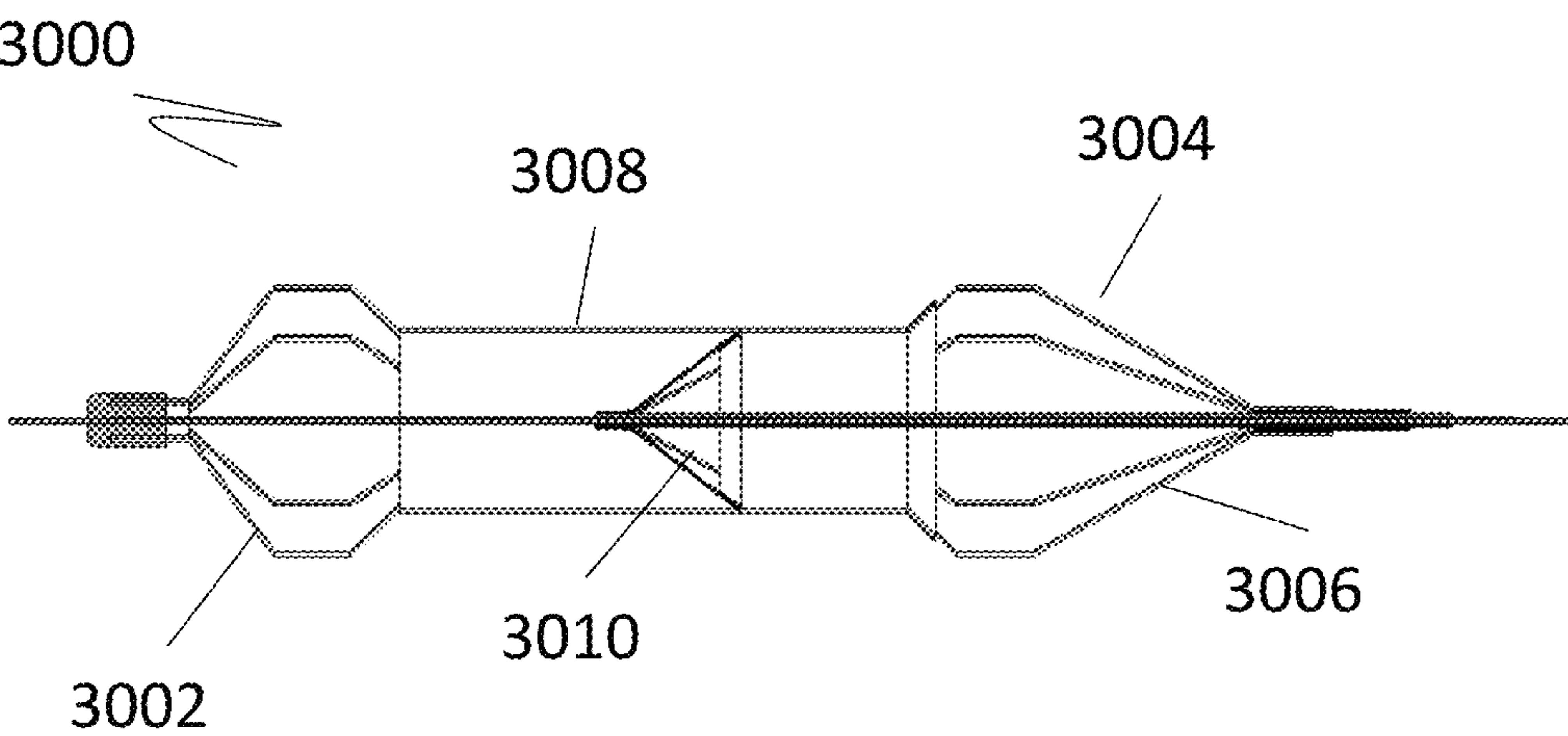


FIG. 47B

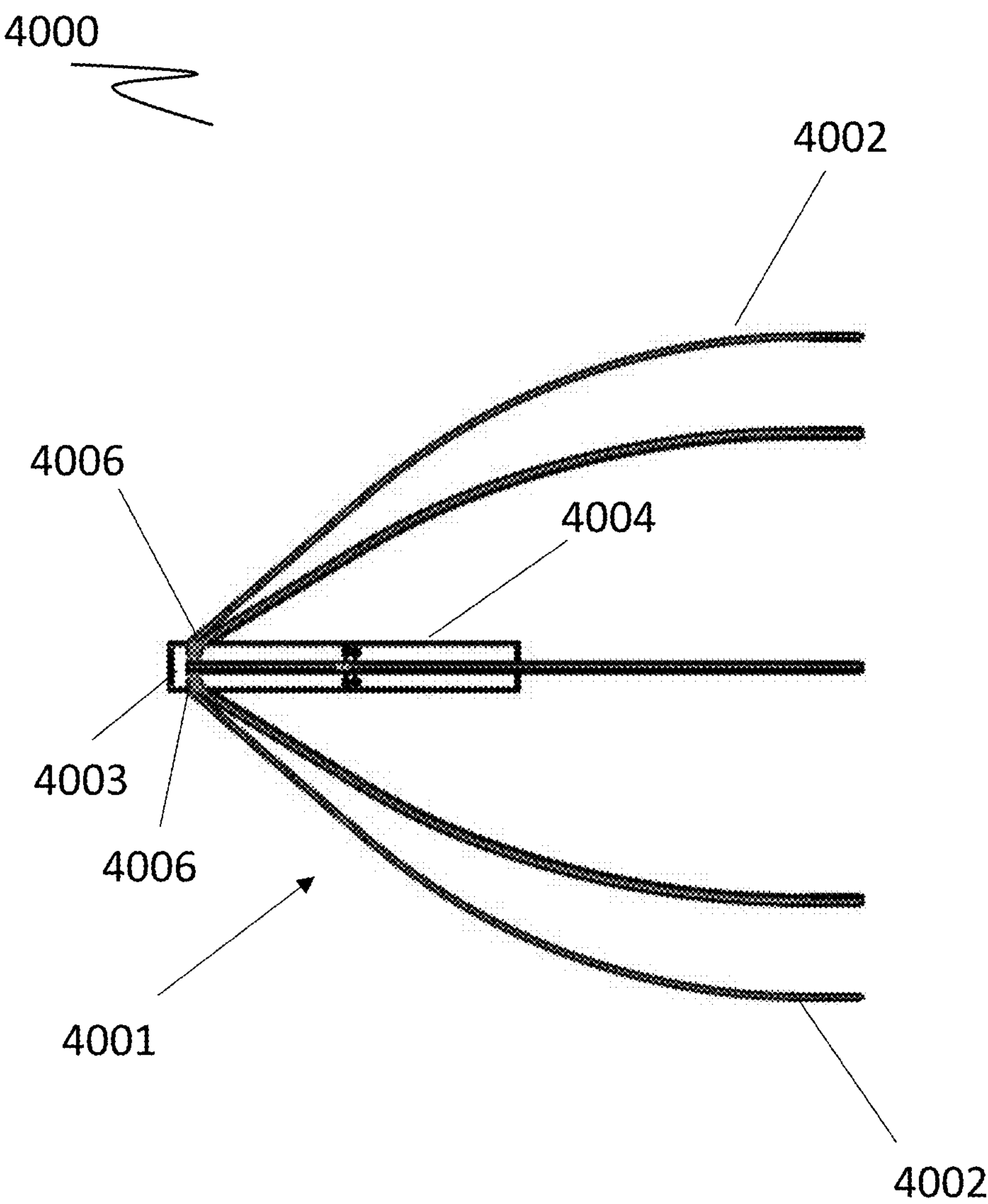


FIG. 48

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**LINEAR CARDIAC ASSIST PULSATILE
PUMP****CROSS-REFERENCE TO RELATED
APPLICATIONS**

This application is a continuation of U.S. application Ser. No. 17/676,025, filed on Feb. 18, 2022, which claims priority to U.S. Provisional Application Ser. No. 63/152,126, filed on Feb. 22, 2021, U.S. Provisional Application Ser. No. 63/176,817, filed on Apr. 19, 2021, and U.S. Provisional Application Ser. No. 63/299,385, filed on Jan. 13, 2022, each of which is hereby incorporated by reference in its entirety.

FIELD

This application relates generally to blood pumping devices. The devices may be cardiac assist devices or cardiac assist pumps of the type used to supplement or sustain blood flow on a short-term basis. Such devices are generally utilized in the treatment of patients experiencing compromised heart performance or heart failure in order to stabilize the patient and gain time for implementing more long-term treatment.

BACKGROUND

The treatment and survivability of patients experiencing severe heart trauma or heart failure is typically a time critical process. In most cases, the treatment of patients experiencing traumatic heart failure requires immediate life-sustaining measures. Basically, medical personnel must initially assist or stabilize the failing heart to maintain systemic circulation until further diagnostic measures are taken or treatment options decided.

While in some instances it may be possible for medical practitioners to stabilize such patients through careful administration of various drugs, the stabilization process often requires the application of a supplemental blood pumping apparatus. Such supplemental blood pumping apparatuses, known generally in the art as “cardiac assist devices” or “cardiac assist pumps” have had limited success despite the availability of various designs. These cardiac assist pumps generally utilize a small pumping apparatus, which is combined with a catheter support operatively coupled to an external pump drive and pump control system. The objective is to insert the pump into the patient’s blood flow at a critical point in order to supplement or substitute for the pumping action of the patient’s heart. While various pump design approaches have been employed, most cardiac assist pumps that have been developed include a rotary type pump such as a turbine impeller or the like.

Unfortunately, rotary type pumps have proven to be problematic for several reasons. Perhaps the most critical limitation of such pumps results from their undesired high speed of operation. Characteristically, such rotary pumps are required to be operated at higher rotational speeds in order to provide sufficient pressure and blood flow. Another drawback is that the use of high rotational speed pumps such as turbines, even on a short-term basis, causes damage to the patient’s blood cells, which in turn endangers the patient’s life. As a result, the operating time of cardiac assist pumps employing a rotational, turbine type pumping apparatus is typically limited. In addition to blood cell damage caused by high speed rotating pump apparatuses, problems also arise due to the constant unvarying flow characteristics of such rotational pumps. It has been found that the constant draw of

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a rotating pump may interfere with the action of heart valves and the pumping action of the heart.

Accordingly, it would be beneficial to have improved cardiac pump devices that avoid excessive damage to blood cells, and which are compatible with the pulsatile blood flow and pumping characteristics of the human heart.

SUMMARY

Described herein are pumps that linearly reciprocate to assist with circulating blood within the body of a patient. Red blood cell damage may be avoided or minimized by such linear pump movement. The linearly reciprocating movement may also generate a pulsatile pumping cycle resulting in a pulsatile blood flow that is compatible with the operation of the patient’s heart. The pumps may be configured to reside at various body locations. For example, the pumps may be situated within the right ventricle, the left ventricle, the ascending aorta, the descending aorta, the thoracic aorta, or the abdominal aorta. In some instances, the pumps may be placed within the inferior vena cava. In other instances, the pump may reside outside the patient.

In general, the pumps for assisting blood circulation described herein may include an expandable housing and a valve member disposed within the expandable housing that linearly reciprocates therein. The valve member may be, for example, a flexible diaphragm or a valve cone. Additionally, the valve members may include an inlet side that faces the inlet of the expandable housing, and an outlet side that faces the outlet side of the expandable housing. The expandable housing may include an interior surface and an expanded configuration, and may define a chamber for collecting blood. The flexible diaphragm may have an extended configuration and a collapsed configuration, and may include a diaphragm body and a rim. The valve cone may have an expanded configuration and a collapsed configuration, and may include a layer having a plurality of flaps that allow blood flow through the valve cone into the housing during the fill stroke, but which prevent blood flow through the valve cone during the pump stroke. In some instances, the pumps include a housing that is not expandable.

The valve members may be coupled to a support element having an expanded configuration and a collapsed configuration. The valve members may be structured such that expansion of the support element transforms the valve members to their expanded or extended configurations. In some variations, the support element may be an expandable frame having a conical shape. The expandable frame may be coupled to the actuator, and may support the valve cone or the flexible diaphragm as it linearly reciprocates within the housing. In other variations, the support element may be a tine support comprising a base and a plurality of tines coupled to the actuator that support the flexible diaphragm in the extended configuration during the pump stroke. The plurality of tines may be flexible and/or resilient, and have an expanded configuration and a compressed configuration.

The pumps may include an actuator coupled to the valve members (e.g., the flexible diaphragm, the valve cone, or the umbrella structure), which may be configured to linearly reciprocate the valve members within the expandable housing to generate a fill stroke and a pump stroke of a pumping cycle. The rim of the valve members may be configured to maintain contact with the interior surface of the expandable housing during the pump stroke. In some variations, contact may be maintained for the entire duration of the pump stroke. In other variations, contact may be maintained for a portion of the pump stroke, as long as sufficient pressure is

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generated to move the desired amount of blood out of the housing during the pump stroke. In further variations, for example, when high pump speeds are required, the valve members may be configured such that there is a slight clearance or gap between the rim and the interior surface of the housing. The clearance gap may help to avoid the creation of undue friction in the pump. The clearance gap may also be sized so that adequate pressure may be generated for the pump stroke while also avoiding crushing or damaging red blood cells during the pump stroke. Here the diameter of the valve members in their extended or expanded configurations may be at least about 95 percent of the diameter of the housing in its expanded configuration. For example, the valve members in their extended or expanded configurations may be at least about percent 95 percent, at least about 96 percent, at least about 97 percent, at least about 98 percent, or at least about 99 percent of the diameter of the housing in its expanded configuration. The pumps may be driven by an external linear motor drive and linear motor controller situated at the end of a catheter external to the patient. The linear motor drive may be operatively coupled to the linearly acting cardiac assist pump by a flexible cable or other flexible actuator. A movable sleeve or sheath may hold the expandable housing and the valve member (e.g., the flexible diaphragm, the valve cone, or the umbrella structure) in a collapsed configuration to enable their insertion and advancement to a target location within the circulatory system.

More specifically, the expandable housing of the pump may comprise a support or scaffold including a proximal end and a distal end. The scaffold may be made from a material comprising stainless steel, titanium, or alloys thereof. With respect to the proximal and distal ends, they may or may not be tapered. Furthermore, the distal end of the scaffold may include an inlet for blood flow during the pump stroke. The proximal end of the scaffold may include an outlet for blood flow during the pump stroke.

In the expanded configuration, the chamber of expandable housing may have a diameter ranging from about 12 mm to about 30 mm, including all values and sub-ranges therein. The expandable housing may further include a covering. For example, the expandable housing may include a polymer layer, which may comprise an elastomeric polymer such as, but not limited to, a silicone, a polyester, a polyurethane, a fluoropolymer, or a combination thereof. Alternatively, the expandable housing may include a fabric layer coupled to the scaffold. For example, the fabric layer may comprise a woven material such as buckram or a material woven from polyester fibers. A film or sheet of non-woven material such as Mylar® plastic film may also be coupled to the expandable housing.

The pump may further include a cannula extending from the expandable housing. The cannula may extend from either the proximal end or the distal end of the expandable housing. The length of the cannula may vary, depending on such factors such as the intended location of pump placement, or the age or size of the patient. For example, cannula lengths may range from about 2.5 cm to about 5.0 cm, about 25 cm to about 30 cm, or about 35 cm to about 40 cm. Some variations of the cannula may have a length ranging from about 0.5 cm to about 10 cm, including all values and sub-ranges therein. In these variations, the length of the cannula may be about 0.5 cm, about 1.0 cm, about 1.5 cm, about 2.0 cm, about 2.5 cm, about 3.0 cm, about 3.5 cm, about 4.0 cm, about 4.5 cm, about 5.0 cm, about 5.5 cm,

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about 6.0 cm, about 6.5 cm, about 7.0 cm, about 7.5 cm, about 8.0 cm, about 8.5 cm, about 9.0 cm, about 9.5 cm, or about 10 cm.

When the pump includes a valve cone within the expandable housing, the valve cone may include a single material layer or a plurality of material layers coupled to an expandable frame. The plurality of material layers may include mesh layers, flow control layers, or a combination thereof. In some instances, a mesh layer may be disposed between a flow control layer and the expandable frame. Woven fabrics or elastomeric polymers may be used to form the mesh layer. Exemplary elastomeric polymers include without limitation, a silicone, a polyester, a polyurethane, a fluoropolymer, or a combination thereof. The material layers may be coupled to the expandable frame in any suitable manner, for example, by stitching, suturing, or embroidering, by use of an adhesive, by heat sealing, or by welding. The expandable frame may comprise stainless steel, nickel, titanium, or alloys thereof. In general, the valve cone has a conical shape, but any shape capable of being collapsed to permit advancement through the cannula may be used. When the valve cone is conically shaped, the plurality of material layers (e.g., the mesh and flow control layers) and the expandable frame in their expanded configurations are conically shaped. As previously mentioned, the valve cone may have an inlet side that faces the inlet of the expandable housing, and an outlet side that faces the outlet of the expandable housing.

The flow control layer of the valve cone (also referred to as the flow control cone herein) may also be formed from various polymers, for example, an elastomeric polymer as stated above, or from Mylar® plastic film. The flow control layer may include a plurality of flaps having an open configuration and a closed configuration. In general, the plurality of flaps are in the open configuration during the fill stroke, and in the closed configuration during the pump stroke. The flow control layer may be cut to create a plurality of flaps, which may be of any suitable size and shape that allows blood to flow into the housing during the fill stroke. For example, the flaps may have a semi-circular shape, an arc shape, a circular shape, a triangular shape, a diamond shape, a square shape, or a rectangular shape. Any suitable number of flaps in the flow control layer may also be employed. For example, a flow control layer including 15 flaps may be useful. The valve cone may be configured such that a greater number of flaps are included when they are smaller in size, and a smaller number of flaps are included when they are larger in size. For example, three flaps may be employed when the flaps are larger in size. When the flaps are semi-circular in shape, they may have a radius ranging from about 0.50 mm to about 3.0 mm, including all values and sub-ranges therein.

Some valve members may also comprise a membrane coupled to a plurality of radially expandable and collapsible struts. The membrane may entirely or partially cover the struts and may be formed from any suitable elastomer. Non-limiting examples of elastomers include silicones, polyesters, polyurethanes, fluoropolymers, or a combination thereof. Exemplary fluoropolymers may be polytetrafluoroethylene (PTFE) or expanded polytetrafluoroethylene (ePTFE). Here the valve members may also have an open configuration and a collapsed configuration. For example, the valve members may have an umbrella structure. The plurality of struts may support the membrane and any suitable number of struts may be included. The number of struts may range from three to ten (including all values and sub-ranges therein). In general, the valve members including struts may have a collapsed configuration during the fill

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stroke, and an open configuration during the pump stroke. In some instances, the valve member consists of the umbrella structure without an associated expandable frame.

The length of the struts included in the umbrella structure may vary depending on such factors as the expanded diameter of the housing, size of the membrane, and manner of attachment of the struts to the linear actuator, and may range from about 1.0 cm to about 3.0 cm, including all values and sub-ranges therein. Struts having a longer length may extend beyond the rim of the membrane. In some instances, the struts include one or more bends along their length. The one or more bends may be provided at any location along the strut. For example, the one or more bends may be at the distal end (free end) of the struts and/or provided at the midpoint of the struts. The bends in the struts may form a bend angle of about 5 degrees to about 15 degrees with respect to the longitudinal axis of the umbrella structure, including all values and sub-ranges therein.

The struts may have one or more sections, and the one or more sections may have any suitable shape or geometry. The cross-sectional shape of the struts may be circular, ovular, triangular, square, or rectangular. The struts may have different cross-sectional shapes along their length. For example, the struts may have one or more sections with a circular cross-sectional shape, and one or more sections with a rectangular cross-sectional shape. In some instances, the struts may include three sections, two end sections and a middle section therebetween. The end sections may have a circular cross-sectional shape and the middle section may have a rectangular cross-sectional shape. The rectangular cross-sectional shape may provide the middle section with a flattened profile. In some variations, different sections of the struts may have different widths. For example, when the struts include three sections (two end and one middle section), the middle section may be wider than the two end sections. The distal tip of the struts may be rounded to help prevent the struts from damaging the interior surface of the housing during the pump stroke. A radiopaque marker may also be provided at any appropriate location along the length of one or more struts, for example, at the distal end of one or more struts (e.g., one third of the struts, half the struts, all of the struts).

The umbrella structures may further include an anchor having a proximal end and a distal end. The proximal end may be configured to attach to the linear actuator of the pump. The distal end may be configured attach to the plurality of struts. When the umbrella structure is in its expanded configuration, the plurality of struts may flare radially outward from the distal end of the anchor to create a strut angle with respect to the longitudinal axis of the umbrella structure. The strut angle may range from about 30 degrees to about 60 degrees, including all values and sub-ranges therein.

The mesh layer may be used to support the flow control layer such that when pressure against the flaps is applied during the pump stroke, the flaps are not pushed through the openings in the expandable frame. Thus, the mesh layer may help maintain the flaps in the closed configuration during the pump stroke when blood is moved out of the housing via the housing outlet. However, during the fill stroke, the mesh layer permits blood to flow from the housing inlet through the holes in the mesh and then through the flaps, transitioning them to their open configuration so that blood may move to the outlet side of the valve cone. In some instances, for example, when the openings of the expandable frame are smaller than the flaps, the valve cone may not include a mesh layer.

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In addition to a rim, the flow control layer may include a body. The body and the rim may be made from the same material or from different materials. Additionally, the body and the rim may be separate components or integrally formed with one another. When provided as separate components, the body may be formed from an elastomeric polymer or from Mylar® plastic film, and the rim may be an O-ring. The peripheral edge of the flow control layer may be rolled over the O-ring to form the rim. The thickness of the rim may be greater than the thickness of the body. The body may have a thickness ranging from about 0.03 mm to about 0.05 mm. The rim may have a thickness ranging from about 0.20 mm to about 1.5 mm. In some instances, the thickness of the rim and body may be equal.

Some variations of the valve member comprise a flexible diaphragm contained within the expandable housing. The flexible diaphragm may comprise an elastomeric polymer. Non-limiting examples of elastomeric polymers include silicones, polyesters, polyurethane elastomers, fluoropolymers, or a combination thereof. Exemplary fluoropolymers may include polytetrafluoroethylene (PTFE) or expanded polytetrafluoroethylene (ePTFE). The body and rim of the flexible diaphragm may comprise the same material or different materials. In some instances, the diaphragm body and rim are integrally formed. Thicknesses of the diaphragm body may range from about 0.03 mm to about 0.3 mm. With respect to the rim of the diaphragm, its thickness may range from about 0.70 mm to about 1.5 mm. The thickness of the rim may be greater than the thickness of the diaphragm body, which may allow the flexible diaphragm to be in its collapsed configuration during the fill stroke, and the extended configuration during the pump stroke of a pumping cycle. However, in some variations, the rim and body may have equal thicknesses. The rim of the flexible diaphragm may have a width ranging from about 1 mm to about 2 mm.

Furthermore, the flexible diaphragm may have any suitable shape or geometry capable of creating a seal between the rim of the diaphragm and the interior surface of the expandable housing during the pump stroke. For example, the flexible diaphragm may have a conical shape when in the extended configuration. A plurality of ribs that extend from a center portion of the diaphragm body to the rim may be employed to maintain the conical shape during a pump stroke. The plurality of ribs may have a rib angle between a rib of the plurality of ribs and an axis perpendicular to the actuator that ranges from about 30 degrees to about 60 degrees. The plurality of ribs may be equally spaced from one another. In some variations, the plurality of ribs may have unequal spacing from one another. Some variations of the pump may also include a tine support comprising a base and a plurality of tines coupled to the actuator that support the flexible diaphragm in the extended configuration during the pump stroke. The plurality of tines may be flexible and/or resilient, and have an expanded configuration and a compressed configuration. In other variations, the flexible diaphragm may be coupled to an expandable frame that is conically shaped. Coupling to the expandable frame may be accomplished in any suitable manner, for example, by stitching, suturing, or embroidering, by use of an adhesive, by heat sealing, or by welding.

Some of the pumps described herein may include a valve member comprising elements that limit its expansion. For example, the valve member may include an expandable frame coupled to a polymer layer, where a plurality of control lines or tethers attach the valve member to the pump actuator. The plurality of tethers may have a relaxed state and a tensioned state, and may have a length that limits

expansion of the valve member such that it contacts and creates a seal with the inner surface of the pump housing during a pump stroke of the pumping cycle without generating undue friction. The length of the tethers may also be tailored so that a small gap is created between the valve member and the inner surface of the pump housing during the pump stroke. During the fill stroke, the valve member may collapse to a collapsed configuration, which in turn may move the plurality of tethers to the relaxed state. During the pump stroke, the valve member may expand to an expanded configuration, which may transition the plurality of tethers from the relaxed state to the tensioned state.

In some instances, the expandable housing of the pump may include a plurality of openings or perforations. The number of openings utilized may range between about 2 to about 25. The openings may be equally or unequally spaced on a portion of the expandable housing. Additionally, the plurality of openings may have a diameter ranging between about 0.10 mm to about 6.50 mm. When the expandable housing includes openings, a skirt may also be coupled to the expandable housing that surrounds the plurality of openings.

Any component of the pumps described herein may be coated. For example, one or more of the cannula, expandable housing, expandable frame, valve cone, flexible diaphragm, and umbrella struts may be coated. Pump components may be entirely or partially coated. The coating may provide increased lubricity and/or wettability to portions of the pump that are coated, or may provide anti-fouling, antiproliferative, or antimicrobial properties to the pump.

The coatings may generally comprise a polymeric material. Exemplary polymeric materials may include without limitation, hydrophilic polymers, hydrophobic polymers, or mixtures of these two types of polymers. The coating may be a single layer on the pump component, or may include a plurality of layers. When multiple layers are employed, each layer may be made from the same polymer or from different polymers. Coatings that include polytetrafluoroethylene (PTFE) or expanded polytetrafluoroethylene (ePTFE) may be useful.

There are some variations in which the pump may be disposed within a console external to a patient. A coaxial catheter coupled the housing of the pump may provide continuous and pulsatile blood flow between the patient and the external pump, and have a diameter between about 10 F. and 18 F. The coaxial catheter may include an inflow lumen and an outflow lumen. The inflow lumen may generally have a diameter greater than about 5 F.

Methods for pumping blood are further described herein. The methods generally include advancing a pump to a target location within the circulatory system of a patient, where the pump includes an expandable housing comprising an interior surface, an expanded configuration, and a collapsed configuration. The pump may further include a valve member that linearly reciprocates within the housing. Exemplary valve members may be a valve cone including a plurality of material layers coupled to an expandable frame, a flexible diaphragm, or an umbrella structure. The valve cone, flexible diaphragm, and membrane of the umbrella structure may comprise a body and a rim, where the valve cone has an expanded configuration and a collapsed configuration, the flexible diaphragm has an extended configuration and a collapsed configuration, and the umbrella structure has an expanded and collapsed configuration. Once at the target location, the expandable housing may be expanded to the expanded configuration and the valve cone, flexible diaphragm, or umbrella structure contained therein linearly

reciprocated to generate a fill stroke and a pump stroke of a pumping cycle. During the pump stroke, contact between the rim of the valve member and the interior surface of the expandable housing may be maintained such that a seal is created to prevent blood flow between the rim and interior surface. Additionally, during the pump stroke, blood is pulled into the expandable housing. Depending on the variation of pump used, blood may be pulled into the expandable housing from the left ventricle or the aorta. The pump stroke may generally push blood out of the expandable housing into a portion of the aorta, for example, the ascending aorta or the descending aorta. During the pumping cycle, the flaps in the flow control layer of a valve cone close during the pump stroke and open during the fill stroke. When a flexible diaphragm is employed, it may be collapsed to the collapsed configuration during the fill stroke and extended to the extended configuration during the pump stroke. Likewise, when linearly reciprocated, the umbrella structure may collapse to the collapsed configuration during the fill stroke and expand to the expanded configuration during the pump stroke.

The pump may be advanced and positioned in various parts of the circulatory system of the patient. For example, the expandable housing of the pump may be advanced through the arterial vasculature, such as through the femoral artery, the aorta, and the aortic valve and into the left ventricle of the patient. When the pump further comprises a cannula, the cannula may also be advanced through the aortic valve and into the left ventricle of the patient. Non-limiting examples of target locations for the expandable housing include the aortic arch, the descending aorta, the thoracic aorta, and the abdominal aorta. In some instances, the expandable housing of the pump may be advanced within the descending aorta and specifically positioned to assist with perfusion of the kidneys of a patient. For example, the expandable housing may be positioned in the descending aorta near the renal arteries to assist with renal perfusion.

In addition to the arterial vasculature, the pump may be advanced and positioned within the venous circulation. For example, the expandable housing of the pump may be advanced within the inferior vena cava to a location between the hepatic veins and the right atrium of the heart. When placed in this location, the pump may draw blood toward the heart and increase circulation from the lower extremities and from the liver. The pump may be positioned at various locations between the hepatic veins and the right atrium. In some variations, the expandable housing is placed closer to the hepatic veins than to the right atrium. In one variation, for example, when the pumps are placed in the venous circulation, they may include a housing chamber (flow chamber) without an associated cannula.

As previously described, the expandable housing may comprise a plurality of openings or perforations, and a skirt coupled to the expandable housing. In this instance, blood exiting the openings may be directed in a retrograde direction toward the heart of the patient during the pump stroke by the skirt. The length of the skirt may be adjusted to achieve a predetermined amount of retrograde blood flow toward the heart of the patient. The number of openings may also be adjusted to achieve a predetermined amount of retrograde blood flow toward the heart of the patient. Alternatively, the diameter of the openings may be adjusted to achieve a predetermined amount of retrograde blood flow toward the heart of the patient. Adjustment of any one or combination of the foregoing features may be utilized so that about 60% of the blood from the pump stroke flows in a

retrograde direction toward the heart of the patient about 50% of the blood from the pump stroke flows in a retrograde direction toward the heart of the patient, or about 40% of the blood from the pump stroke flows in a retrograde direction toward the heart of the patient.

When the pump is disposed external to the patient, the method for pumping blood may include accessing the circulatory system of a patient with a coaxial catheter and coupling the coaxial catheter to the housing of the pump. The housing may comprise an interior surface. A flexible diaphragm contained within the housing may comprise a diaphragm body and a rim, where the flexible diaphragm has an extended configuration and a collapsed configuration. Alternatively, a valve cone may be disposed within the housing to linearly reciprocate therein. The external pump may be disposed within, or attached to, a console comprising a user interface.

Access to the circulatory system may be obtained from any suitable artery or vein, for example, the femoral artery, the subclavian artery, the carotid artery, or the jugular vein. Once access is obtained, the coaxial catheter may be advanced to a target location in the circulatory system and a valve member, for example, a valve cone, flexible diaphragm, or umbrella structure, linearly reciprocated within the expandable housing to generate a fill stroke and a pump stroke of a pumping cycle. During the pump stroke, contact between the rim of the valve cone, the flexible diaphragm, or the umbrella structure, and the interior surface of the expandable housing may be maintained to create a seal therebetween and prevent blood from flowing around the flexible diaphragm. The seal may help generate and maintain the force of the pump stroke as well as minimize red blood cell damage that may occur with blood flowing between a space existing between the rim and the interior surface. The methods described herein may include advancing coaxial catheter to various target locations in a patient. For example, the target location for the inflow lumen may be a left ventricle of the patient, or the target location for the outflow lumen may be above an aortic valve of the patient.

The coaxial catheter may comprise an inflow lumen and an outflow lumen. The inflow lumen may receive blood from the left ventricle and the outflow lumen may return blood to the ascending aorta. In general, the pump stroke may pull blood into the housing through the inflow lumen as well as push blood out of the housing and through the outflow lumen. During the fill stroke, the flexible diaphragm may be collapsed to the collapsed configuration. Correspondingly, the flexible diaphragm may be extended to the extended configuration during the pump stroke. When a valve cone is used, the plurality of flaps in the flow control layer may be open during the fill stroke and closed during the pump stroke. A mesh layer may be provided with the flow control layer to support the flaps and prevent them from opening during the pump stroke.

Other methods for pumping blood may include advancing a pump to a target location within the aorta of a patient, such as the thoracic aorta or the abdominal aorta, where the pump has a fill stroke and a pump stroke; pulling a fill volume of blood into the pump during the pump stroke; and pushing an exit volume of blood out of the pump during the pump stroke, where the exit volume comprises a first portion of blood and a second portion of blood. The fill stroke may pull blood from the left ventricle of the patient. Additionally, the first portion of blood may be pumped in a retrograde direction toward the head of the patient, and the second portion of blood may be pumped in an antegrade direction.

The second portion of blood may be about 60% of the exit volume, about 50% of the exit volume, or about 40% of the exit volume.

In some methods, an expandable housing having a cannula extending from a proximal end of the housing is advanced within a selected artery and positioned at a target location, such as the patient's aorta and left ventricle. The selected artery may be the femoral artery. Once at the target location, a sheath surrounding the expandable housing may be withdrawn, thereby allowing the expandable housing to expand to its pumping configuration. An actuator may then be advanced into the housing and a linear motor drive activated to induce reciprocating motion of a valve member (e.g., a valve cone or a flexible diaphragm) coupled thereto within the expandable housing in forward and rearward directions. During the reciprocating movement, forward movements may induce blood flow into the housing and rearward movements may exert a pumping force against blood within the housing. The result is a linear pulsatile pumping action that may be extremely efficient, and which may be compatible with the pulsatile behavior of the human heart. The characteristics of the reciprocating movement of the pumps described herein may be independently varied to provide optimized forward strokes, rearward strokes, and movement profiles.

Systems for pumping blood are also described herein. The systems may generally include a pump, where the pump comprises an expandable housing having an interior surface and an expanded configuration. A valve member including a rim may be disposed within the expandable housing, and may have an expanded or extended configuration, and a collapsed configuration. The pump may also include an actuator coupled to the valve member that linearly reciprocates the valve member within the housing to generate a pump stroke and a fill stroke of the pumping cycle. During the pump stroke, the rim of the valve member may be configured to maintain contact with the interior surface of the housing. In some variations, contact may be maintained for the entire duration of the pump stroke. In other variations, contact may be maintained for a portion of the pump stroke, as long as sufficient pressure is generated to move the desired amount of blood out of the housing during the pump stroke. In further variations, for example, when high pump speeds are required, the valve members may be configured such that there is a slight clearance or gap between the rim and the interior surface of the housing. The clearance gap may help to avoid the creation of undue friction in the pump. The clearance gap may also be sized so that adequate pressure may be generated for the pump stroke while also avoiding crushing or damaging red blood cells during the pump stroke. Here the diameter of the valve members in their extended or expanded configurations may be at least about 95 percent of the diameter of the housing in its expanded configuration. For example, the valve members in their extended or expanded configurations may be at least about 95 percent, at least about 96 percent, at least about 97 percent, at least about 98 percent, or at least about 99 percent of the diameter of the housing in its expanded configuration.

Additionally, the systems may include a console located external to the patient that contains a controller configured to regulate the actuator. A user interface may be coupled to the controller and configured to manually set or adjust a pump parameter and/or a patient parameter, and/or display the pump and patient parameters. The user interface may be a display that forms part of the console that houses the linear

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actuator. The console may be a stationary component of the system, or a mobile component when coupled to a wheeled cart or other rolling base.

Exemplary pump parameters include without limitation, pump cycles per minute and duration of the pump cycle. When setting or adjusting the duration of the pump cycle, the duration of either the fill stroke or the pump stroke may be set or adjusted. Non-limiting examples of patient parameters include age, height, weight, left ventricular pressure, left ventricular end-diastolic pressure, aortic pressure, and systemic blood pressure. The systems may issue an audible and/or visual alert when any pump parameter or patient parameter falls above or below a preset value, or above or below a preset range of values.

In use, the pump of the systems may be advanced to a target location within the circulatory system of a patient. The pumps may comprise an expandable housing including an interior surface, an expanded configuration and a collapsed configuration, and a valve member comprising a rim disposed within the expandable housing, as described above. Once at the target location, the expandable housing may be expanded from the collapsed configuration to the expanded configuration. Pump parameters and/or patient parameters may be determined and the valve member may be linearly reciprocated within the expandable housing according to those parameters to generate a fill stroke and a pump stroke. During the pump stroke, contact between the rim of the valve member and the interior surface of the expandable housing may be maintained. As mentioned above, pump parameters may include pump cycles per minute, duration of the pump cycle, or both. When setting or adjusting the duration of the pump cycle, the duration of either the fill stroke or the pump stroke may be set or adjusted, or both may be set or adjusted. When pump parameters are determined, they may be based on a patient parameter such as age, height, weight, left ventricular pressure, left ventricular end-diastolic pressure, aortic pressure, or systemic blood pressure.

The pump parameters and patient parameters may be displayed on a user interface. The parameters may be continuously or intermittently monitored, and the measurements continuously or intermittently displayed on the user interface. The user interface may be a display that forms part of the console that houses the linear actuator. The console may be a stationary component of the system, or a mobile component when coupled to a wheeled cart or other rolling base, as mentioned above. Pump and patient parameters may be manually adjusted via buttons on the user interface. In some instances, the display of the user interface includes touch-sensitive buttons for manually adjusting the parameters. In other instances, the pump parameters may be automatically adjusted based on measured patient parameters.

The pump of the systems may be advanced to a target location within an artery. When the artery is the aorta, the target location may be the ascending aorta, the aortic arch, the thoracic aorta, the descending aorta, or the abdominal aorta. Pumps may also be advanced to a target location within a vein. The vein may be the inferior vena cava. When advanced within the inferior vena cava, the target location may reside between a hepatic vein and the right atrium. At this location, the pump may increase circulation from the liver or from a lower extremity. Another target location for the pump may be above or below the renal veins. Yet another target location may be within the aorta, either above or below the renal arteries. Pumps positioned at these target locations may assist with perfusion of the kidneys as part of

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the treatment of cardiorenal syndrome due to acute or chronic heart failure, or decreased renal perfusion due to other causes.

BRIEF DESCRIPTION OF THE DRAWINGS

FIG. 1 depicts a perspective view of an exemplary pump and linear motor drive.

FIG. 2 depicts the pump of FIG. 1 being advanced within the aorta to a left ventricle of the heart.

FIG. 3 illustrates the movement of blood resulting from a pumping stroke of the pump of FIG. 2.

FIG. 4 illustrates the filling stroke of the pump of FIG. 2.

FIG. 5 depicts an enlarged cross-sectional view of the pump of FIG. 1 prior to deployment in a heart.

FIG. 6 depicts an enlarged cross-sectional view of the pump of FIG. 1 at an intermediate point during its configuration for pumping operation.

FIG. 7 depicts an enlarged cross-sectional view of the pump of FIG. 1 at the completion of its configuration for pumping operation.

FIG. 8 depicts an enlarged cross-sectional view of the pump of FIG. 1 during a filling stroke portion of its pumping operation.

FIG. 9 depicts an enlarged cross-sectional view of the pump of FIG. 1 during a pumping stroke portion of its pumping operation.

FIGS. 10A-10C depict side views of an exemplary housing comprising a scaffold and blocking layer. The scaffold is shown in FIG. 10A and the blocking layer in FIG. 10B. In FIG. 10C, the scaffold is shown coupled to the blocking layer.

FIG. 11 depicts a perspective view of an exemplary pump including the housing of FIG. 10C and a flexible diaphragm supported by a plurality of tines.

FIGS. 12A and 12B depict an enlarged view of a flexible diaphragm according to one variation. FIG. 12A shows a top view of flexible diaphragm and FIG. 12B shows a side, cross-sectional view of the diaphragm in FIG. 12A taken along line A-A.

FIGS. 13A-13C depict enlarged views of a plurality of tines according to one variation. FIG. 13A shows a side view of the plurality of tines; FIG. 13B shows a side, cross-sectional view of the tines of FIG. 13A taken along line A-A; and FIG. 13C shows a front view of the tines of FIG. 13A, illustrating their spacing from one another.

FIGS. 14A-14C depict enlarged views of another exemplary design for the plurality of tines. FIG. 14A shows a side view of the plurality of tines; FIG. 14B shows a side, cross-sectional view of the tines of FIG. 14A taken along line A-A; and FIG. 14C shows a front view of the tines of FIG. 14A, illustrating their spacing from one another.

FIG. 15 depicts a perspective view of another exemplary pump including a conical shaped flexible diaphragm.

FIGS. 16A-16C depict enlarged views of the conical shaped flexible diaphragm of FIG. 15. FIG. 16A shows a top view of the diaphragm of FIG. 15; FIG. 16B shows a side view of the diaphragm of FIG. 16A, and FIG. 16C shows a side, cross-sectional view of the diaphragm of FIG. 16B.

FIG. 17 illustrates seal formation between an exemplary conical shaped flexible diaphragm and an interior surface of a housing.

FIGS. 18A and 18B depict a pump according to another variation, where the housing lacks a cannula extending therefrom. FIG. 18A shows the pump positioned in the

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descending thoracic portion of the aorta. FIG. 18B shows the pump positioned in the descending abdominal portion of the aorta.

FIG. 19 depicts an exemplary pump comprising a housing that includes a plurality of openings and a skirt coupled to the housing.

FIG. 20 depicts an enlarged view of the housing of FIG. 19 with a cut out to show how the skirt and plurality of openings work with the flexible diaphragm to generate retrograde blood flow.

FIG. 21 illustrates how blood flows during a pumping cycle including retrograde and antegrade flow.

FIGS. 22A-22C depict a pump according to yet another variation, coupled to a linear motor drive external to the patient. FIG. 22A shows the pump within the patient and coupled to the linear motor drive within an external console; FIG. 22B shows a close-up view of the housing of the pump within the patient; and FIG. 22C shows a close-up view of the distal end of the cannula within the left ventricle.

FIGS. 23A-23C depict an exemplary external pump disposed within a bedside console, coupled to the patient via a coaxial catheter. FIG. 23A shows the coaxial catheter within the patient and coupled to linear motor drive within a bedside console; FIG. 23B shows a close-up view of the inflow and outflow lumens of the coaxial catheter; and FIG. 23C shows a close-up view of the inlet and outlet of the coaxial catheter.

FIGS. 24A-24C depict exemplary locations for pressure sensor attachment to the pump. FIG. 24A shows a perspective view of the pump and pressure sensors; FIG. 24B shows an enlarged view of two pressure sensors at the outlet of the pump; and FIG. 24C shows an enlarged view of two pressure sensors at the inlet of the pump.

FIGS. 25A-25C depict an exemplary valve member including an expandable frame, a mesh cone, and a flow control cone. FIG. 25A shows the mesh cone and the flow control cone coupled to the expandable frame; FIG. 25B shows an assembly view of the expandable frame, mesh cone, and flow control cone; and FIG. 25C shows the mesh cone and flow control cone stitched to the expandable frame at multiple attachment points.

FIGS. 26A-26C depict the expandable frame shown in FIGS. 25A and 25B. FIG. 26A shows a perspective view of the expandable frame; FIG. 26B shows a side view of the expandable frame; and FIG. 26C shows a top view of the expandable frame.

FIGS. 27A and 27B depict the mesh cone of FIGS. 25A to 25C. FIG. 27A shows a circular piece of mesh including a free edge, which may be rolled into the cone shape shown in FIG. 27B.

FIGS. 28A-28C depict the flow control cone of FIGS. 25A to 25C. FIG. 28A shows a circular piece of material including a plurality of flaps and a free edge; FIG. 28B shows a rim running circumferentially about the periphery of the material; and FIG. 28C shows the circular piece of material rolled into a cone shape.

FIGS. 29A and 29B depict another exemplary valve member including a plurality of flaps.

FIGS. 30A-30D depict a further variation of a valve member including a plurality of struts and a membrane in an umbrella structure.

FIG. 31 depicts an exemplary valve member including a plurality of tethers that limit expansion thereof.

FIGS. 32A and 32B depict an exemplary controller console and user interface.

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FIG. 33 depicts an exemplary pump including a housing chamber that lacks a cannula. The pump is shown positioned within the descending aorta above the renal arteries.

FIG. 34 depicts a view of another exemplary expandable frame supporting a flexible diaphragm.

FIGS. 35A-35B depict perspective and side views of an exemplary umbrella structure including struts entirely covered by a membrane.

FIG. 35C depicts a side view of another exemplary umbrella structure including a bend in the plurality of struts.

FIGS. 36A-36C depict views of a further exemplary umbrella structure including longer struts partially covered by a membrane.

FIG. 37 depicts a side view of another exemplary variation of an expandable housing in its expanded configuration.

FIG. 38 depicts another exemplary variation of a valve member including a plurality of struts that are fixed to the linear actuator at one end and slidable over the linear actuator at the other end.

FIGS. 39A-39B depict an exemplary variation of an inverted umbrella structure.

FIG. 40 depicts an exemplary variation of a strut distal end in an umbrella structure.

FIG. 41 depicts another exemplary variation of a strut distal end.

FIGS. 42A-42C depict a further exemplary umbrella structure in which the struts include a bend and openings in their distal ends. FIG. 42A is a side view of the umbrella structure; FIG. 42B is an end view of the umbrella structure; and FIG. 42C provides an assembly view of the umbrella structure.

FIG. 43 depicts an exemplary cell shape formed by the struts of the expandable housing.

FIG. 44 depicts an exemplary diamond cell shape formed by the struts of the expandable housing.

FIG. 45 depicts an exemplary expandable housing including a plurality of parallel struts.

FIGS. 46A-46B depict an exemplary housing having enlarged ends.

FIGS. 47A-47B depict another exemplary housing having enlarged ends.

FIG. 48 depicts a further exemplary valve member including hinges to assist with the collapse of struts during the fill stroke of the pumping cycle.

DETAILED DESCRIPTION

Described herein are pumps for assisting blood circulation. Instead of a rotary impeller, the pumps may include a linearly reciprocating member to move blood, which may help avoid the shear forces that cause red blood cell damage, and which pumps blood in a pulsatile fashion, mimicking the natural pumping cycle of the heart. The pumps may create a pressure wave or back pulse during the fill stroke to assist with the operation of the associated heart and may eliminate the collapse of blood vessels. Furthermore, the pumps may be able to provide adequate blood flow at operational speeds between 50 and 500 cycles per minute, which provides very slow movement compared to rotary impellers, and which may prevent red blood cell hemolysis. With slower pump speeds, less heat may be generated than rotary impellers, avoiding the need to include cooling apparatuses.

In some instances, the linearly reciprocating pumps may be used to increase renal perfusion. The kidneys perform several critical functions, including maintaining overall fluid balance, regulating and filtering minerals from the blood, and filtering waste materials from food, medications, and

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toxic substances. Thus, when blood flow through the kidneys is decreased, fluid may be retained, and waste materials may build up in the body to dangerous levels. Decreased renal perfusion may occur in patients with acute or chronic heart failure (e.g., cardiorenal syndrome), where lower cardiac output may result in decreased renal blood flow, or in patients with medical conditions such as diabetes or hypertension, which affect the small blood vessels in the kidneys. The pumps described herein may assist with perfusion of the kidneys as part of the treatment of cardiorenal syndrome due to acute or chronic heart failure, or decreased renal perfusion due to other causes. The renal perfusion pumps may be advanced to a target location within the aorta, either above or below the renal arteries to assist with circulation to the renal arteries.

The linearly reciprocating member may include a valve constructed such that a seal is created between it and the housing during a pump stroke of the pumping cycle, thereby generating the blood pressure needed to move blood, e.g., peripherally, to the renal arteries, etc. The pump stroke and length of the linearly reciprocating member, as well as the stroke speed, may be independently adjustable. Blood pressure and blood flow rate may be controlled by stroke length and speed adjustments. Furthermore, adjustable front and back stroke speed ramping may avoid a jolt within the pressure characteristics of the circulatory system. The pumps may be placed in various parts of the circulatory system of a patient, such as the left ventricle, the right ventricle, and the aorta. The pumps may be used to assist with renal perfusion when placed in the descending aorta above or below the renal arteries. In some instances it may be useful to have the pump external to the patient.

Pumps

The pumps for assisting blood circulation described herein may include a housing and a linearly reciprocating member that comprises a valve, for example, a flexible diaphragm, valve cone, umbrella structure, or inverted umbrella structure disposed within the housing. The housing may be expandable and include an interior surface, an expanded configuration, and a collapsed configuration. A sheath, which may be concentrically disposed about the housing, may maintain the housing in the collapsed configuration during advancement to a target location. Upon reaching the target location, the sheath may be retracted to allow expansion of the housing to the expanded configuration. The diameter of the sheath may vary depending on the diameter of the pump housing, which in turn may depend on such factors as whether the pump is located within the body or external to the body, indication of use, patient age or size, etc. In variations in which the pump is used within the body, and specifically within an artery, it may be beneficial for the sheath to be relatively small and flexible. For example, the diameter of the sheath may be about 9 F, about 10 F, about 11 F, about 12 F, about 13 F, about 14 F, or any diameter from about 9 F to about 14 F, including all values and sub-ranges therein. Additionally, when the valve member is a flexible diaphragm, the flexible diaphragm may have an extended configuration and a collapsed configuration, and may include a diaphragm body and a rim. Likewise, when the valve member is a valve cone, the valve cone may have an expanded configuration and a collapsed configuration, and may include a layer having a plurality of flaps that allow blood flow into the housing during the fill stroke but prevents blood flow through the valve cone during the pump stroke. A bearing within the expandable housing may also be provided to contain movement of the flexible diaphragm or valve cone within the housing.

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The pumps may also include an actuator coupled to the valve member (e.g., a flexible diaphragm, a valve cone, an umbrella structure, or an inverted umbrella structure) via a support element, which may be configured to linearly reciprocate the valve member within the housing to generate a fill stroke and a pump stroke of a pumping cycle. The rim of the valve member may be configured to maintain contact with the interior surface of the housing during the pump stroke. However, the support elements may generally be sized and/or shaped so that they do not contact the inside surface of the housing while they linearly reciprocate within the housing. The pumps may be driven by an external linear motor drive and linear motor controller, which may be situated at the proximal end of a catheter external to the patient. The linear motor drive may be operatively coupled to the pump by a cable or other actuator. Furthermore, the pumps may be powered by AC or DC sources.

Housing

In general, the housing of the pump comprises a body, a proximal end, and a distal end. Additionally, the housing may be expandable and include an expanded configuration and a collapsed configuration, as previously stated. The housing may define a chamber for collecting and holding blood until moved out by a pump stroke, and may comprise a support or scaffold and a covering. The housing may be advanced to a target location within the circulatory system of a patient in the collapsed configuration. Upon reaching the target location, the housing may then be expanded to the expanded configuration to provide a chamber for collection of the blood to be pumped. The housing chamber may have a diameter ranging from about 12 mm to about 30 mm in its expanded configuration, including all sub-ranges therein. For example, the housing chamber may have a diameter of about 12 mm, about 13 mm, about 14 mm, about 15 mm, about 16 mm, about 17 mm, about 18 mm, about 19 mm, about 20 mm, about 21 mm, about 22 mm, about 23 mm, about 24 mm, about 25 mm, about 26 mm, about 27 mm, about 28 mm, about 29 mm, or about 30 mm in its expanded configuration. The diameter may be selected based on such factors as the location at which the housing will reside, the age of the patient, and whether other features, e.g., a cannula, coaxial catheter, skirt, etc., are utilized with the housing. Furthermore, the housing chamber may have a length ranging from about 2.5 cm to about 4.5 cm in its expanded configuration, including all values and sub-ranges therein. For example, the housing chamber may have a length of about 2.5 cm, about 3.0 cm, about 3.5 cm, about 4.0 cm, or about 4.5 cm in its expanded configuration. In some variations, and as shown in FIG. 37, the expandable housing **2100** may have a chamber diameter **2102** of about 20 mm and a chamber length **2104** of about 2.9 cm. The cannula length **2108** may be about 1.3 cm. Cannulas of the pump devices are further described below. With these measurements, the total length of the pump residing in the heart below the aortic valve **2106** may be about 8.8 cm.

The support or scaffold may also include a proximal end and a distal end. The scaffold may be formed from braided, woven, and/or coiled filaments, and may be made from various materials. For example, scaffold materials may include biocompatible polymers and metals comprising stainless steel, titanium, or alloys thereof. For example, the scaffold may comprise a nickel-titanium alloy (Nitinol). With respect to the proximal and distal ends of the scaffold, they may be tapered, blunt, or straight. Furthermore, the distal end of the scaffold may include an inlet for blood flow during the pump stroke. The proximal end of the scaffold may include an outlet for blood flow during the pump stroke.

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In one variation, the scaffold may be a self-expanding stent. In other variations, the scaffold comprises a plurality of struts, which may range in number from 10 to 24. For example, the scaffold may include 10 struts, 11 struts, 12 struts, 13 struts, 14 struts, 15 struts, 16 struts, 17 struts, 18 struts, 19 struts, 20 struts, 21 struts, 22 struts, 23 struts, or 24 struts.

The housing may further comprise a covering, coating, or layer configured to block the flow of blood. The covering, coating, or layer may be provided on the entire scaffold or on a section or portion of the scaffold. In one variation, the covering or layer may comprise a polymer, and may thus form a polymer layer. The polymer layer may be overmolded on the scaffold such that scaffold is embedded within the polymer layer. In some variations, the scaffold may be positioned within the center of the polymer layer, while in other variations, the scaffold may be positioned toward an inner or outer edge of the polymer layer. Embedding or otherwise entirely covering the scaffold with the polymer layer may provide the expandable housing with a smooth interior surface. The polymer layer may comprise an elastomeric polymer such as, but not limited to, silicone, polyester, polyurethane, or a combination thereof. Alternatively, the covering or layer may comprise a fabric, and may thus form a fabric layer. In these variations, the expandable housing may include a fabric layer coupled to the scaffold, usually to an interior surface of the scaffold. The fabric layer may be coupled to the scaffold by any suitable means, such as, for example stitching the fabric layer to the scaffold at one or more points (e.g., a plurality). The stitch points may be specifically selected such that the fabric layer forms a smooth surface (e.g., on the interior of the housing) so as not to disrupt the interface between the flexible diaphragm and the housing. In other variations, the fabric layer may be coupled to the scaffold using an adhesive such as an acrylic adhesive, a cyanoacrylate adhesive, or a silicone adhesive. Non-limiting examples of materials that may be used as the fabric layer include a woven material such as buckram or a material woven from polyester fibers. A film or sheet of non-woven material such as Mylar® plastic film may also be used.

In some instances, the housing of the pump (e.g., the covering or layer) may include a plurality of openings or perforations. The number of openings utilized may range from about 2 to about 25, including all values and sub-ranges therein. For example, the expandable housing may include 2 openings, 3 openings, 4 openings, 5 openings, 6 openings, 7 openings, 8 openings, 9 openings, 10 openings, 11 openings, 12 openings, 13 openings, 14 openings, 15 openings, 16 openings, 17 openings, 18 openings, 19 openings, 20 openings, 21 openings, 22 openings, 23 openings, 24 openings, or 25 openings. The openings may be equally or unequally spaced on a portion of the housing, and/or arranged in a pattern on a portion of the housing. Additionally, the plurality of openings may have a diameter ranging from about 0.10 mm to about 6.50 mm, including all values and sub-ranges therein. For example, the diameter may be about 0.10 mm, about 0.5 mm, about 1.0 mm, about 1.5 mm, about 2.0 mm, about 2.5 mm, about 3.0 mm, about 3.5 mm, about 4.0 mm, about 4.5 mm, about 5.0 mm, about 5.5 mm, about 6.0 mm, or about 6.5 mm. The plurality of openings in the expandable housing may have the same diameter or different diameters. Furthermore, the plurality of openings may have any suitable shape, for example, circular, ovoid, or slot-like. In variations comprising slots, the slots may be

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linear, v-shaped, or arcuate in shape. In one variation, the housing includes four openings evenly spaced about the housing.

When the housing includes openings or perforations, a skirt may be coupled to the expandable housing in a manner that covers, surrounds, or otherwise overlies the plurality of openings to assist in generating retrograde blood flow directed toward the patient's head during the pump stroke of a pumping cycle. The retrograde blood flow may help provide adequate perfusion of arteries branching from the aortic arch, for example, the carotid arteries and subclavian arteries. The ability to maintain adequate perfusion of the subclavian artery may prevent flow reversal from the vertebralbasilar artery to the subclavian artery, a phenomenon known as "subclavian steal." The combination of the number of openings and opening diameter may provide an amount of open surface area on the housing for retrograde blood flow. Additionally, the skirt may be configured to adjust the amount of open surface area for retrograde flow by adjusting the number of patent (open) and closed openings. In general, a larger amount of open surface area may provide more retrograde blood flow toward the head and heart of the patient, and a smaller amount of open surface area may provide a greater amount of antegrade blood flow to the body. In some variations, a mechanism that lifts, opens, or flares the skirt off the external surface of the housing may be provided. For example, a tether may be coupled to the skirt, e.g., around the external surface of the skirt, and configured to open and close the skirt against the housing similar to how a noose can be tightened and loosened. The amount of opening or closing may be adjusted using a rotatable dial disposed, e.g., on a console external to the patient.

The skirt may have any suitable shape that directs blood back toward the head and heart (e.g., cylindrical or frustoconical), and may be coupled to the housing in various ways. In one variation, the skirt may be a separate component from the housing and may be attached to the housing by any suitable means, such as, for example, friction fit or using an adhesive. In another variation, the skirt may be integral with the housing (e.g., the two may be formed integrally, such as, by molding the two as a single component). The skirt may be made from the same materials as the housing. For example, the skirt may comprise a mesh made from stainless steel, titanium, or alloys thereof (e.g., Nitinol), and a polymer or fabric layer. The length of the skirt may also vary, and range from about 0.32 cm (0.125 inch) to about 1.90 cm (0.750 inch).

The housing may or may not be associated with a cannula, as further described below. Referring to FIG. 33, pump 1700 is shown positioned in the descending aorta 1702, above the renal arteries 1704. The pump 1700 may include a valve member 1706 within a housing 1708 that linearly reciprocates to increase perfusion of the kidneys 1710. In this variation, the housing 1708 may lack a cannula.

55 Cannula

In some variations, the pumps may include a cannula comprising an elongate body, a proximal end, a distal end, and a lumen running therethrough. The cannula may be coupled to the housing as a separate component, or be integrally formed as an extension thereof. Depending on the placement of the housing, the cannula may be coupled or extend from the proximal or distal end of the housing. For example, when the housing resides within the left ventricle, a cannula may extend from the proximal end of the housing such that it traverses the aortic valve and extends into the ascending aorta. In this variation, the cannula may have a smaller diameter than the housing in its expanded configuration.

ration, and thus may aid positioning of the pump across the aortic valve. In other variations, the pumps may include a cannula extending from the distal end of the housing. For example, when the housing resides in the aorta, a cannula may extend from the distal end of the housing such that it traverses the aortic valve to extend into the left ventricle. In further variations, the housing may not have a cannula extending therefrom. In these instances, the housing may reside within any portion of the aorta, for example, the thoracic aorta or the abdominal aorta, or in a vein, for example, the inferior vena cava. The cannula may also be expandable and comprise an expanded configuration and a collapsed configuration.

Like the housing, the cannula may comprise a covering, coating, or layer configured to block the flow of blood. When both the housing and the cannula include a covering, coating, or layer, the length of the covering, coating, or layer may range from about 4.0 cm to about 10 cm, including all values and sub-ranges therein. For example, the covering, coating, or layer may have a length of about 4.0 cm, 4.5 cm, about 5.0 cm, about 5.5 cm, about 6.0 cm, about 6.5 cm, about 7.0 cm, about 7.5 cm, about 8.0 cm, about 8.5 cm, about 9.0 cm, about 9.5 cm, or about 10 cm.

Cannulas of various lengths may be used. For example, short, medium, or long cannulas may be used. When a short cannula is employed, the length of the cannula may range from about 2.5 cm to about 5.0 cm in its expanded configuration, including all values and sub-ranges therein. For example, the length of the short cannula may be about 2.5 cm, about 3.0 cm, about 3.5 cm, about 4.0 cm, about 4.5 cm, or about 5.0 cm in its expanded configuration. When a medium length cannula is used, the length of the cannula may range from about 25 cm to about 30 cm in its expanded configuration, including all values and sub-ranges therein. For example, the length of the medium cannula may be about 25 cm, about 26 cm, about 27 cm, about 28 cm, about 29 cm, or about 30 cm in its expanded configuration. When a long cannula is used, the length of the cannula may range from 35 cm to about 40 cm in its expanded configuration, including all values and sub-ranges therein. For example, the long cannula may be about 35 cm, about 36 cm, about 37 cm, about 38 cm, about 39 cm, or about 40 cm in its expanded configuration. In some variations, a pump may be provided with each of a short, a medium, and a long cannula and a user may select the appropriate cannula based on desired use of the pump. It should be appreciated, that in some instances, other cannula lengths may also be used. For example, the length of the cannula may range from about 0.5 cm to about 10 cm in its expanded configuration, including all values and sub-ranges therein. For example, the length of the cannula may be about 0.5 cm, about 1.0 cm, about 1.5 cm, about 2.0 cm, about 2.5 cm, about 3.0 cm, about 3.5 cm, about 4.0 cm, about 4.5 cm, about 5.0 cm, about 5.5 cm, about 6.0 cm, about 6.5 cm, about 7.0 cm, about 7.5 cm, about 8.0 cm, about 8.5 cm, about 9.0 cm, about 9.5 cm, or about 10 cm in its expanded configuration. The diameter of the cannula may also range from about 5.0 mm to about 15 mm in its expanded configuration, including all values and sub-ranges therein. For example, the cannula diameter may be about 5.0 mm, about 6.0 mm, about 7.0 mm, about 8.0 mm, about 9.0 mm, about 10 mm, about 11 mm, about 12 mm, about 13 mm, about 14 mm, or about 15 mm.

In some variations, the pump may include a housing chamber having a length of about 3.8 cm and diameter of about 20 mm in its expanded configuration, and a cannula having a length of about 4.8 cm and diameter of about 8.0 mm in its expanded configuration. In other variations, the

pump may include a housing chamber having a length of about 3.5 cm and a diameter of about 20 mm in its expanded configuration, and a cannula having a length of about 2.2 cm and a diameter of about 8.0 mm in its expanded configuration. In further variations, the pump may include a housing chamber having a length of about 2.8 cm and a diameter of about 20 mm in its expanded configuration, and a cannula having a length of about 1.3 cm and a diameter of about 8.0 mm in its expanded configuration.

Coaxial Catheter

As mentioned above, in some variations the pump may be disposed external to the body, for example, within a console at the patient's bedside. In these variations, the pump may further comprise a coaxial catheter. A first end of the coaxial catheter may be coupled to the housing of the pump via a connector or adapter and the opposite (second) end of the coaxial catheter may be inserted into the patient such that blood flows between the patient and the housing. The coaxial catheter may have an outside diameter between about 10 F. and about 18 F, including all values and sub-ranges therein. For example, the outside diameter of the coaxial catheter may be about 10 F, about 11 F, about 12 F, about 13 F, about 14 F, about 15 F, about 16 F, about 17 F, or about 18 F. The coaxial catheter may include an inflow lumen and an outflow lumen. In some variations, the outflow lumen may be concentrically disposed about the inflow lumen. In other variations, the inflow and outflow lumens may extend parallel to one another within the coaxial catheter. The inflow lumen may generally have an internal diameter between about 7 F and about 14 F.

The inflow and/or outflow lumens of the coaxial catheter may be flushed, e.g., with sterile saline or heparinized saline. Flushing may be performed at any time, but is generally performed prior to use of the coaxial catheter. The fluid for flushing the coaxial catheter may be introduced into one or more of the catheter lumens by various types of connectors, for example, Y connectors or two or three way connectors. Other types of catheter connectors and fittings may also be used. Flushing around the coaxial catheter site may also be performed around the site of insertion into the body.

Valve Cone

The linearly reciprocating member of the pumps described herein may include a valve member such as a valve cone. The valve cone may be disposed within the expandable housing and may include a plurality of material layers coupled to a support member. The support member may be an expandable frame. However, in some variations, a single layer of material may be coupled to the support member. As previously mentioned, the valve cone may have an inlet side that faces the inlet of the expandable housing, and an outlet side that faces the outlet of the expandable housing. The plurality of material layers may include mesh layers, flow control layers, or a combination thereof. Any number of material layers may be used, as long as at least one flow control layer is included. The flow control layer generally includes a plurality of flaps that open when blood is pulled into the expandable housing during the fill stroke, and which close when blood is moved out of the expandable housing during the pump stroke. The mesh layer may be disposed between the flow control layer and the expandable frame and used to support the flow control layer such that when pressure against the flaps is applied during the pump stroke, the flaps are not pushed or bent through the openings in the expandable frame. Thus, the mesh layer may help maintain the flaps in the closed configuration during the pump stroke when blood is moved out of the housing via the housing outlet. However, during the fill stroke, the mesh

layer permits blood to flow from the housing inlet through the holes in the mesh and then through the flaps, transitioning them to their open configuration so that blood may move to the outlet side of the valve cone.

Woven fabrics or elastomeric polymers may be used to form the mesh layer. Exemplary elastomeric polymers include without limitation, a silicone, a polyester, a polyurethane, a fluoropolymer, or a combination thereof. The thickness of the mesh layer may range from about 0.03 mm to about 0.05 mm, including all values and sub-ranges therein. The size and shape of the mesh openings may also vary and may depend on the size and shape of the flaps in the flow control layer given their supportive function, as described above. With respect to shape, the mesh openings may be circular, triangular, square, rectangular, or diamond shaped, etc.

The material layers may be coupled to the expandable frame in any suitable manner, for example, by stitching, suturing, or embroidering, by use of an adhesive, by heat sealing, or by welding. The material layers may be coupled to the expandable frame at a plurality of attachment points on the frame. The expandable frame may have an expanded configuration and a collapsed configuration, and comprise stainless steel, nickel, titanium, or alloys thereof (e.g., nitinol). In one variation, the expandable frame is made from a laser cut nitinol tube. The expandable frame may have a first end that couples to the actuator of the pump, and a shaped second end that couples to the material layers of the valve cone. In general, the shape of the valve cone corresponds to the shape of the expandable frame. Although the expandable frame typically has a conical shape, any shape capable of being collapsed to permit advancement through the cannula may be used. When the expandable frame is conically shaped, the plurality of material layers (e.g., the mesh and flow control layers) may also be conically shaped.

The flow control layer of the valve cone may also be formed from various polymers, for example, an elastomeric polymer as stated above, or from Mylar® plastic film. The flow control layer may include a plurality of flaps having an open configuration and a closed configuration. In general, the plurality of flaps are in the open configuration during the fill stroke, and in the closed configuration during the pump stroke. The flow control layer may be cut to create a plurality of flaps, which may be of any suitable size and shape that allows blood to flow into the housing during the fill stroke. For example, the flaps may have a semi-circular shape, an arc shape, a circular shape, a triangular shape, a diamond shape, a square shape, or a rectangular shape. Any suitable number of flaps in the flow control layer may also be employed. The number of flaps may range from 2 to 20. For example, 2 flaps, 3 flaps, 4 flaps, 5 flaps, 6 flaps, seven flaps, 8 flaps, 9 flaps, 10 flaps, 11 flaps, 12 flaps, 13 flaps, 14 flaps, 15 flaps, 16 flaps, 17 flaps, 18 flaps, 19 flaps, or 20 flaps may be included. In one variation, a flow control layer including 15 flaps may be useful. The valve cone may be configured such that a greater number of flaps are included when they are smaller in size, and a smaller number of flaps are included when they are larger in size. When the flaps are semi-circular in shape, they may have a radius ranging from about 0.50 mm to about 3.0 mm, including all values and sub-ranges therein.

When the cone valve is conically shaped, the flow control layer is generally also conically shaped. Here the material of the flow control layer may first be provided as a circle with center cut out and a slit extending from the cut out to the periphery of the circle (e.g., see 28A). The slit provides a free edge so that the layer may later be rolled to form a cone

shape. Next, the flaps may be formed by laser cutting or stamping the flap shapes into the flow control layer. The flaps may have any suitable size and shape, as previously stated. In one variation, a rim is then created at the periphery of the circle by rolling the edge of the flow control layer upon itself to create thickness at the periphery and stitching, heat sealing, gluing, etc., the rolled edge to maintain the thickness in that area. In another variation, the edge may be rolled over an O-ring to form the rim. In a further variation, the rim is a separate component from the flow control layer, and includes an O-ring that is stitched, heat sealed, glued, bonded, etc., to the edge of the flow control layer. After the rim is formed, a free edge of the circular flow control layer is rolled to shape it into a cone. The rim may help create a seal between the rim of the flow control cone and the interior surface of the housing during the pump stroke. A conically shaped mesh layer may be formed by the same process except that a rim need not be included.

In addition to a rim, the flow control layer may include a body. The body and the rim may be made from the same material or from different materials. Additionally, the body and the rim may be separate components or integrally formed with one another. When provided as separate components, the body may be formed from an elastomeric polymer or from Mylar® plastic film, and the rim may be an O-ring. The peripheral edge of the flow control layer may be rolled over the O-ring to form the rim. The thickness of the rim may be greater than the thickness of the body. The body may have a thickness ranging from about 0.03 mm to about 0.05 mm, including all values and sub-ranges therein. The rim may have a thickness ranging from about 0.20 mm to about 1.5 mm, including all values and sub-ranges therein. For example, the rim may have a thickness of about 0.20 mm, about 0.30 mm, about 0.40 mm, about 0.50 mm, about 0.60 mm, about 0.70 mm, about 0.80 mm, about 0.90 mm, about 1.0 mm, about 1.1 mm, about 1.2 mm, about 1.3 mm, about 1.4 mm, or about 1.5 mm.

Flexible Diaphragm

In some variations, the linearly reciprocating member of the pumps described herein may include a flexible diaphragm as the valve member. The flexible diaphragm may be contained within the housing. The flexible diaphragm may have a collapsed configuration and an extended configuration, and may linearly reciprocate within the housing. In the collapsed configuration, the flexible diaphragm may have a smaller diameter than when in the extended configuration to allow advancement through the vasculature. Once at the target location in the patient, the flexible diaphragm may be transformed to its extended configuration to move blood from an inlet of the housing, through a body of the housing, to and through an outlet of the housing, and create the pressure needed for pumping blood. The flexible diaphragm may be coupled to a support member, which in turn is coupled to an actuator that linearly reciprocates the flexible diaphragm within the housing. The support member may be an expandable frame that is conically shaped (shown in FIG. 34) or a tine support, as further described below. Coupling to the expandable frame may be accomplished in any suitable manner, for example, by stitching, suturing, or embroidering, by use of an adhesive, by heat sealing, or by welding. The flexible diaphragm may include a diaphragm body and a rim. In some variations, the flexible diaphragm may comprise an elastomeric polymer. Non-limiting examples of elastomeric polymers include but are not limited to: silicone, polyester, polyurethane elastomers, fluoropolymers, or a combination thereof. Some variations of the flexible diaphragm comprise polytetrafluoroethylene

(PTFE) as the elastomeric polymer. The body and rim of the flexible diaphragm may comprise the same material or different materials. In some instances, the diaphragm body and rim are integrally formed.

The material and/or thickness of the diaphragm body and rim may be selected so that the flexible diaphragm is able to bend and allow blood to flow around it during a fill stroke, but resilient enough to prevent the flexible diaphragm from everting or folding upon itself during a pump stroke. Furthermore, the material and/or thickness of the flexible diaphragm may be sufficiently rigid so that the pressure needed to effect a pump stroke is generated as well as to prevent stretching of the diaphragm body. In one variation, the flexible diaphragm may maintain its shape during the pumping cycle by including a rim thicker than the diaphragm body.

In some variations, thicknesses of the diaphragm body may range from about 0.03 mm to about 0.3 mm, including all values and sub-ranges therein. For example, diaphragm thickness may be about 0.03 mm, about 0.04 mm, about 0.05 mm, about 0.06 mm, about 0.07 mm, about 0.08 mm, about 0.09 mm, about 0.10 mm, about 0.20 mm, or about 0.30 mm. With respect to the rim of the diaphragm, its thickness may range from about 0.20 mm to about 1.5 mm, including all values and sub-ranges therein. For example, the rim thickness may be about 0.20 mm, about 0.30 mm, about 0.40 mm, about 0.50 mm, about 0.60 mm, about 0.70 mm, about 0.80 mm, about 0.90 mm, about 1.0 mm, about 1.1 mm, about 1.2 mm, about 1.3 mm, about 1.4 mm, or about 1.5 mm. In some variations, the rim thickness may range from about 0.5 mm to about 1.0 mm, including all values and sub-ranges therein. The thickness of the rim may be greater than the thickness of the diaphragm body, which may help the flexible diaphragm maintain its shape during the pumping cycle, as mentioned above. A greater rim thickness may also aid in creating a seal between the rim and interior surface of the housing during the pump stroke. However, in some variations, the rim and body may have equal thicknesses. The ratio of the thickness between the diaphragm body and rim may range from about 1:5 to about 1:20. The rim of the flexible diaphragm may have a width ranging from about 1.0 mm to about 2.0 mm, including all values and sub-ranges therein. In one variation, the diaphragm body may have a thickness of about 0.05 mm and the rim may have a thickness of about 0.25 mm.

Furthermore, the flexible diaphragm may have any suitable shape or geometry capable of creating a seal between the rim of the diaphragm and the interior surface of the housing during the pump stroke. For example, the flexible diaphragm may have a conical, frustoconical, or hemispherical shape when in the extended configuration. The flexible diaphragm may also comprise a plurality of ribs that may help provide more rigidity to the flexible diaphragm body. In one variation, the flexible diaphragm has a conical shape and a plurality of ribs that aid in maintaining the conical shape during a pump stroke. The plurality of ribs may be integrally formed with the diaphragm body, or they may be separate components coupled to the diaphragm body by, e.g., use of an adhesive, welding, etc. In some variations, the plurality of ribs may radiate from a center portion of the diaphragm body to the rim. The plurality of ribs may have a rib angle between a longitudinal axis of a rib of the plurality of ribs and an axis perpendicular to the actuator that ranges from about 30 degrees to about 60 degrees, including all values and sub-ranges therein. For example, the rib angle may be about 30 degrees, about 35 degrees, about 40 degrees, about 45 degrees, about 50 degrees, about 55 degrees, or about 60

degrees. The plurality of ribs may be equally spaced from one another. In some variations, the plurality of ribs may have unequal spacing from one another.

Actuator/Controller

The pumps described herein may include an actuator coupled to the valve member, usually via a support member. The valve member may be a flexible diaphragm or a valve cone. The actuator may be generally configured to linearly reciprocate the flexible diaphragm or valve cone within the housing to generate a fill stroke and a pump stroke of a pumping cycle. Exemplary actuators may include without limitation, a cable, a wire, a rod, or other actuator having the flexibility to track over a guidewire and navigate the vasculature, as well as the stiffness needed to reciprocate the flexible diaphragm during the pump and fill strokes. The linear reciprocating movement of the actuator may be generated by a linear motor drive and linear motor controller. Although the linear motor is usually situated external to the patient, in some variations, the linear motor may be implanted within the patient, e.g., in a subcutaneous pocket, or provided as part of the pump placed within the heart or vasculature of the patient.

The linear motor controller may regulate various parameters of the pumping cycle. For example, the linear motor controller may regulate the speed of linear reciprocation of the actuator and flexible diaphragm, and the length of the pump and fill strokes. The speed of linear reciprocation may be regulated by increasing or decreasing the number of pumping cycles per minute. In some variations, the number of pumping cycles per minute may be preset or adjusted to a speed that corresponds to the natural cardiac pumping cycle of a patient. In other variations, a patient parameter such as blood pressure (e.g., left ventricular pressure, left ventricular end-diastolic pressure, aortic pressure, and/or systemic blood pressure) may be preset to a target value or range, and pumping cycle parameters adjusted to meet the preset blood pressure value or range. Preset targets for blood pressure as well as pumping cycles per minute may be based on factors such as the age, height, or weight of the patient, or a combination of all of these factors. The type of heart failure a patient is diagnosed with (e.g., systolic heart failure, diastolic heart failure, right-sided heart failure, left-sided heart failure) may also be a factor when establishing the pumping cycles per minute and blood pressure target values.

In some variations, the adjustment or control of pump parameters or patient parameters (e.g., left ventricular pressure, left ventricular end-diastolic pressure, aortic pressure, and/or systemic blood pressure) may be accomplished manually, e.g., by one or more control features or buttons provided on a user interface of an external console. In other variations, pump parameters may be adjusted automatically, e.g., using a closed loop system. The closed loop system may comprise a processor and instructions stored in memory of the processor. During operation of the pump, the processor may store and/or process data from the pump and/or patient, and may execute instructions from memory to automatically adjust pump parameters based on data received from one or more sensors provided with the pump. For example, the speed of the pumping cycle may be automatically adjusted (i.e., increased or decreased) so that a preset blood pressure is met, as described above.

Various types of sensors may be employed to measure pump parameters (e.g., pump cycles per minute) and patient parameters (e.g., blood pressure and blood flow rate). Non-limiting examples of sensors include pressure sensors, flow sensors, temperature sensors, heart rate sensors, and heart

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rhythm sensors. The pressure sensors may be placed in various pump locations. In some variations, one or more pressure sensors may be mounted in or on a blood flow inlet or inlet/inflow tubing, and one or more pressure sensors may be mounted in or on a blood flow outlet, outlet/outflow tubing, or skirt of the pump. In other variations, two pressure sensors may be mounted in or on the inlets and outlets for redundancy in case one inlet and/or outlet pressure sensor fails. In further variations, one or more pressure sensors may be mounted near a blood flow inlet or inlet/inflow tubing, and one or more pressure sensors may be mounted near a blood flow outlet, outlet/outflow tubing, or skirt of the pump. The pressure sensors may be communicatively coupled to the controller such that the controller may receive measurements from the pressure sensors and may utilize those measurements to modify pump parameters, as stated above. For example, in some variations, the controller may be configured to have predetermined high blood pressure set points, low blood pressure set points and/or a predetermined target blood pressure range. The controller may be further configured to compare the measurements received from one or more of the pressure sensors to the high blood pressure set points, low blood pressure set points, and/or the predetermined desired blood pressure range and to modify one or more pump parameters (e.g., speed of reciprocation) accordingly. For example, when measurements from the pressure sensors indicate that a patient's measured blood pressure has dropped below the low set point and/or is below the desired range, the controller may increase the speed of the linear reciprocation. When measurements from the pressure sensors indicate that a patient's measured blood pressure has risen above the high blood pressure set point and/or is above the desired range, the controller may decrease the speed of the linear reciprocation to thereby reduce flow and return blood pressure back below the high set point and/or within the target range.

Tines

Some variations of the pumps described herein may also comprise a tine support as the support member. The tine support may comprise a base and a plurality of tines configured to support the flexible diaphragm in the extended configuration during the pump stroke. In other variations, as described further below in FIGS. 5-7, the tine support may be coupled to the flexible diaphragm. The plurality of tines may be flexible and/or resilient, and may have an expanded configuration and a compressed configuration. In the compressed configuration, the plurality of tines may have a smaller diameter than when in the extended configuration to allow advancement through the vasculature. Once at the target location in the patient, the plurality of tines may be expanded to a larger diameter. Furthermore, the plurality of tines may have an expanded configuration during the pump stroke of a linear pumping cycle, and a compressed configuration or partially compressed configuration during the fill stroke. The plurality of tines may be coupled to the actuator. In one variation, each of the plurality of tines may extend from a common hub or base to a free end. The hub may be configured to couple to the actuator. Furthermore, the free ends of the plurality of tines may radiate or flex outwardly when the plurality of tines move from the compressed to the expanded configuration.

The number of tines included in the plurality of tines may range from about two to about eight. For example, the plurality of tines may include two (2) tines, three (3) tines, four (4) tines, five (5) tines, six (6) tines, seven (7) tines, or eight (8) tines. In one variation, the plurality of tines includes six (6) tines. The plurality of tines may be equally

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spaced or unequally spaced from one another. With respect to materials, the plurality of tines may be made from a metal such as stainless steel, titanium, or alloys thereof, or a biocompatible polymer such as a fluoropolymer, a polyamide, polyetheretherketone (PEEK), a polyimide, a polyolefin, a polyurethane, or combinations thereof.

In one variation, the plurality of tines may comprise metal strips. The metal strips may extend from a common base at one end. At the other end, each tine of the plurality of tines has a free end. The free ends may be attached to a barrel, e.g., a short cylinder, by welding, soldering, or gluing. The barrels may provide further supportive area for the flexible diaphragm to rest against during a pump stroke to help prevent movement of the flexible diaphragm between the tines during the pump stroke. In one variation, the length of each barrel is about 1.0 mm. The tines may be made from a metal cylinder that is laser cut to form the strips.

Instead of strips, the plurality of tines may comprise a plurality of flexible first wires. Any suitable number of first wires may be employed. For example, four (4) wires, six (6) wires, eight (8) wires, ten (10) wires, or 12 (twelve) wires may be used. A plurality of holes corresponding to the number of first wires may be drilled into a base so that one end of the wires may be inserted into the holes. At the other end of the wires (free ends), a barrel may be attached in the same manner described above. The barrels may include a central hole through which a second wire is threaded. After threading through all the barrels, the ends of the second wire may be joined by soldering, welding, gluing, and the like. The second wire may be made from various materials, including but not limited to, stainless steel, spring steel (piano wire), or nitinol. In some variations, each tine of the plurality of tines may be comprised of two wires attached to the same barrel at their free ends. Thus, when the plurality of tines includes 6 (six) tines, the number of wires would be twelve (12). The second wire may provide additional flexible diaphragm support to that provided by the barrels during a pump stroke so that movement of the flexible diaphragm between the tines during the pump stroke is prevented or minimized.

Umbrella Structures

In some variations, the pumps for assisting blood circulation may include a housing comprising an interior surface and an expanded configuration, and a valve member comprising an umbrella structure disposed within the expandable housing. The umbrella structure may include a membrane having a body and a rim, a frame comprising a plurality of struts, and an anchor, and may also have an expanded configuration and a collapsed configuration. An actuator coupled to the umbrella structure may be configured to linearly reciprocate the umbrella structure within the housing. During the pump stroke and the fill stroke of the pump, the rim of the membrane may be configured to maintain contact with the interior surface of the housing. In some variations, contact may be maintained for the entire duration of the pump stroke. In other variations, contact may be maintained for a portion of the pump stroke, as long as sufficient pressure is generated to move the desired amount of blood out of the housing during the pump stroke. In further variations, for example, when high pump speeds are required, the umbrella structures may be configured such that there is a slight clearance or gap between the rim and the interior surface of the housing. The clearance gap may help to avoid the creation of undue friction in the pump. The clearance gap may also be sized so that adequate pressure may be generated for the pump stroke while also avoiding crushing or damaging red blood cells during the pump

stroke. Here the diameter of the umbrella structures in their expanded configurations may be at least about 95 percent of the diameter of the housing in its expanded configuration. For example, the umbrella structures in their expanded configurations may be at least about percent 95 percent, at least about 96 percent, at least about 97 percent, at least about 98 percent, or at least about 99 percent of the diameter of the housing in its expanded configuration.

The membrane of the umbrella structure may be coupled to the plurality of struts and entirely or partially cover the struts. The membrane may comprise an elastomeric polymer. Non-limiting examples of elastomeric polymers include silicone, polyesters, polyurethanes, fluoropolymers, or a combination thereof. Fluoropolymers that may be employed include polytetrafluoroethylene (PTFE) or expanded polytetrafluoroethylene (ePTFE). In some variations, the umbrella structure may comprise a plurality of struts and a PTFE or ePTFE membrane that has been coated onto the struts. The membrane may cover the entirety of the struts or a portion thereof, as mentioned above. In some variations, the membrane may cover a length of the strut ranging from about 0.5 cm to about 3.0 cm, including all values and sub-ranges therein. For example, the length of coverage may be about 0.5 cm, about 1.0 cm, about 1.5 cm, about 2.0 cm, about 2.5 cm, or about 3.0 cm. The body and rim of the membrane may comprise the same or different materials. In some instances, the membrane body and rim are integrally formed. Thicknesses of the membrane body may range from about 0.03 mm to about 0.3 mm. With respect to the rim of the membrane, its thickness may range from about 0.70 mm to about 1.5 mm. The thickness of the rim may be greater than the thickness of the membrane body. However, in some variations, the rim and body may have equal thicknesses.

The umbrella structure may comprise a frame including any suitable number of struts. The number of struts may range from three to ten, including all values and sub-ranges therein. For example, the number of struts may be three, four, five, six, seven, eight, nine, or ten. In one variation, the umbrella structure comprises six struts. In another variation, the umbrella structure comprises ten struts. The plurality of struts may support the membrane, and the struts may be made from stainless steel, nickel, titanium, or alloys thereof (e.g., nitinol). In one variation, the struts are made from a laser cut nitinol tube.

The struts may have any suitable shape or geometry. The struts may have one or more sections, and the one or more sections may have any suitable shape or geometry. The cross-sectional shape of the struts may be circular, ovular, triangular, square, or rectangular. The struts may have different cross-sectional shapes along their length. For example, the struts may have one or more sections with a first cross-sectional shape (e.g., circular), and one or more sections with a second cross-sectional shape (e.g., rectangular). In some instances, the struts may include three sections, two end sections and a middle section therebetween. The end sections may have a circular cross-sectional shape and the middle section may have a rectangular cross-sectional shape. The rectangular cross-sectional shape may provide the middle section with a flattened profile. In some variations, different sections of the struts may have different widths. For example, when the struts include three sections (two end and one middle section), the middle section may be wider than one or both of the two end sections. In other variations, different sections of the struts may have different thicknesses. For example, one or both end sections may have

a greater thickness than the middle section (the middle section is flatter than one or both end sections).

The distal tip of the struts may be configured to be atraumatic. In one variation, the atraumatic distal tip may be shaped to help prevent the struts from damaging the interior surface of the housing during the pump stroke. For example, the atraumatic distal tip may have a rounded shape or an ovular shape. Additionally or alternatively, one or more slits or cutouts may be provided along the length of the strut to increase strut flexibility, which may help prevent the struts from damaging the interior surface of the housing during the pump stroke. In some variations, the distal tip may include an opening that allows the flow of blood therethrough. The openings may have various sizes and shapes, which may depend on the size and shape of the distal end. For example, the opening may be shaped to be circular, ovular, square, rectangular, triangular, etc. In one variation, the opening at the distal tip is rectangular in shape. In another variation, the opening at the distal tip is circular in shape. A radiopaque marker may also be provided at any appropriate location along the length of one or more struts, for example, at the distal end of one or more struts (e.g., one third of the struts, half the struts, all of the struts). In some variations, the umbrella structure may include a bend and an opening in one or more of the struts. In some variations, inclusion of both of these features may help minimize the risk of the struts puncturing the housing during the pump stroke.

The length of the struts may range from about 1.0 cm to about 3.0 cm, including all values and sub-ranges therein. For example, the struts may have a length of about 1.0 cm, about 1.1 cm, about 1.2 cm, about 1.3 cm, about 1.4 cm, about 1.5 cm, about 1.6 cm, about 1.7 cm, about 1.8 cm, about 1.9 cm, about 2.0 cm, about 2.1 cm, about 2.2 cm, about 2.3 cm, about 2.4 cm, about 2.5 cm, about 2.6 cm, about 2.7 cm, about 2.8 cm, about 2.9 cm, or about 3.0 cm. In some variations, for example, in variations having longer length struts, the struts may extend beyond the rim of the membrane. In other variations, the struts may not extend beyond the rim and may instead be entirely covered by the membrane.

As mentioned above, in some variations, one or more of the struts may include one or more bends or curves along their length. The one or more bends may be provided at any location along the strut. For example, the one or more bends may be at the distal end (free end) of the struts and/or provided at the midpoint of the struts. The bent region of the struts may have various lengths. For example, the length of the bent region may range from about 0.2 cm to about 1.0 cm, including all values and sub-ranges therein. For example, the bent region may have a length of about 0.2 cm, about 0.3 cm, about 0.4 cm, about 0.5 cm, about 0.6 cm, about 0.7 cm, about 0.8 cm, about 0.9 cm, or about 1.0 cm.

The bends in the struts may form a bend angle of about 5 degrees to about 15 degrees with respect to the longitudinal axis of the umbrella structure, including all values and sub-ranges therein. For example, the bend angle may be about 5 degrees, about 6 degrees, about 7 degrees, about 8 degrees, about 9 degrees, about 10 degrees, about 11 degrees, about 12 degrees, about 13 degrees, about 14 degrees, or about 15 degrees. In addition to a rounded, atraumatic distal tip, the bends may be employed to prevent the struts from piercing or otherwise damaging the interior surface of the housing during the pump stroke.

The umbrella structures may further include an anchor having a proximal end and a distal end. The proximal end of the anchor may be configured to attach the struts to the linear actuator of the pump. The distal end of the anchor may be

configured to attach to the plurality of struts. In some variations, the anchor and struts are integrally formed by laser cutting from a nitinol tube. Anchor lengths may range from about 0.5 cm to about 1.5 cm, including all values and sub-ranges therein. For example, the anchor length may be about 0.5 cm, about 0.6 cm, about 0.7 cm, about 0.8 cm, about 0.9 cm, about 1.0 cm, or about 1.5 cm. The umbrella structures in some instances may include a component that facilitates collapse of the struts during the fill stroke of the pumping cycle. For example, the struts may be attached to the proximal or distal end of the anchor via a hinge, pivot, joint, or other swivel mechanism that increases flexibility of the struts at that point. Exemplary types of hinges may include without limitation, butt hinges, non-Mortise hinges, pivot hinges, and bi-fold hinges, which would be sized according to the width and/or length of the strut. A flexible connector may also be used to join the strut to the anchor. The flexible connector may include a polymer or a polymer with fiber reinforcement. The polymer may comprise a thermoplastic elastomer such as a styrenic block copolymer, a thermoplastic polyolefin, a thermoplastic polyurethane, a thermoplastic polyamide, or a thermoplastic copolyester. All of the struts or some of the plurality of struts may be attached to the anchor by a swivel mechanism or a flexible connector.

When the umbrella structure is in its expanded configuration, the plurality of struts may radially expand from the distal end of the anchor to create a strut angle with respect to the longitudinal axis of the umbrella structure. The strut angle may depend in part on the strut length, and may range from about 30 degrees to about 60 degrees, including all values and sub-ranges therein. For example, the strut angle may be about 30 degrees, about 35 degrees, about 40 degrees, about 45 degrees, about 50 degrees, about 55 degrees, or about 60 degrees.

Instead of expanding radially from the anchor, the plurality of struts may be configured to invert (e.g., fold backwards) about the anchor to form, e.g., a conical shape. In such configurations, the plurality of struts may be attached to the proximal end of the anchor. In contrast, when the plurality of struts expand radially from the anchor, the actuator may generally be attached to the distal end of the anchor. A membrane may also entirely or partially cover the plurality of inverted struts.

In some variations, for example when longer struts are employed, the struts may form a cage structure. The struts of the cage may be fixed or anchored to the linear actuator at one end and slidable over the linear actuator at the other end. With this configuration, as shown in FIG. 38, the cage expands to an expanded configuration during the pump stroke of the pumping cycle, and collapses down to a collapsed configuration during the fill stroke. Referring to FIG. 38, the plurality of struts 2200 may include a proximal end 2202, a distal end 2204, and a middle section 2206. When the cage 2208 is in the expanded configuration (as shown in FIG. 38), the middle section 2206 of the struts 2200 may be flat and also may form a flattened region of the cage 2208. The proximal ends 2202 of the struts 2200 may be fixedly attached to a linear actuator (not shown). The distal ends 2204 are not attached to the linear actuator, and thus may slide along the linear actuator during reciprocation of the cage 2208. A membrane (not shown) may be coupled to the cage 2208 and cover any suitable length of the struts 2200 that allows a pump stroke to be generated.

Any component of the pumps described herein may be coated. For example, one or more of the cannula, expandable housing, expandable frame, and flexible diaphragm may be coated. One or more tines, or one or more struts may also be

coated. Pump components may be entirely or partially coated. The coating may provide increased lubricity and/or wettability to portions of the pump that are coated, or may provide anti-fouling, antiproliferative, or antimicrobial properties to the coated pump components.

The thickness of the coating may vary depending on the pump component being coated. In some variations, when the expandable housing includes a coating, the thickness of the coating may range from about 0.0025 cm to about 0.010 cm (about 0.001 inch to about 0.004 inch), including all values and sub-ranges therein. For example, the coating thickness may be about 0.0025 cm, about 0.003 cm, about 0.004 cm, about 0.005 cm, about 0.006 cm, about 0.007 cm, about 0.008 cm, about 0.009 cm, or about 0.010 cm. When the flexible diaphragm is coated, the coating thickness may range from about 0.0013 cm to about 0.0025 cm (about 0.0005 inch to about 0.001 inch), including all values and sub-ranges therein. For example, the coating thickness may be about 0.0013 cm, about 0.0015 cm, about 0.0020 cm, or about 0.0025 cm.

The coatings may generally comprise a polymeric material. Exemplary polymeric materials may include without limitation, hydrophilic polymers, hydrophobic polymers, or mixtures of these two types of polymers. The coating may be a single layer on the pump component, or may include a plurality of layers. When multiple layers are employed, each layer may be made from the same polymer or from different polymers.

Examples of hydrophilic polymers that may be used to form the coating include, but are not limited to, polyurethanes, including polyether polyurethanes, polyester polyurethanes, polyurethane-ureas, and their copolymers; polyvinylpyrrolidones; polyvinyl alcohols; polyethylene glycols and their copolymers; polypropylene glycols and their copolymers; polyoxyethylenes and their copolymers; polyacrylic acid; polyacrylamide; carboxymethyl cellulose; cellulose and its derivatives; dextrans and other polysaccharides; starches; guar; xanthan and other gums and thickeners; collagen; gelatins; and other biological polymers.

Examples of hydrophobic polymers that may be used to form the coating include, but are not limited to, fluoropolymers such as polytetrafluoroethylene (PTFE) and expanded polytetrafluoroethylene (ePTFE), polyvinyl chloride (PVC), polyvinylacetate, poly(ethylene terephthalate), silicone, polyesters, polyamides, polyureas, styrene-block copolymers, polymethyl methacrylate, acrylic-butadiene-styrene copolymers, polyethylene, polystyrene, polypropylene, natural and synthetic rubbers, acrylonitrile rubber, and mixtures and copolymers of any of the foregoing. In one variation, the coating includes polytetrafluoroethylene (PTFE) as the polymeric material. In another variation, the coating comprises expanded polytetrafluoroethylene (ePTFE) as the polymeric material.

Pump Systems

Systems for pumping blood are also described herein. The systems may generally include a pump, where the pump comprises an expandable housing having an interior surface and an expanded configuration. A valve including a rim may be disposed within the expandable housing, and may have an expanded or extended configuration, and a collapsed configuration. The pump may also include an actuator coupled to the valve that linearly reciprocates the valve within the housing to generate a pump stroke and a fill stroke of the pumping cycle. During the pump stroke, the rim of the valve member may be configured to maintain contact with the interior surface of the housing. In some variations, contact may be maintained for the entire duration of the pump

stroke. In other variations, contact may be maintained for a portion of the pump stroke, as long as sufficient pressure is generated to move the desired amount of blood out of the housing during the pump stroke. In further variations, for example, when high pump speeds are required, the valve members may be configured such that there is a slight clearance or gap between the rim and the interior surface of the housing. The clearance gap may help to avoid the creation of undue friction in the pump. The clearance gap may also be sized so that adequate pressure may be generated for the pump stroke while also avoiding crushing or damaging red blood cells during the pump stroke. Here the diameter of the valve members in their extended or expanded configurations may be at least about 95 percent of the diameter of the housing in its expanded configuration. For example, the valve members in their extended or expanded configurations may be at least about percent 95 percent, at least about 96 percent, at least about 97 percent, at least about 98 percent, or at least about 99 percent of the diameter of the housing in its expanded configuration.

Additionally, the systems may include a console located external to the patient that contains a controller configured to regulate the actuator. A user interface may be coupled to the controller and configured to manually set or adjust a pump parameter or a patient parameter and/or display the pump and patient parameters. The user interface may be a display that forms part of the console that houses the linear actuator. The console may be a stationary component of the system, or a mobile component when coupled to a wheeled cart or other rolling base.

Exemplary pump parameters include without limitation, pump cycles per minute and duration of the pump cycle. When setting or adjusting the duration of the pump cycle, the duration of either the fill stroke or the pump stroke may be set or adjusted. Non-limiting examples of patient parameters include age, height, weight, left ventricular pressure, left ventricular end-diastolic pressure, aortic pressure, and systemic blood pressure.

Referring to FIG. 32A, an exemplary console **1600** is shown coupled to a mobile base **1602**. The console **1600** may be removably coupled to the mobile base **1602**, and may be lifted off the base **1602** when desired. Additionally, the mobile base **1602** may include a handle **1604** and a storage compartment **1606** for holding pump components. The console **1600** may include areas **1608** for accessing and connecting the drive line/cable. A user interface **1610** comprising a display **1612** may also be provided on the console **1600**. The display **1612** may show various pump and patient parameters, and may include a touch screen and/or buttons (e.g., touch-sensitive buttons). For example, as shown in FIG. 32B, pump parameters such as cycles per minute (CPM) (also referred to as pump cycles per minute herein), total number of pump cycles, and run time of the pump are displayed. Patient parameters such as blood flow, left ventricular pressure, aortic pressure, and blood pressure may also be displayed. Touch-sensitive buttons **1614** may be used to manually set or adjust, e.g., increase or decrease, the pump cycles per minute. An audible and/or visual alert may be issued when any pump parameter or patient parameter falls above or below a preset value, or above or below a range of preset values.

In use, the pump of the systems may be advanced to a target location within the circulatory system of a patient. The pumps may comprise an expandable housing including an interior surface, an expanded configuration and a collapsed configuration, and a valve member comprising a rim disposed within the expandable housing, as described above.

Once at the target location, the expandable housing may be expanded from the collapsed configuration to the expanded configuration. Pump parameters and/or patient parameters may be determined and the valve member may be linearly reciprocated within the expandable housing according to those parameters to generate a fill stroke and a pump stroke. During the pump stroke, contact between the rim of the valve member and the interior surface of the expandable housing may be maintained. In some variations, the valve members may not contact the interior surface of the housing and be configured such that there is a slight clearance or gap between the rim and the interior surface of the housing, as mentioned above. As also mentioned above, pump parameters may include pump cycles per minute, duration of the pump cycle, or both. When setting or adjusting the duration of the pump cycle, the duration of either the fill stroke or the pump stroke may be set or adjusted, or both may be set or adjusted. When pump parameters are determined, they may be based on a patient parameter such as age, height, weight, left ventricular pressure, left ventricular end-diastolic pressure, aortic pressure, or systemic blood pressure.

The pump parameters and patient parameters may be displayed on a user interface. The parameters may be continuously or intermittently monitored, and the measurements continuously or intermittently displayed on the user interface. The user interface may be a display that forms part of the console that houses the linear actuator. The console may be a stationary component of the system, or a mobile component when coupled to a wheeled cart or other rolling base, as mentioned above. Pump and patient parameters may be manually adjusted via buttons on the user interface. In some instances, the display of the user interface includes touch-sensitive buttons for manually adjusting the parameters. In other instances, the pump parameter may be automatically adjusted based on the patient parameter. The automatic adjustment may be accomplished by the controller.

The pump of the systems may be advanced to a target location within an artery. When the artery is the aorta, the target location may be the ascending aorta, the aortic arch, the thoracic aorta, the descending aorta, or the abdominal aorta. Pumps may also be advanced to a target location within a vein. The vein may be the inferior vena cava. When advanced within the inferior vena cava, the target location may reside between a hepatic vein and the right atrium. At this location, the pump may increase circulation from the liver or from a lower extremity. Another target location for the pump may be above or below the renal veins.

When the pumps are positioned such that they traverse the aortic valve, the length of the pumps below the aortic valve (and within the left ventricle) may range from about 4.0 cm to about 10 cm, including all values and sub-ranges therein. For example, the length of the pumps below the aortic valve may be about 4.0 cm, about 4.5 cm, about 5.0 cm, about 5.5 cm, about 6.0 cm, about 6.5 cm, about 7.0 cm, about 7.5 cm, about 8.0 cm, about 8.5 cm, about 9.0 cm, or about 10 cm. These lengths may include the length of the housing chamber and all or part of an associated cannula. Total pump length from the distal tip of the device to the proximal end of an associated cannula may range from about 5.0 cm to about 14 cm, including all values and sub-ranges therein. For example, the total pump length may be about 5.0 cm, about 5.5 cm, about 6.0 cm, about 6.5 cm, about 7.0 cm, about 7.5 cm, about 8.0 cm, about 8.5 cm, about 9.0 cm, about 9.5 cm, about 10 cm, about 10.5 cm, about 11 cm, about 11.5 cm, about 12 cm, about 12.5 cm, about 13 cm, about 13.5 cm, or about 14 cm.

Additional Exemplary Variations

An exemplary pump is shown in FIG. 1. As shown there, pump 10 includes an elongated outer sheath 11 having an interior end 12 supporting a bearing 13. An expandable housing 25 (better seen in FIG. 3) is received within the interior of outer sheath 11 and holds bearing 13 in a fixed attachment. An inner sheath 16 extends through the interior of outer sheath 11 from bearing 13. Tine support 15 having a plurality of tines 20 for supporting a flexible diaphragm 30 is disposed within inner sheath 16 in a collapsed configuration. An actuator (drive cable) 40 is coupled to tine support 15 by a fixed attachment at one end and extends through the interior of inner sheath 16 to attach to linear motor 19 within linear motor drive 18 at its other end.

Referring to FIGS. 5, 6 and 7, another variation of the pump is illustrated. In these figures, pump 100 is substantially identical to pump 10 both in structure and function with the difference being found in the configuration of the expandable housings. In comparison to FIGS. 3 and 4, it will be noted that pump 10 utilizes an expandable housing 25 having a cannula or an extended portion 28 extending therefrom. Turning to FIG. 5, it will be noted that pump 100 utilizes an expandable housing 60 that does not have a cannula or extended portion 28. Apart from this difference in structure of the expandable housings, pumps 10 and 100 are substantially identical.

More specifically, FIG. 5 sets forth a section view of the pulsatile pump portion (expandable housing and flexible diaphragm) of pump 100. FIG. 5 shows the expandable housing 60 in its collapsed configuration. The expandable housing 60 may be advanced from within an outer sheath 11 (shown in FIG. 4). Expandable housing 60 includes an inlet (scaffold portion) 63 proximate end 62, which in turn supports a bearing 13 in a fixed attachment. Expandable housing 60 further includes an outlet (scaffold portion) 64 and a chamber 61 within expandable housing 60. The chamber 61 may be formed by overmolding a portion of the scaffold of expandable housing 60 with a polymer layer or coupling a fabric layer to the scaffold, as previously described. Pump 100 further includes an inner sheath 16 which extends through outlet 64 and chamber 61 to the interior end of bearing 13. Tine support 15 is received within inner sheath 16 and includes a plurality of tines 20. A drive cable 40 extends through inner sheath 16 and is coupled to tine support 15. A flexible diaphragm 30 is also coupled to tine support 15.

In the configuration shown in FIG. 5, pump 100 has initiated the expansion of expandable housing 60 while tine support 15 remains captivated within inner sheath 16 in the compressed configuration. Thus, the next step in configuring pump 100 for operation requires withdrawing inner sheath 16 to allow the plurality of tines 20 to expand and assume their operational expanded configuration.

FIG. 6 sets forth a section view of the pulsatile pump portion of pump 100. As mentioned above, FIG. 6 shows pump 100 at a point intermediate between the compacted configuration of FIG. 5 and the operational configuration of FIG. 7. Pump 100 includes an expandable housing 60. Expandable housing 60 includes an inlet 63 proximate end 62, which in turn supports a bearing 13 in a fixed attachment. Expandable housing 60 further includes an outlet 64 and a chamber 61. pump 100 further includes an inner sheath 16 which has been withdrawn to a point within outlet 64 thereby releasing tines 20 and diaphragm 30 from the captivity of inner sheath 16. Expandable housing 60 further includes a chamber 61 and an end 62. Tine support 15 is received within inner sheath 16 and includes a plurality of

tines 20. A drive cable 40 extends through inner sheath 16 and outer sheath 11 and is coupled to tine support 15. A flexible diaphragm 30 is also coupled to tine support 15.

In the configuration shown in FIG. 6, pump 100 has initiated the expansion of expandable housing 60 and release of tine support 15 from inner sheath 16. Thus, the next step in configuring pump 100 for operation requires allowing tines 20 of tine support 15 and diaphragm 30 to expand and assume their operational configurations.

FIG. 7 sets forth a section view of the pulsatile pump portion of pump 100. As mentioned above, FIG. 6 shows pump 100 in its operational configuration. Expandable housing 60 includes an inlet 63 proximate end 62, which in turn supports a bearing 13 in a fixed attachment. Expandable housing 60 further includes a mesh portion 64 and a chamber 61. Pump 100 further includes an inner sheath 16 which has been withdrawn to a point within outlet 64 thereby releasing tines 20 and diaphragm 30 from the captivity of inner sheath 16. Expandable housing 60 further includes a chamber 61 and an end 62. Tine support 15 extends partially into bearing 13. Tine support 15 includes a plurality of tines 20 that have expanded to the position shown. A drive cable 40 extends through inner sheath 16 and outer sheath 11 and is coupled to tine support 15. Flexible diaphragm 30 is also coupled to tine support 15 and has expanded to its full extended configuration overlapping the outer ends of tines 20.

In the configuration shown in FIG. 7, pump 100 has completed the expansion of expandable housing 60 and released tine support 15 from inner sheath 16 allowing tines 20 and diaphragm 30 to assume their fully extended positions. Thus, pump 100 is fully configured for operation.

In some variations, the pumps for assisting blood circulation include an expandable housing as illustrated in FIGS. 10A to 10C. Referring to FIG. 10A, expandable housing 200 has a cannula 202 extending therefrom. The cannula 202 may have a smaller diameter than the expandable housing 200, which may be useful when the cannula is to traverse the aortic valve. Expandable housing 200 may comprise a scaffold 204, which, in some variations, may be an expandable stent. Scaffold 204 may include a tapered proximal end 208 and a tapered distal end 210, although, it need not. The distal end 210 may function as an inlet for blood into the expandable housing 200 and the proximal end 208 may function as an outlet for blood exiting the expandable housing 200. In order to block blood from flowing through the stent openings and provide a smooth surface upon which the flexible diaphragm can reciprocate, the expandable housing 200 may comprise a layer 206 coupled to and/or covering the scaffold (e.g., stent) 204. FIG. 10B depicts a polymer layer 206 that may be overmolded on or otherwise attached to the scaffold 204. The polymer layer 206 may be overmolded on the scaffold 204 such that the scaffold 204 is embedded within or otherwise fully surrounded by the polymer layer 206. FIG. 10C shows the expandable housing 200 and cannula 202 with the polymer layer 206 coupled to the scaffold 204.

The expandable housing in FIG. 10C may include a flexible diaphragm, which may be, in some variations, supported by a plurality of tines, as shown in FIG. 11. Referring to FIG. 11, flexible diaphragm 212 may be disposed within a chamber formed in the body of the expandable housing 200. and the flexible diaphragm 212 may have a collapsed configuration and an expanded configuration (as depicted in FIG. 11). Flexible diaphragm 212 may be coupled to actuator 214 such that linear movement of the actuator 214 results in corresponding linear movement of the diaphragm 212. A plurality of tines 216, which may help

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support the flexible diaphragm **214** against blood pressure during the pump stroke, are also shown in their expanded configuration. The expandable housing **200**, flexible diaphragm **212**, and/or tines **216** may be configured to self-expand, such that expansion of the expandable housing **200**, flexible diaphragm **212**, and tines **216** may be achieved by relative motion between the expandable housing **200** and a flexible outer sheath **218** that may be constraining the expandable housing **200**, flexible diaphragm **212** and/or tines during advancement to the desired position in the body (e.g., retraction of the outer sheath **218** and/or advancement of expandable housing **200** relative to outer sheath **218**).

Instead of a plurality of tines, the support member for coupling to the flexible diaphragm may be an expandable frame. Referring to FIG. **34**, flexible diaphragm **1800** may be disposed within a chamber formed by expandable housing **1802**. The flexible diaphragm **1800** may have a collapsed configuration and an expanded configuration (as shown in FIG. **34**). Flexible diaphragm **1800** may be coupled to actuator **1804** such that linear movement of the actuator **1804** results in corresponding linear movement of the flexible diaphragm **1800**. An expandable frame **1806**, which may help support the flexible diaphragm **1800** against blood pressure during the pump stroke, is also shown in its expanded configuration. The expandable housing **1802**, flexible diaphragm **1800**, and/or expandable frame **1806** may be configured to self-expand.

In general, the flexible diaphragm contained within the expandable housing moves blood from an inlet of the housing, through the chamber in the body of the expandable housing, to and through an outlet of the housing, and creates the pressure for pumping blood. As shown in FIG. **12A**, the flexible diaphragm **300** in its extended configuration includes a diaphragm body **302** and a rim **304** about the periphery of the body **302**. The body **302** and rim **304** of the flexible diaphragm **300** are integrally formed. However, in other variations, they may be formed separately and coupled to one another.

In some variations, the diaphragm body **302** and the rim **304** may have different thicknesses. For example, in some variations, the thickness of the rim **304** may be greater than the thickness of the diaphragm body **302**, as shown in the cross-section view provided in FIG. **12B**. The smaller thickness of the diaphragm body **302** may allow the flexible diaphragm to be in its collapsed configuration during the fill stroke or a portion thereof, and the extended configuration during the pump stroke of a pumping cycle. The greater rim thickness may provide the periphery of the diaphragm **300** with greater rigidity relative to the diaphragm body **302** and may aid in creating a seal between the rim **304** and interior surface of the expandable housing during the pump stroke.

Some variations of the pump may include a tine support comprising a base and a plurality of tines coupled to the actuator that support the flexible diaphragm in the extended configuration during the pump stroke. For example, as shown in FIGS. **13A** to **13C**, tine support **401** includes a base **404** and a plurality of tines **400**. The plurality of tines **400** may comprise six (6) pliable metal strips **402** having an expanded configuration (as shown in the FIG. **13A**) and a compressed configuration (see FIG. **5**). The metal strips **402** may have a compressed configuration during advancement of the expandable housing within the vasculature to a target location, and may expand radially outward to an expanded configuration at the target location. Although shown as having a rectangular cross-sectional shape, the plurality of tines **400** may have any suitable shape or geometry, e.g., circular, square, triangular, ovoid, etc. The metal strips **402**

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may extend from a common hub or base **404** at one end, and may have free ends **406** at the other end. As shown in the cross-section view of FIG. **13B**, the base **404** may include a bore **408** configured to couple the plurality tines to an actuator. Although shown as including six (6) metal strips **402**, more or less strips may be utilized. The metal strips **402** may be equally spaced from one another, as shown in FIG. **13C**. However, in some variations, the metal strips **402** may be unequally spaced from one another. Also shown in FIGS. **13A** to **13C** are barrels **412**, which are short cylinders attached to the free ends **406** of the metal strips **402**. The free ends **406** may be attached to a barrel **412** using any suitable means, such as, for example, by welding, soldering, or gluing. The barrels **412** may provide further supportive area for the flexible diaphragm to rest against during a pump stroke to help prevent movement of the flexible diaphragm between the tines during the pump stroke.

In some variations, the plurality of tines **500** may comprise a plurality of flexible first wires **502**, as illustrated in FIGS. **14A** to **14C**. Although each tine of the plurality of tines in the figure is shown to include two first wires **502**, they may include one wire or more than two wires. A plurality of holes (not shown) corresponding to the number of first wires **502** may be formed (e.g., drilled) in a base **504** of the tine support **501** so that one end of the wires may be inserted into the holes. At the other end of the wires (free ends **506**), a barrel **508** is attached in the same manner described above. More specifically, in FIGS. **14A** to **14C**, pairs of first wires **502** are attached to the same barrel at their free ends **506** to form one tine of the plurality of tines. Accordingly, six (6) tines are formed when pairing the twelve (12) first wires. The barrels **508** may each include a central hole **510** through which a second wire **512** may be threaded. After threading through all the barrels **508**, the ends of the second wire **512** may be joined by soldering, welding, gluing, and/or the like. The second wire may provide additional flexible diaphragm support to that provided by the barrels during a pump stroke so that movement of the flexible diaphragm between the tines during the pump stroke may be prevented or minimized. As shown in the cross-section view of FIG. **14B**, the base **504** may include a bore **514** configured for coupling to an actuator. The first wires **502** may be equally spaced from one another, as shown in FIG. **14C**. However, the first wires **502** may also be configured to be unequally spaced from one another.

Other pump variations may not include a plurality of tines supporting the flexible diaphragm. For example, as shown in FIG. **15**, a flexible cone shaped diaphragm **600** is disposed within expandable housing **602**. The flexible diaphragm **600** may have a compressed configuration and an extended configuration, and may have a conical shape when in the extended configuration. As shown in FIGS. **16A** (end view) and **16B** (side view), the flexible diaphragm **600** may include a diaphragm body **604** and a rim **606** about the periphery of the body **602**. As depicted FIGS. **16A-16B**, the body **604** and rim **606** of the flexible diaphragm **600** may be integrally formed and may be formed from the same material. However, in other variations, they may be separate components and/or may comprise different materials.

In some variations, the body **604** and the rim **606** may have the same thickness, while in other variations, the thicknesses of the body **604** and the rim **606** may differ. For example, in some instances, it may be advantageous to utilize a diaphragm with a rim **606** that has a greater thickness than the body **604**. Turning to FIG. **17**, shown there is an enlarged cross-sectional view of diaphragm **600** in an extended configuration, coupled to actuator **612** and positioned within

the chamber of the body of expandable housing **614**. Rim **606** contacts interior surface **612** of the expandable housing **614** such that a seal **610** may be formed between the expandable housing **614** and the diaphragm **600**. As can also be seen in FIG. 17, rim **606** of diaphragm **600** has a greater thickness than diaphragm body **604**. The greater thickness of rim **606** may aid in creating the seal **610** between the rim **606** and interior surface **612** of the expandable housing during the pump stroke, while still allowing for diaphragm body **606** to have the flexibility necessary for collapse during the fill stroke. In this variation, the conical shape of the diaphragm helps to seal the diaphragm against the interior surface **612** and also prevent eversion of the diaphragm when pressure from blood flow (in the direction of arrows) pushes against it.

In some variations, the flexible diaphragm may comprise one or more (e.g., a plurality, two, three, four, five, six or more) ribs. Referring to the cross-sectional view provided in FIG. 16C, a plurality of ribs **608** may extend from a center portion **601** of the diaphragm body **604** to the rim **606**. The plurality of ribs **608** may be employed to maintain the conical shape of the diaphragm body **604** during a pump stroke. The plurality of ribs **608** may have a rib angle between the longitudinal axis of each rib and an axis perpendicular to the actuator of about 60 degrees. Although the plurality of ribs **608** are shown as equally spaced from one another, in some instances they may be spaced unequally from one another.

Instead of a flexible diaphragm, the pumps may include a valve cone as the linearly reciprocating valve member. In one variation, as illustrated in FIGS. 25A to 25C, the valve cone **1200** may include an expandable frame **1202**, a mesh cone **1204**, and a flow control cone **1206**. Flow control cone **1206** includes a plurality of arc shaped flaps **1212**. Other flap shapes may also be used. Additionally, although the expandable frame **1202**, mesh cone **1204**, and flow control cone **1206** are shown as conically shaped, they may be formed to have a different shape. Expandable frame **1202** may be a stent-like structure having an expanded configuration at one end and a collapsed configuration. In the expanded cone shape shown in the figures, the expandable frame **1202** contains the mesh cone **1204** and the flow control cone **1204** within the cone **1208** of the frame **1202**. The flow control valve **1200** may be generally configured such that the mesh cone **1204** sits between the flow control cone **1206** and the expandable frame **1202**. In this configuration, the plurality of flaps **1212** open in the direction of arrow A when blood is pulled through the mesh cone into the expandable housing during the fill stroke, and close when blood is moved out of the expandable housing in the direction of arrow B during the pump stroke, as illustrated in FIG. 25B. The mesh cone **1204** may be disposed between the flow control cone **1206** and the expandable frame **1202** to provide support to the flaps **1212** of the flow control cone **1206** such that when pressure against the flaps **1212** is applied during the pump stroke, the flaps **1212** are not pushed or bent through the openings **1201** in the expandable frame **1202**. Thus, the mesh cone **1204** may help maintain the flaps **1212** in the closed configuration during the pump stroke when blood is moved out of the housing via the housing outlet. However, during the fill stroke, the mesh cone **1204** permits blood to flow from the housing inlet through the holes in the mesh and then through the flaps **1212**, transitioning them to their open configuration so that blood may move to the outlet side of the valve cone. The mesh cone **1204** and flow control cone **1206** may be stitched to the expandable frame **1202** at multiple attachment points **1210**, as shown in FIG. 25C.

Other mechanisms of attaching the material layers to the expandable frame may also be employed.

The expandable frame **1202** is shown separately from the rest of the valve cone depicted in FIGS. 26A to 26C. FIG. 26A provides a perspective view of the expandable frame **1202**, FIG. 26B provides a side view of the frame **1202**, and FIG. 26C provides a top view of the frame **1202**. As shown in the figures, expandable frame **1202** may include a first end **1214** and a second end **1216**. The first end **1214** may be coupled to an actuator for reciprocating the valve cone back and forth within the housing. The second end **1216** is generally expandable to form a shaped end, for example, cone shape **1208**. The expandable frame **1202** may comprise a plurality of cells **1218**, which may be diamond shaped. However, the cell shape is not so limited, and they may have any suitable shape. In addition, the cells may have any suitable size. In one variation, the cells may be sized smaller than the flaps in the flow control cone so that the flaps are not pushed through the cells during the pump stroke.

In FIGS. 27A and 27B, the mesh cone **1204** is shown separately from the rest of the valve cone depicted in FIGS. 25A to 25C. Referring to FIG. 27A, the material of mesh cone **1204** may first be provided as a circular layer **1220** with a center cut out **1222** and a slit **1224** extending from the cut out **1222** to the periphery of the circle **1226**. The slit **1224** provides a free edge so that the circular layer **1220** may subsequently be rolled to form mesh cone **1204**. The cone shape of the mesh cone **1204** may be held by stitching, heat sealing, gluing, etc., the mesh material. The height (H) of the mesh cone **1204** may be between about 1.0 cm to about 2.0 cm, including all values and sub-ranges therein. For example, the height of the mesh cone may be about 1.0 cm, about 1.1 cm, about 1.2 cm, about 1.3 cm, about 1.4 cm, about 1.5 cm, about 1.6 cm, about 1.7 cm, about 1.8 cm, about 1.9 cm, or about 2.0 cm.

FIGS. 28A to 28C depict the flow control cone **1206** separately from the rest of the valve cone depicted in FIGS. 25A to 25C. Referring to FIG. 28A, the material of flow control cone **1206** may first be provided as a circular layer **1228** with a center cut out **1230** and a slit **1232** extending from the cut out **1230** to the periphery of the circle **1234**. The slit **1232** provides a free edge so that the circular layer **1228** may later be rolled to form flow control cone **1206**. Next, the flaps **1212** may be formed by laser cutting or stamping the flap shapes into the circular layer **1228**. The flaps **1212** are shown as arc shaped in the figures, but may have any suitable size and shape, as previously stated. Referring to FIG. 28B, a rim **1236** may be created at the periphery of the circular layer **1228** by rolling the edge of the layer upon itself to create thickness at the periphery **1234**, and then stitching, heat sealing, gluing, etc., the rolled edge to maintain the thickness in that area. After the rim **1236** is formed, the free edge of the slit **1232** is rolled to shape the circular layer **1228** into flow control cone **1206**. The rim **1236** may help create a seal between the flow control cone **1206** and the interior surface of the housing during the pump stroke. The cone shape flow control cone **1206** may be held by stitching, heat sealing, gluing, etc., the mesh material. The height (H) of the flow control cone **1204** may be between about 1.0 cm to about 2.0 cm, including all values and sub-ranges therein. For example, the height of the flow control cone may be about 1.0 cm, about 1.1 cm, about 1.2 cm, about 1.3 cm, about 1.4 cm, about 1.5 cm, about 1.6 cm, about 1.7 cm, about 1.8 cm, about 1.9 cm, or about 2.0 cm.

In some variations, the flow control cone may comprise one or more slits extending radially outward from a central portion of the flow control cone, but terminating prior to, the

outer edge of the flow control cone that may form a plurality of flaps. For example, the flow control cone may be cut to create the one or more slits and thus the plurality of flaps. The plurality of flaps may be of any suitable size and shape that allows blood to flow into the housing during the fill stroke. In general, the flow control cone may be configured such that a greater number of flaps are included when they are smaller in size, and a smaller number of flaps may be included when they larger in size. For example, as shown in FIGS. 29A and 29B, three triangular shaped flaps may be employed when the flaps are larger in size. FIG. 29A shows the side of the flow control cone that would face an outlet of the pump housing, and FIG. 29B shows the side of the flow control cone that would face an inlet of the pump housing. Referring to the figures, valve cone 1300 includes a flow control cone 1302 disposed within and covering an expandable frame 1304. Three slits 1306 in the flow control cone 1302 form three triangular shaped flaps 1308 in the flow control cone 1302. The expandable frame 1304 supports the flow control cone 1302 such that when pressure is applied against the flaps 1308 during the pump stroke, the flaps are not pushed through the openings 1310 in the expandable frame 1304. However, during the fill stroke, the expandable frame 1304 permits blood to flow from the housing inlet through the expandable frame openings 1310 and then through the flaps 1308, lifting them off the surface of the expandable frame 1304 so that blood may move to the outlet side of the flaps 1308.

In further variations, the flow control cone may comprise a membrane and a plurality of struts arranged in an umbrella structure, and may have an open configuration and a collapsed configuration. For example, the membrane may be coupled to and supported by the plurality of struts. Any suitable number of struts may be included. For example, the number of struts may range from three to ten. For example, three struts, four struts, five struts, six struts, seven struts, eight struts, nine struts, or ten struts may be employed. In general, the flow control cone comprising a membrane and a plurality of struts may have a collapsed configuration during the fill stroke (FIGS. 30A and 30B), and an open configuration during the pump stroke (FIGS. 30C and 30D). Referring to FIGS. 30A-30D specifically, valve cone 1400 includes an expandable frame 1402 and a flow control cone 1404 disposed within the expandable frame 1402. As better shown in FIGS. 30B and 30C, flow control cone 1404 may comprise an umbrella structure including a membrane 1406 having a rim 1412 and a plurality of struts 1408. The membrane 1406 is coupled at one end to the expandable frame 1402 via a weld ring 1410. The rim 1412 is a free edge that is not attached to the expandable frame 1402. During the fill stroke, collapse of the membrane 1406 permits blood to flow from a housing inlet through the expandable frame openings 1414 to fill a pump the housing. During the pump stroke, the expandable frame 1402 supports the membrane 1406 such that when pressure against the membrane 1406 is applied, the membrane 1406 transitions to its open configuration to cover the expandable frame openings 1414 so that blood is moved to an outlet side of the housing and prevented from flowing back toward the inlet side. However, as previously mentioned, in some variations the expandable frame 1402 may not be needed, and the membrane 1406 including a plurality of struts 1408 linearly reciprocates without the expandable frame 1402 to generate a pump stroke and a fill stroke.

Umbrella structures that may linearly reciprocate without an associated expandable frame are shown in FIGS. 35A to 35C and FIGS. 36A to 36C. In the figures, the umbrella

structures may include a membrane, a plurality of struts, and an anchor. The membrane may entirely or partially cover the struts. Referring to FIG. 35A, an umbrella structure 1900 is shown with a membrane 1902 entirely covering the plurality of struts 1904 and an anchor 1906 having a proximal end 1908 and a distal end 1910. As shown in the side view of FIG. 35B, the struts 1904 may flare radially outwardly to form a conical shape and also create a strut angle (SA) of 40 degrees with respect to the longitudinal axis 1912 of the umbrella structure 1900. In the variation shown in FIG. 35C, the strut angle (SA) is also 40 degrees, but the struts 1914 include a further bend 1916. The bend angle (BA) of the struts formed therefrom may be 30 degrees with respect to the longitudinal axis 1918 of the umbrella structure 1920. In yet a further variation, as shown in FIGS. 36A to 36C, the umbrella structure 2000 also includes a membrane 2002, a plurality of struts 2004 having a proximal end 2005 and distal end 2006, and an anchor 2008 having a proximal end 2010 and a distal end 2012. In this variation, the struts 2004 may have a profile like skis, where the distal end 2006 of struts 2004 include a bend, and a middle section 2007 is flattened and of larger width than the proximal end 2005 or the distal end of the strut 2004. The membrane 2002 may partially cover the plurality of struts 2004. The distal end 2006 of some of the plurality of struts may include a rounded tip 2014. The rounded tip 2014 may comprise a radiopaque marker. Referring to FIG. 36C, a side view of the umbrella structure 2000 is provided that shows a strut angle (SA) of 40 degrees with respect to the longitudinal axis 2016 of the umbrella structure 2000. Additionally, the struts 2004 each include a bend 2018 at the strut distal end 2006. The bend angle (BA) of the struts formed therefrom may be 15 degrees with respect to the longitudinal axis 2016 of the umbrella structure 2000.

The umbrella structures may include a component that facilitates collapse of the struts during the fill stroke of the pumping cycle. In some instances the component may be a swivel mechanism, e.g., a hinge, or a flexible connector that increases flexibility of the struts at that point. The swivel mechanism or flexible connector may attach the struts to the anchor at the proximal end or the distal end of the anchor. For example, as shown in FIG. 48, the valve member 4000 may comprise an umbrella structure 4001 including a plurality of struts 4002. The struts 4002 may be attached to the proximal end 4003 of the anchor 4004 by swivel mechanisms 4006.

Instead of radially expanding from the anchor, the plurality of struts may invert (e.g., fold backwards) about the anchor to form, e.g., a conical shape. For example, as shown in FIG. 39A, the umbrella structure 2300 includes a plurality of struts 2302 that are inverted about the anchor 2304. The anchor 2304 may include a proximal end 2306 and a distal end 2308. When the plurality of struts 2302 are inverted, the actuator (not shown) may generally be attached to the proximal end 2306 of the anchor 2304. In contrast, when the plurality of struts 2302 radially expand from the anchor 2304, and are not inverted, the actuator (not shown) may generally be attached to the distal end 2308 of the anchor 2304. A membrane 2310 may also cover the plurality of struts 2302, as shown in FIG. 39B. Although shown as entirely covering the struts in the variation in FIG. 39B, in some variations, the membrane may only partially cover the struts.

The distal tip of the struts may be configured to be atraumatic, as previously mentioned. In one variation, the atraumatic distal tip may be shaped to help prevent the struts from damaging the interior surface of the housing during the

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pump stroke. For example, the atraumatic distal tip may have a rounded shape or an ovular shape as shown in FIG. 40. Referring to FIG. 40, a plurality of struts 2400 are shown that include a distal end 2402 having an ovular (e.g., paddle-like) shape. Additionally or alternatively, one or more slits or cutouts 2404 may be provided along the length of the strut to increase strut flexibility, which may help prevent the struts from damaging the interior surface of the housing during the pump stroke.

In some variations, the distal tip of one or more struts may include an opening that allows the flow of blood there-through. The openings may have various sizes and shapes, which may depend on the size and shape of the distal end. The openings may be shaped to be circular, ovular, square, rectangular, triangular, and the like. In one variation, the opening at the distal tip is rectangular in shape. In another variation, the opening at the distal tip is circular in shape. Referring to FIG. 41, valve member 2500 includes a plurality of struts 2502 having a circular distal tip 2504, and a membrane 2508 that extends beyond the distal tips 2504, e.g., between about 1.0 mm to about 2.0 mm beyond the distal tips, including all values and sub-ranges therein. For example, the membrane may extend beyond the distal tip about 1.0 mm, about 1.1 mm, about 1.2 mm, about 1.3 mm, about 1.4 mm, about 1.5 mm, about 1.6 mm, about 1.7 mm, about 1.8 mm, about 1.9 mm, or about 2.0 mm. Each circular distal tip 2504 includes a circular opening 2506. Although depicted in FIG. 41B with all the distal ends of the struts including an opening, in some variations, only a portion of the distal ends may include an opening (e.g., in one fifth of the struts, in one fourth of the struts, in one third of the struts, in half the struts). A radiopaque marker 2510 may also be provided at any appropriate location along the length of the struts, for example, at the distal end of one or more struts (e.g., one third of the struts, half the struts, all of the struts). Instead of a radiopaque marker, a portion of the struts may be coated with a radiopaque material.

In other variations, the umbrella structure may include a bend and an opening in one or more of the struts. In some variations, inclusion of both of these features may further help minimize the risk of the struts puncturing the housing during the pump stroke. Referring to FIGS. 42A to 42C, the umbrella structure 2600 may include a membrane 2602, a plurality of struts 2604, and an anchor 2606. An actuator 2608 (e.g., a drive tube) linearly reciprocates the umbrella 2600 to expand the umbrella 2600 during the pump stroke, and collapse the umbrella 2600 during the fill stroke. The struts 2604 may include a bend 2614. The portion of the strut 2604 distal to the bend 2614 may form the distal tip 2610 of the strut 2604. The distal tips 2610 may include an opening 2612 that allows the flow of blood therethrough. Although the shape of the opening 2612 corresponds to the shape of the distal tip 2610 in the variation shown in FIG. 42A, this need not be the case and it is understood that other shapes may be used and that the shape of the opening need not correspond to the shape of the distal tip 2610. For example, the shape of the distal tip may be ovular but the opening may be square shaped. The umbrella structure 2600 may include 10 struts 2604, but as mentioned herein, in other variations, a fewer or greater number of struts may be employed. As shown in FIG. 42B, the struts 2604 may be equally spaced about the perimeter of the membrane 2602. Referring to FIG. 42C, an assembly view is provided of a variation of a valve member 2618 including the umbrella structure 2600. In the variation depicted there, the valve member 2618 includes an umbrella structure 2600 comprising a membrane, a plurality of struts 2604, an anchor 2606, and an

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actuator 2608 (e.g., a drive tube). The membrane may be formed from a plurality of layers, and for example, by sealing an outer layer of material 2620 to an inner layer of material 2622, with the umbrella structure 2600 therebetween. Sealing of the outer and inner layers may be accomplished in various ways, e.g., by the use of heat, pressure, and/or adhesives. A ring 2616 may also be attached to the inner layer 2622 by heat sealing or pressure sealing, or by employing adhesives. The ring 2616 may further include a plurality of apertures through which the struts 2604 may extend. The ring 2616 may thicken the membrane edge to aid contact of the membrane 2602 with the housing (not shown) during the pump stroke.

The inner layer, the outer layer, and the ring may be made from the same material or from different materials. In some variations, one or more of the inner layer, the outer layer, and the ring may comprise an elastomeric polymer. Non-limiting examples of elastomeric polymers include silicone, polyesters, polyurethanes, fluoropolymers, or a combination thereof. Fluoropolymers that may be employed include polytetrafluoroethylene (PTFE) or expanded polytetrafluoroethylene (ePTFE). In one variation, the inner layer, the outer layer, and the ring are made from PTFE. In another variation, the inner layer, the outer layer, and the ring are made from ePTFE.

Other variations of the pump may include a valve member comprising elements that limit its expansion. For example, the valve member may include an expandable frame coupled to a polymer layer, where a plurality of control lines or tethers attach the valve member to the pump actuator. The plurality of tethers may have a relaxed state and a tensioned state, and may have a length that limits expansion of the valve member such that it contacts and creates a seal with the inner surface of the pump housing during a pump stroke of the pumping cycle without generating undue friction. The length of the tethers may also be tailored so that a small gap is created between the valve member and the inner surface of the pump housing during the pump stroke. During the fill stroke, the valve member may collapse to a collapsed configuration, which in turn may move the plurality of tethers to the relaxed state. During the pump stroke, the valve member may expand to an expanded configuration, which may transition the plurality of tethers from the relaxed state to the tensioned state.

For example, referring to FIG. 31, an exemplary valve member is shown disposed within an expandable housing 1500. The valve member includes a frame 1502 that may be a hollow hemispherical structure made from nitinol and coated with a thin polymer. The frame 1502 may have an expanded configuration and a collapsed configuration. When expanded, the element frame may have a diameter of about 20 mm. A plurality of control lines 1504 attach an open end 1508 of frame 1502 to a pump actuator 1506. Additionally, a check valve 1510 may be included in the pump. During the fill stroke, the hydraulic pressure of the blood may cause the frame 1502 to partially collapse, allowing blood to flow around it. At the start of the fill stroke, closure of check valve 1510 may ensure rapid collapse of the frame 1502. When the stroke reverses to the pump stroke of the pump cycle, the check valve 1510 may open and the frame 1502 may expand to its expanded configuration. The control lines 1504 may adjust the sealing pressure of the element against the housing 1500 during the pump stroke to prevent too much pressure from being applied, which may create undue friction. A check valve may also be provided with the alternative valve members described herein to assist with their collapse and expansion.

In some variations, the pump may include an expandable housing comprising a plurality of openings or perforations in a body thereof, as previously mentioned. The openings may be through-wall openings in the body (e.g., through both the scaffold and layer), such that blood from the chamber of the body of the expandable housing may flow directly from within the chamber to outside of the chamber, without passing back through the inlet or through the outlet. When openings are included, a skirt may be coupled to or extend from an external surface of the expandable housing in a manner that surrounds, overlies or otherwise covers the plurality of openings to direct the blood flowing through the openings. For example, the skirt may be configured to generate retrograde blood flow directed toward the patient's heart during the pump stroke of a pumping cycle. The retrograde blood flow may help provide adequate perfusion of arteries branching from the aortic arch, for example, the carotid arteries and subclavian arteries.

Turning to FIG. 19, pump 800 may include an expandable housing 802 including a plurality of openings 804 and a cylindrical skirt 806 coupled to expandable housing 802 in a manner that spaces it therefrom. The skirt 806 may be coupled to and circumferentially (or partially circumferentially) surround an external surface of the housing 802, and may overlie at least a portion of the plurality of openings 804. The skirt 806 may comprise a first diameter at its proximal end and a second larger diameter at its distal end, such that skirt 806 may be coupled to housing 802 at its proximal end, but then may be flared or spaced apart from the plurality of openings 804 formed in housing 802 to allow the retrograde flow of blood therethrough. Skirt 806 and expandable housing 802 may be integrally formed as a single piece, or they may be separate components coupled to one another by friction fit, an adhesive, welding, soldering, and/or the like. At the proximal end 801 of the expandable housing 802, an outlet 808 may be provided for antegrade blood flow to the body. A cannula 810 may be coupled to expandable housing 802 and may extend from the distal end of the housing 820 through the aorta 816 and aortic valve 822 into the left ventricle 814. At the distal end 824 of cannula 810, an inlet 812 for blood entry from the left ventricle 814 may be provided. The cannula may have varying lengths. Varying lengths may be used to accommodate such factors as different patient anatomy, patient size or age, desired location of pump placement, and/or point of access to the circulatory system. Although any suitable length may be utilized, the cannula may have a short, medium, or long length, as previously described. In FIG. 19, cannula 810 has a medium length, which ranges from about 25 cm to about 30 cm.

Referring to FIG. 20, an enlarged view of pump 800 of FIG. 19 is shown. A cut out is provided in the expandable housing 802 to further show the structure and configuration of skirt 806 in relation to the plurality of openings 804. In FIG. 20, housing 802 includes a plurality of openings 804 at its distal end 820. Skirt 806 is concentrically disposed about the expandable housing 802 and overlies the plurality of openings 804. Additionally, skirt 806 is configured such that a space 805 is provided between the plurality of openings 804 and the skirt 806. In use, as flexible diaphragm 803 is moved toward outlet 808, blood within expandable housing 802 is pushed in the direction of arrow 826 through outlet 808 of expandable housing 802 and toward the feet of the patient. During movement of the flexible diaphragm 803, a first portion of blood is pushed through the plurality of openings 804 as the flexible diaphragm passes by them. The first portion of blood is pushed into space 805 and then

directed by skirt 806 back toward the heart in the direction of arrows 828. As the flexible diaphragm 803 continues to move toward outlet 808, the portion of blood (second portion) remaining in the expandable housing 802 is pushed through outlet 808 toward the feet and to the rest of the body. The combination of the number of openings and the diameter of each opening may provide an amount of open surface area on the expandable housing for retrograde blood flow. Additionally, the skirt may be configured to adjust the amount of open surface area for retrograde flow by adjusting the number of patent (open) and closed openings. In general, a larger amount of open surface area may provide more retrograde blood flow toward the head of the patient, and a smaller amount of open surface area may provide a greater amount of antegrade blood flow to the body.

Some variations of the pump may be used to assist with renal perfusion. In these variations, the pumps may include any combination of structures described herein. For example, the pumps may include a housing and a linearly reciprocating member that comprises a valve, for example, a flexible diaphragm, a valve cone, an umbrella structure or an inverted umbrella structure disposed within the housing. The housing may be expandable and may include an interior surface, an expanded configuration, and a collapsed configuration. A sheath, which may be disposed about the housing, may maintain the housing in the collapsed configuration during advancement to a target location. Upon reaching the target location, the sheath may be retracted to allow expansion of the housing to the expanded configuration.

In some variations, the renal perfusion pump is configured as shown in FIG. 33. Referring to the figure, pump 1700 is shown positioned in the descending aorta 1702, above the renal arteries 1704. The pump 1700 may include a valve member 1706 within a housing 1708 that linearly reciprocates to increase perfusion of the kidneys 1710. In this variation, the housing 1708 may lack a cannula. Housing 1708 may include a plurality of cells 1707 that, upon expansion of the housing 1708, have a diamond shape. However, it is understood that the struts may form wider or narrower diamond shapes, or may be configured to form other cell shapes. For example, instead of a diamond shape, cells 2700 may be ovalar in shape, as shown in FIG. 43. Other cell shapes may include circles, triangles, squares, rectangles, etc. In variations including a cannula 2802, as illustrated in FIG. 44, the expandable housing 2800 may also include diamond shaped cells 2804. In further variations, the struts 2902 of the expandable housing 2900 may be straight and may run parallel to each other, as shown in FIG. 45.

As noted above, when in its expanded configuration, the housing may have a diameter ranging from about 12 mm to about 30 mm, including all sub-ranges therein. For example, the housing may have a diameter of about 12 mm, about 13 mm, about 14 mm, about 15 mm, about 16 mm, about 17 mm, about 18 mm, about 19 mm, about 20 mm, about 21 mm, about 22 mm, about 23 mm, about 24 mm, about 25 mm, about 26 mm, about 27 mm, about 28 mm, about 29 mm, or about 30 mm in its expanded configuration. Furthermore, the housing chamber of the renal perfusion pump may have a length ranging from about 2.5 cm to about 10 cm in its expanded configuration, including all values and sub-ranges therein. For example, the housing chamber may have a length of about 2.5 cm, about 3.0 cm, about 3.5 cm, about 4.0 cm, about 4.5 cm, about 5.0 cm, about 5.5 cm, about 6.0 cm, about 6.5 cm, about 7.5 cm, about 8.0 cm, about 8.5 cm, about 9.0 cm, about 9.5 cm, or about 10 cm in its expanded configuration.

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Some variations of the expandable housing may also include one or more enlarged ends that have a diameter larger than that of the housing in its expanded state. In some instances, the diameter of an enlarged end may be about 1.5 times to about two times larger than the diameter of the expanded housing. The one or more ends may be self-expandable. Expansion at the one or more ends may help anchor the housing within the vasculature, e.g., the descending aorta. The one or more ends may expand to anchor within a vessel having a diameter ranging from about 15 mm to about 25 mm, including all values and sub-ranges therein. For example, the one or more ends may expand to anchor within a vessel having a diameter of about 15 mm, about 16 mm, about 17 mm, about 18 mm, about 19 mm, about 20 mm, about 21 mm, about 22 mm, about 23 mm, about 24 mm, or about 25 mm. In some variations, the housing may include one enlarged end. In other variations, the housing may include two enlarged ends. Upon enlargement, the ends may be configured to have the same shape or a different shape. For example, referring to FIGS. 46A, 46B, 47A, and 47B, housings 2900, 3000 include two enlarged ends, a first enlarged end 2902, 3002 and a second enlarged end 2904, 3004. The first enlarged end 2902, 3002 has a rounded shape, while the second expandable end 2904, 3004 has a taper 2906, 3006. The shape of the expanded ends may differ, and may depend on, e.g., the orientation of the struts and/or the shape of the cells formed by the struts.

The housing may further comprise a covering, coating, or layer configured to block the flow of blood, as previously described herein. The covering, coating, or layer may be provided on the entire housing or on a section or portion of the housing. In some variations, the covering, coating, or layer may be provided on a length of housing ranging from about 1.0 cm to about 6.0 cm, including all values and sub-ranges therein. For example, the coated length of the housing may be about 1.0 cm, about 1.5 cm, about 2.0 cm, about 2.5 cm, about 3.0 cm, about 3.5 cm, about 4.0 cm, about 4.5 cm, about 5.0 cm, about 5.5 cm, or about 6.0 cm. Referring to FIGS. 46B, 47A, and 47B, the coating 2908, 3008 may be provided on the portion of the housing 2900, 3000 between the first expandable end 2902, 3002 and the second expandable end 2904, 3004. As shown in FIG. 47B, a valve member 3010 may reciprocate within the coated length of the housing.

When the valve member is a flexible diaphragm, the flexible diaphragm may have an extended configuration and a collapsed configuration, and may include a diaphragm body and a rim, as mentioned above. Likewise, when the valve member is a valve cone, the valve cone may have an expanded configuration and a collapsed configuration, and may include a layer having a plurality of flaps that allow blood flow into the housing during the fill stroke but prevent blood flow through the valve cone during the pump stroke. A bearing within the expandable housing may also be provided to contain movement of the flexible diaphragm or valve cone within the housing. When the valve member is an umbrella structure, the umbrella may include a membrane having a body and a rim, a frame comprising a plurality of struts, and an anchor, and may also have an expanded configuration and a collapsed configuration, as noted above.

The distal tip of the struts may be configured to be atraumatic, as previously mentioned. In one variation, the atraumatic distal tip may be shaped to help prevent the struts from damaging the interior surface of the housing during the pump stroke. For example, the atraumatic distal tip may have a rounded shape or an ovular shape. Additionally or alternatively, one or more slits or cutouts may be provided

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along the length of the strut to increase strut flexibility, which may help prevent the struts from damaging the interior surface of the housing during the pump stroke. In some variations, the distal tip may include an opening that allows the flow of blood therethrough. The openings may have various sizes and shapes, which may depend on the size and shape of the distal end. The opening may be shaped to be circular, ovular, square, rectangular, triangular, etc. In one variation, the opening at the distal tip is rectangular in shape. In another variation, the opening at the distal tip is circular in shape. A radiopaque marker may also be provided at any appropriate location along the length of one or more struts, for example, at the distal end of one or more struts (e.g., one third of the struts, half the struts, all of the struts). In some variations, the umbrella structure may include a bend and an opening in one or more of the struts. Inclusion of both of these features may help minimize the risk of the struts puncturing the housing during the pump stroke.

The renal perfusion pump linearly reciprocates in the same manner as described above. In brief, the renal perfusion pump may include an actuator coupled to the valve member (e.g., a flexible diaphragm, a valve cone, or an umbrella structure) via a support element, which may be configured to linearly reciprocate the valve member within the housing to generate a fill stroke and a pump stroke of a pumping cycle. The rim of the valve member may be configured to maintain contact with the interior surface of the housing during the pump stroke. However, the support elements may generally be sized and/or shaped so that they do not contact the inside surface of the housing while they linearly reciprocate within the housing. The pumps may be driven by an external linear motor drive and linear motor controller, which may be situated at the proximal end of a catheter external to the patient. The linear motor drive may be operatively coupled to the pump by a cable or other actuator. Furthermore, the pumps may be powered by AC or DC sources.

The pumps described herein may be driven by an external linear motor drive and linear motor controller situated at the end of a catheter external to the patient. The linear motor drive may be operatively coupled to the pump by a flexible cable or other flexible actuator running through the catheter. For example, as shown in FIG. 22A, pump 900 may be coupled to a linear motor drive 902 and linear motor controller 904 via catheter 906. Linear motor drive 902 and linear motor controller 904 may be situated outside the patient, within console 908. Catheter 906 may be coupled to the expandable housing 910 of pump 900, as shown in the close-up view in FIG. 22B. Here expandable housing 910 includes a plurality of openings 914 and a skirt 912 concentrically disposed about the openings 914. A cannula 916 may extend from the expandable housing 910 such that a distal end 918 of the cannula 916 may be positioned in the left ventricle 920. As shown in the close-up view in FIG. 22C, an inlet 922 may be provided at the distal end 918 of cannula 916. Inlet 922 may pull blood from the left ventricle 920 and into expandable housing 910 for pumping systemically. The linear motor controller 904 may further be configured to control pump 900. In some variations, linear motor controller 904 may be configured to control pump 900 via sensor feedback, such as, for example, pressure sensor feedback. For example, as described above, one or more pressure sensors (not shown) may be mounted in or on inlet 922 of cannula 916, and one or more pressure sensors may be mounted in or on outlet 924 of expandable housing 910. In some variations, two pressure sensors may be mounted in or on the inlet 922 and/or outlet 924 for redundancy. For

example, referring to FIG. 24A, pump 1100 may include two pressure sensors 1102 on the distal end of an inner sheath 1103 at the pump outlet 1104, and another two pressure sensors 1106 may be disposed on a nose cap 1105 at the pump inlet 1108. FIGS. 24B and 24C show enlarged views of the pressure transducers at the pump outlet 1104 and pump inlet 1108. The controller 904 may be configured to have predetermined high and low blood pressure set points. When measurements from the pressure transducers indicate that blood pressure has dropped below the low set point, the controller 904 may increase the speed of the linear reciprocation, and/or when measurements from the pressure transducers indicate that blood pressure has increased above the high set point, the controller 904 may decrease the speed of the linear reciprocation to thereby reduce flow and return blood pressure back within a target range.

Turning to FIGS. 23A-23C, in some variations, a pump may be disposed external to the body, for example, within a console at the patient's bedside. A coaxial catheter may be coupled to the pump at one end and inserted into the patient at the other end so that blood flows between the patient and the external pump. The coaxial catheter may include an inflow lumen and an outflow lumen. Similar to that described for FIG. 22A, an external pump may be driven by a linear motor drive and linear motor controller situated at the end of the coaxial catheter external to the patient. The linear motor drive may be operatively coupled to the pump by any suitable connector or fitting, e.g., a quick connect coupler. For example, as shown in FIG. 23A, external pump 1000 may be coupled to a coaxial catheter 1006 via inlet and outlet tubes 1016. Pump 1000 may also be coupled to a linear motor drive 1002 and linear motor controller 1004 within console 1008. Console 1008 may also comprise a power supply 1010, a battery 1012, and/or a user interface 1014. The coaxial catheter may include an inflow lumen 1018 and an outflow lumen 1020, as shown in the close-up view provided in FIG. 23B. The distal end of coaxial catheter 1006 is illustrated in the close-up view provided in FIG. 23C, where blood is shown being pulled from the left ventricle 1024 into inflow lumen 1018 at a pump intake end, and pushed out of outflow lumen 1020 at a pump exhaust end right above the aortic valve 1022. The linear motor controller 1004 may further be configured to control the pump 1000 via pressure transducer feedback, as described in more detail herein. For example, one or more pressure transducers (not shown) may be mounted in or on inflow lumen 1018, and another pressure transducer mounted in or on outflow lumen 1020. In some variations, two pressure transducers may be mounted in or on the inflow and outflow lumens for redundancy.

METHODS

Methods for pumping blood using a linear reciprocating pump are also described herein. Utilizing a linear pump, as opposed to a rotary pump, may help avoid the shear forces that cause red blood cell damage, and may pump blood in a pulsatile fashion, mimicking the natural pumping cycle of the heart. In order for the pump to generate sufficient blood pressure to move blood peripherally, a linearly reciprocating member may be configured such that a seal is created between it and the pump housing during a pump stroke of the pumping cycle. The pumps may be placed in various parts of the circulatory system of a patient, such as the left ventricle, the right ventricle, and the aorta. However, in some instances it may be useful to have the pump lie external to the patient. The linear reciprocating pumps may

be placed to assist with heart failure due to, e.g., myocardial infarction, hypertension, trauma, and cardiac anomalies.

As a first step, the methods may include accessing the circulatory system of a patient. Access may generally be accomplished using the Seldinger technique whereby a guidewire is placed within a desired artery or vein and the pump advanced over the guidewire to a target location. Arterial access may be obtained, e.g., from the femoral artery or the carotid artery. Arterial access may be useful when the target location for the pump is the left ventricle or aorta. Venous access may be obtained, e.g., from the femoral vein or internal jugular vein. Venous access may be useful when the target location for the pump is the right ventricle. The guidewire may be slidingly advanced through the lumen of a pump actuator such as a drive line, cable, or rod, which linearly reciprocates a valve member, for example, a valve cone or a flexible diaphragm, within the expandable housing of the pump.

The methods may also include advancing a pump to a target location within the circulatory system of a patient, where the pump includes an expandable housing comprising an outer surface, an interior surface, an expanded configuration, and a collapsed configuration. The pump may further include a valve member. In some variations, the valve member may be a valve cone including a flow control layer and a mesh layer coupled to an expandable frame. In other variations, the valve member may be a flexible diaphragm comprising a diaphragm body and a rim disposed within the expandable housing, where the flexible diaphragm has an extended configuration and a collapsed configuration. Once at the target location, the expandable housing may be expanded from the collapsed configuration to the expanded configuration, and the valve cone or the flexible diaphragm contained therein linearly reciprocated to generate a fill stroke and a pump stroke of a pumping cycle. When the pump further comprises a cannula, the cannula may be advanced through the aortic valve and into the left ventricle of the patient. Non-limiting examples of target locations for the expandable housing and flexible diaphragm include the aortic arch, the descending aorta, the thoracic aorta, and the abdominal aorta.

In addition to the arterial vasculature, the pump may be advanced and positioned within the venous circulatory system. For example, the expandable housing of the pump may be advanced within the inferior vena cava to a location between the hepatic veins and the right atrium of the heart. When placed in this location, the pump may draw blood toward the heart and increase circulation from the lower extremities and from the liver. The pump may be positioned at various locations between the hepatic veins and the right atrium. In some variations, the expandable housing is placed closer to the hepatic veins than to the right atrium.

The expandable housing and the valve members (e.g., the valve cone and the flexible diaphragm) may be in their collapsed configurations within an outer sheath and inner sheath, respectively, during advancement within the vasculature. In some variations, once the expandable housing has been positioned at the target location, the outer sheath may be retracted to allow the housing to expand from the collapsed configuration to the expanded configuration. In other variations, the expandable housing may be advanced out of the housing, e.g., using a pusher, thereby allowing the housing to expand from the collapsed configuration to the expanded configuration. The inner sheath, which may be concentrically disposed about the valve cone or the flexible diaphragm, may then be retracted to allow the valve cone or the diaphragm to expand from the collapsed configuration to

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the expanded or extended configuration. When the pump comprises a support member such as an expandable frame, withdrawal of the inner sheath may also allow the frame to expand from the collapsed configuration to the expanded configuration. When the pump comprises a support member such as a tine support, withdrawal of the inner sheath may also allow the plurality of tines to expand from the compressed configuration to the expanded configuration.

The pump may be reciprocated within the expandable housing under the force of a reciprocating actuator (e.g., drive cable) to initiate a succession of fill strokes and pump strokes. In variations where the valve member is a flexible diaphragm, during each fill stroke of the pump, the flexible diaphragm may be collapsed, allowing blood to flow past the diaphragm (with or without supporting tines) to fill the expandable housing. During each pump stroke of the pump, the flexible diaphragm may return to its extended configuration, forcing blood out from the expandable housing. In variations where the valve member is a valve cone including a flow control layer and a mesh layer, during each fill stroke of the pump, the flaps in the flow control layer open and the openings in the mesh allow blood to flow through the valve cone to fill the expandable housing. During each pump stroke of the pump, the flaps return to their closed configuration and are supported by the mesh layer to remain closed against the pressure of the blood as the blood is forced out of the expandable housing. The reciprocating motion of the drive cable and pulsatile pump may be controlled by a programmable linear motor controller to provide the desired blood flow and pressure characteristics. In some variations, the linear motor controller may be configured to control the pump via sensor (e.g., pressure transducer) feedback as described in more detail herein.

During the pump stroke, contact between the rim of the valve cone or flexible diaphragm and the inner surface of the expandable housing may be maintained such that a seal is created to prevent blood flow between the rim and interior surface. Additionally, during the pump stroke, blood may be pulled into the expandable housing. Depending on the variation of pump used, blood may be pulled into the expandable housing from the left ventricle or the aorta. The pump stroke may generally push blood out of the expandable housing into a portion of the aorta, for example, the ascending aorta or the descending aorta. When the expandable housing and flexible diaphragm are situated outside the patient, blood may be pushed through the coaxial catheter coupled thereto to the ascending aorta, right above the aortic valve. During the pumping cycle, the valve cone or the flexible diaphragm may be collapsed to the collapsed configuration during the fill stroke and expanded to the expanded or extended configuration during the pump stroke.

The pump may be advanced and positioned in various parts of the circulatory system of the patient. In one variation, the pump may be advanced until the expandable housing and pulsatile portion of the pump (e.g., the flexible diaphragm with or without tines) is located within the left ventricle and a cannula extending from the proximal end of the expandable housing extends through the aortic valve. In this variation, blood may flow through a proximal inlet of the expandable housing to fill the expandable housing during the fill stroke (rearward movement of the flexible diaphragm toward the feet). Blood then exits a distal outlet of the expandable housing to provide blood to the body during the pump stroke (forward movement of the flexible diaphragm toward the head).

For example, as illustrated in FIG. 2, a pump 10 may be advanced in its collapsed configuration within a patient's

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aorta to the left ventricle. Heart 50 includes a left ventricle 56, which fluidly communicates with an ascending aorta 52 and a descending aorta 51. Ascending aorta 52 further supports a plurality of arteries such as arteries 53 (brachiocephalic artery), 54 (left common carotid artery), and 55 (left subclavian artery). In FIG. 2, pump 10 is advanced to the left ventricle through the descending aorta 51 in the direction of arrow 35. As described above, pump 10 may include an outer sheath 11 through which a drive cable 40 may pass. As also described above, pump 10 may define an end 12 within which a bearing 13 may be supported. An expandable housing 25 (better seen in FIG. 3) may be deployed from the outer sheath 11 and may also fixedly support bearing 13. Tine support 15 including a plurality of tines 20 may be coupled to the end of drive cable 40 and may be captivated within an outer sheath 11 in the manner set forth above in FIG. 1.

Once pump 10 is positioned within the left ventricle 56, it assumes the operational position shown in FIG. 3. Here expandable housing 25 has been expanded to its expanded configuration and thus is shown to include a distal inlet (mesh portion) 26 and a proximal outlet (mesh portion) 27. Proximal outlet 27 is provided at the end of the cannula (housing extension) 28 extending from the expandable housing 25 and through the aortic valve into the ascending aorta 52. With this configuration, blood is pulled into the expandable housing 25 from the left ventricle 56 during the fill stroke, and moved out of the expandable housing 25 in the direction of the arrows to the ascending aorta 52 and arteries 53, 54, and 55 during the pump stroke.

The pumping action of pump 10 may be undertaken by activating the linear motor 19 (seen in FIG. 1) to initiate a reciprocating action of tine support 15 (and the plurality of tines 20) by successive forces pushing and pulling on flexible cable 40. The pumping action of pump 10 is set forth below in FIGS. 8 and 9 in greater detail. However, suffice it to note here that FIG. 3 generally illustrates the operation of pump 10 during a pump stroke, which is characterized by a pulling force upon drive cable 40 and movement of the tine support 15 in the direction indicated by arrow 36. During this pump stroke, it will be noted that diaphragm 30 has extended to its fully open configuration and thus exerts a driving force against blood within expandable housing 25, forcing blood upwardly through cannula (housing extension) 28 and outwardly through proximal outlet (mesh portion) 27, and creating blood flow through ascending aorta 52 and outwardly to the patient's body through arteries such as arteries 53, 54 and 55. Referring to FIG. 4, it will be noted that a push force against drive cable 40 in the direction indicated by arrow 37 therein produces a fill stroke during which diaphragm 30 is collapsed and blood flows into expandable housing 25 through distal inlet 26.

With cardiac assist pulsatile pump 10 remaining positioned within the left ventricle and aorta and expandable housing 25 remaining configured for operation, the pumping action of pump 10 continues as linear motor 19 (seen in FIG. 1) continues the reciprocating action of tine support 15 (and the plurality of tines 20) by successive forces pushing and pulling on flexible cable 40. Once again it will be understood that the pumping action of pump 10 is set forth below in FIGS. 8 and 9 in greater detail. However, suffice it to note here that FIG. 4 illustrates the operation of pump 10 during a fill stroke characterized by a pushing force upon drive cable 40 moving tine support 15 in the direction indicated by arrow 37. During this fill stroke, it will be noted that diaphragm 30 has partially collapsed and thus exerts a reduced force against blood within expandable housing 25.

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As a result, blood is able to flow inwardly through distal inlet (mesh portion) 26 filling the interior of expandable housing 25. For purposes of illustration, and with temporary return to FIG. 3, it will be recalled that a pull force against drive cable 40 in the direction indicated by arrow 36 therein produces a pump stroke during which diaphragm 30 is expanded and blood flows outwardly from expandable housing 25. Accordingly, with simultaneous reference to FIGS. 3 and 4, the pumping action of pump 10 may be illustrated by alternating the pump stroke shown in FIG. 3 and the fill stroke shown in FIG. 4.

Some pump variations do not include a cannula extending from the expandable housing. For example, pump 100 in FIGS. 5, 6 and 7, is substantially identical to pump 10 in FIGS. 3 and 4 both in structure and function, except for the lack of cannula (extended portion) 28. In addition, as shown in FIGS. 18A and 18B, pump 700 does not include a cannula extending from either the proximal end 702 or distal end 704 of the expandable housing 710, but is otherwise substantially identical to pump 100. Exemplary target locations for pumps 100 and 700 may be the thoracic aorta 706 (FIG. 18A) or the abdominal aorta 708 (FIG. 18B). In FIG. 5, blood from one portion of the aorta enters the expandable housing 60 via inlet 63 and is pumped to a second portion of the aorta upon exiting outlet 64 of the expandable housing 60. Referring to FIG. 18A, blood from one portion 716 of the thoracic aorta 706 enters the expandable housing 710 via inlet 712 and is pumped to a second portion 718 of the thoracic aorta 706 upon exiting outlet 714 of the expandable housing 710. In FIG. 18B, blood from one portion 720 of the abdominal aorta 708 enters the expandable housing 710 via inlet 712 and is pumped to a second portion 722 of the abdominal aorta 708 upon exiting outlet 714 of the expandable housing 710.

By way of overview, FIGS. 5, 6 and 7 set forth sequential section views of the pulsatile pump 100 illustrating the transition of the pulsatile pump portion between its compacted configuration utilized during catheter insertion and its expanded operational configuration utilized during pumping action. Thus, FIG. 5 shows a section view of linear cardiac assist tile pump 100 in its collapsed configuration while FIG. 7 shows a section view of pump 100 in its expanded operational configuration. FIG. 6 sets forth a section view of pump 100 at a point intermediate between the configurations shown in FIGS. 5 and 7.

FIGS. 8 and 9 set forth section views of pump 100 in operation. FIG. 8 sets forth a section view of pump 100 during a fill stroke while FIG. 9 sets forth a section view of pump 100 during a pump stroke. The succession of fill and pump strokes are carried forward on a repeated basis to produce pulsatile pumping action as the linear motor (linear motor 19 seen in FIG. 1) reciprocates drive cable 40 and thereby reciprocates the pumping mechanism within pump 100.

With specific reference to FIG. 8 pump 100 includes an expandable housing 60 having an end 62 supporting a bearing 13 and inlet (scaffold portion) 63. Expandable housing 60 further includes a chamber 61 and an outlet (scaffold portion) 64. The chamber may be formed by embedding a portion of the scaffold of expandable housing 60 within a polymer layer (e.g., overmolding) or coupling a fabric layer to the scaffold, as previously described. Tine support 15 may be slidably received within bearing 13 and joined to the interior end of a drive cable 40. Tine support 15 supports a plurality of tines 20 and a flexible diaphragm 30. Tine support 15 may define a plurality of outwardly extending spline ribs between which spline grooves are

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formed. The spline grooves provide blood flow paths by which blood is able to flow past tine support 15.

As mentioned, FIG. 8 shows a fill stroke in the operation of pump 100. Accordingly, the reciprocating force applied to drive cable 40 moves tine support 15 in the direction indicated by arrow 38. Because blood is present within chamber 61, the movement of tine support 15 in the direction indicated by arrow 38 causes a force against the back side of diaphragm 30 which in turn flexes it in the manner shown. The flexing of diaphragm 30 away from its outwardly extended position (seen in FIG. 9) allows blood flow around tines 20 and diaphragm 30 within chamber 61. This provides a filling of chamber 61 with blood drawn through inlet portion 63 and bearing 13. Once tine support 15 reaches the end of its filling stroke, the drive apparatus described above applies a pulling force to drive cable 40 initiating a pump stroke shown in FIG. 9.

With specific reference to FIG. 9 pump 100 includes an expandable housing 60 having an end 62 supporting a bearing 13 and an inlet (scaffold portion) 63. Expandable housing 60 further includes a chamber 61 and an outlet (scaffold portion) 64. Tine support 15 is slidably received within bearing 13 and is joined to the interior end of a drive cable 40. Tine support 15 includes a plurality of tines 20 and a flexible diaphragm 30. Tine support 15 defines a plurality of outwardly extending spline ribs between which spline grooves are formed. The spline grooves provide blood flow paths by which blood is able to flow past tine support 15.

As mentioned, FIG. 9 shows a pump stroke in the operation of pump 100. Accordingly, the reciprocating force applied to drive cable 40 moves tine support 15 in the direction indicated by arrow 39. Because blood is present within chamber 61, the movement of tine support 15 in the direction indicated by arrow 39 causes a force against the front side of diaphragm 30 which in turn forces diaphragm 30 against tines 20 the extended position shown. The extension of diaphragm 30 to its outwardly extended position forces blood from chamber 61 ahead of diaphragm 30 as diaphragm 30 moves in the direction indicated by arrow 39. This in turn creates a blood flow outwardly from chamber 61 through outlet 64. Once the tine support 15 reaches the end of its pump stroke, the drive apparatus described above applies a pushing force to drive cable 40 initiating the next fill stroke shown in FIG. 8. As the drive apparatus described above reciprocates, alternate push and pull forces against cable 40 are generated that correspond to successive fill and pump strokes of pump 100, which produce a pulsatile blood flow.

As previously described, the expandable housing in some variations may comprise a plurality of openings and a skirt coupled to the expandable housing. In this instance, blood exiting the openings may be directed in a retrograde direction toward the heart of the patient during the pump stroke by the skirt. The retrograde blood flow may help provide adequate perfusion of arteries branching from the aortic arch, for example, the carotid arteries and subclavian arteries. The ability to maintain adequate perfusion of the subclavian artery may prevent flow reversal from the vertebralbasilar artery to the subclavian artery, a phenomenon known as "subclavian steal." For example, referring to FIG. 21, pump 800 may pull blood from the left ventricle 814 through inlet 812 provided at the distal end 824 of cannula 810, which may extend from expandable housing 802. From the inlet 812, blood may flow in the direction of arrows 830 to fill expandable housing 802. During a pump stroke, blood from the expandable housing 802 may generally be moved toward outlet 808 in the direction of arrows 826. However,

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as blood is moved past the plurality of openings **804**, a first portion of blood may be pushed through openings **804** and then directed by skirt **806** back toward the heart in the direction of arrows **828** to perfuse vessels **818** branching from the aortic arch. The portion of blood (second portion) not pushed out of the expandable housing through the plurality of openings **804**, and remaining in the expandable housing **802** is pushed through outlet **808** toward the feet and to the rest of the body.

The length of the skirt may be adjusted to achieve a predetermined amount of retrograde blood flow toward the heart of the patient. Alternatively, the number of openings may be adjusted to achieve a predetermined amount of retrograde blood flow toward the head of the patient. The diameter of the openings may also be adjusted to achieve a predetermined amount of retrograde blood flow toward the head of the patient. The combination of the number of openings and opening diameter may provide an amount of open surface area on the expandable housing for retrograde blood flow. Accordingly, adjustment of any one or combination of the foregoing features may be utilized so that about 60% of the blood from the pump stroke flows in a retrograde direction toward the heart of the patient about 50% of the blood from the pump stroke flows in a retrograde direction toward the heart of the patient, or about 40% of the blood from the pump stroke flows in a retrograde direction toward the head of the patient.

In some variations, the skirt may be configured to adjust the amount of open surface area for retrograde flow by adjusting the number of patent (open) and closed openings. For example, a tether may be coupled to the skirt and configured to open and close the skirt against the expandable housing similar to how a noose can be tightened and loosened. The amount of opening or closing may be adjusted using a rotatable dial disposed, e.g., on a console external to the patient. In general, a larger amount of open surface area may provide more retrograde blood flow toward the head and heart of the patient, and a smaller amount of open surface area may provide a greater amount of anterograde blood flow to the body.

Other methods for pumping blood may include advancing a pump to a target location within the aorta of a patient, such as the thoracic aorta or the abdominal aorta, where the pump has a fill stroke and a pump stroke; pulling a fill volume of blood into the pump during the pump stroke; and pushing an exit volume of blood out of the pump during the pump stroke, where the exit volume comprises a first portion of blood and a second portion of blood. The fill stroke may pull blood from the left ventricle of the patient. Additionally, the first portion of blood may be pumped in a retrograde direction toward the head of the patient, and the second portion of blood may be pumped in an anterograde direction. The second portion of blood may be about 60% of the exit volume, about 50% of the exit volume, or about 40% of the exit volume.

When the pump is disposed external to the patient, the method for pumping blood may include accessing the circulatory system of a patient with a coaxial catheter. The external pump may include the same valve member, e.g., a valve cone or a flexible diaphragm, as the internal pumps placed within the vasculature or a heart chamber, but the housing may not be expandable. The valve cone or flexible diaphragm contained within the expandable housing may comprise a body and a rim. The flexible diaphragm may have an extended configuration and a collapsed configuration, and the valve cone may have an expanded configuration and a collapsed configuration. The external pump may

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be disposed within a console comprising a user interface. The coaxial catheter may comprise an inflow lumen and an outflow lumen. The coaxial catheter may be coupled to the external pump at one end, and the other end inserted and advanced within the patient.

Access to the circulatory system with a coaxial catheter may be obtained from any suitable artery or vein, for example, the femoral artery, the subclavian artery, the carotid artery, or the jugular vein. Once access is obtained, the coaxial catheter may be advanced to a target location in the circulatory system and the flexible diaphragm linearly reciprocated within the housing to generate a fill stroke and a pump stroke of a pumping cycle. During the pump stroke, contact between the rim of the valve cone or the flexible diaphragm and the interior surface of the housing may be maintained to create a seal therebetween and prevent blood from flowing around the valve cone or the flexible diaphragm. The seal may help generate and maintain the force of the pump stroke as well as minimize red blood cell damage that may occur with blood flowing between a space existing between the rim and the interior surface. The methods described herein may include advancing a coaxial catheter to various target locations in a patient. For example, the target location for the inflow lumen of the coaxial catheter may be a left ventricle of the patient, and the target location for the outflow lumen of the coaxial catheter may be above an aortic valve of the patient.

For example, as shown in FIG. 23A, external pump **1000** is coupled to a coaxial catheter **1006** by inlet and outlet tubes **1016**. Coaxial catheter **1006** includes an inflow lumen **1018** and an outflow lumen **1020**, as shown in the close-up view provided in FIG. 23B. Access to the circulatory system by coaxial catheter **1006** is via the femoral artery **1026**. Once access is obtained, coaxial catheter **1006** is advanced to the left ventricle **1024**. More specifically, and as shown in the close-up view of FIG. 23C, the distal end of coaxial catheter **1006** is advanced until the inflow lumen **1018** is within the left ventricle and the outflow lumen **1020** is situated above the aortic valve. In FIG. 23C, blood is shown as being pulled from the left ventricle **1024** into inflow lumen **1018** at a pump intake end, and pushed out of outflow lumen **1020** at a pump exhaust end right above the aortic valve **1022**. Pump **1000** is also coupled to a linear motor drive **1002** and linear motor controller **1004** within console **1008**. Console **1008** also includes a power supply **1010**, a battery **1012**, and a user interface **1014**. The linear motor controller **1004** may be configured to control the speed of the pump **1000** via pressure transducer feedback. For example, a pressure transducer (not shown) may be mounted in or on inflow lumen **1018**, and another pressure transducer mounted in or on outflow lumen **1020**. In some variations, two pressure transducers may be mounted in or on the inflow and outflow lumens for redundancy in case one fails. The controller may be configured to have predetermined high and low blood pressure set points. When measurements from the pressure transducers indicate that blood pressure has dropped below the low set point, the controller **1004** would increase the speed of the linear reciprocation, and if too high (e.g., above the high set point), the controller **1004** would slow the speed of the linear reciprocation to thereby reduce flow and blood pressure back within a target range.

The foregoing description, for purposes of explanation, used specific nomenclature to provide a thorough understanding of the invention. However, it will be apparent to one skilled in the art that specific details are not required in order to practice the invention. Thus, the foregoing descriptions of specific embodiments of the invention are presented

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for purposes of illustration and description. They are not intended to be exhaustive or to limit the invention to the precise forms disclosed; obviously, many modifications and variations are possible in view of the above teachings. The embodiments were chosen and described in order to explain the principles of the invention and its practical applications, they thereby enable others skilled in the art to utilize the invention and various embodiments with various modifications as are suited to the particular use contemplated.

The invention claimed is:

1. A pump for assisting blood circulation comprising:
a housing; and
a valve member disposed within the housing, wherein the valve member has an umbrella structure and comprises a membrane coupled to a plurality of struts, and wherein the umbrella structure is configured to linearly reciprocate within the housing to generate a pump stroke and a fill stroke and circulate blood within a patient.
2. The pump of claim 1, wherein a rim of the membrane is configured to maintain contact with an interior surface of the housing during at least a portion of the pump stroke.
3. The pump of claim 1, wherein the umbrella structure has an expanded configuration and a collapsed configuration.
4. The pump of claim 1, wherein the housing has an expanded configuration and a collapsed configuration.
5. The pump of claim 1, wherein the housing comprises a plurality of openings, and wherein a portion of the plurality of openings have a size or a shape different from another portion of the plurality of openings when the housing is in its expanded configuration.
6. The pump of claim 1, wherein the housing comprises at least one enlarged end.
7. The pump of claim 1, wherein the membrane comprises an elastomeric polymer.
8. The pump of claim 7, wherein the elastomeric polymer comprises a silicone, a polyester, a polyurethane, a fluoropolymer, or a combination thereof.
9. The pump of claim 8, wherein the elastomeric polymer comprises a fluoropolymer and the fluoropolymer comprises polytetrafluoroethylene (PTFE) or expanded polytetrafluoroethylene (ePTFE).
10. The pump of claim 1, wherein the plurality of struts comprises between six struts and ten struts.
11. The pump of claim 1, wherein at least one of the plurality of struts comprises a circular, ovular, triangular, square, or rectangular cross-sectional shape.
12. The pump of claim 1, wherein a distal end of at least one strut of the plurality of struts comprises a circular shape or an ovular shape.
13. The pump of claim 1, wherein at least one strut of the plurality of struts includes a bend along a length thereof.

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14. The pump of claim 13, wherein the bend has a bend angle ranging from about 5 degrees to about 30 degrees.

15. The pump of claim 1, wherein a distal end of at least one strut of the plurality of struts comprises an opening.

16. The pump of claim 1, wherein each strut of the plurality of struts comprises stainless steel, nickel, titanium, or an alloy thereof.

17. The pump of claim 1, wherein at least one of the housing and the valve member comprises a polymer coating.

18. The pump of claim 17, wherein the polymer coating comprises polytetrafluoroethylene (PTFE) or expanded polytetrafluoroethylene (ePTFE).

19. The pump of claim 2, wherein the rim has a thickness ranging from about 0.20 mm to about 1.5 mm.

20. The pump of claim 1, further comprising a cannula.

21. The pump of claim 20, wherein the cannula extends from a distal end of the housing.

22. The pump of claim 20, wherein the cannula extends from a proximal end of the housing.

23. The pump of claim 1, further comprising an actuator coupled to the umbrella structure.

24. A pump for assisting blood circulation comprising:
a housing; and

a valve member disposed within the housing, the valve member comprising a membrane at least partially covering a plurality of struts, wherein the valve member is configured to linearly reciprocate within the housing to generate a pump stroke and a fill stroke.

25. The pump of claim 24, further comprising a controller configured to adjust one or more parameters of a pumping cycle of the pump.

26. The pump of claim 25, wherein the one or more parameters comprise one or more of a speed of linear reciprocation of the valve member, a length of the pump stroke, and a length of the fill stroke.

27. The pump of claim 24, wherein the plurality of struts have a radially expanded configuration and a radially collapsed configuration.

28. The pump of claim 24, wherein the membrane comprises an elastomeric polymer.

29. The pump of claim 24, wherein one or more of the housing and the valve member comprises a polymer coating.

30. A pump for assisting blood circulation comprising:
a housing; and

a valve member disposed within the housing, the valve member having an umbrella structure, wherein the umbrella structure comprises a membrane coupled to a plurality of struts, and wherein the membrane comprises a body and a rim, and a thickness of the rim is greater than a thickness of the body.

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